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Thermo-mechanical effects in drilling using metal working fluids and cryogenic cooling and their impact in tool performance

J. C. Outeiro¹ · P. Lenoir¹ · A. Bosselut²

Abstract Cryogenic machining opens up new industrial perspectives in difficult-to-cut materials like nickel-based alloys. In particular, drilling is an operation that generates high thermal and mechanical loading to the drill. Therefore, tool performance, hole geometry and surface integrity can be highly affected. The objective of this study is to analyse tool performance during drilling of IN718 using conventional metal working fluids (MWF) and cryogenic cooling conditions, and correlate it with the thermo-mechanical phenomena. This study is conducted with standard coated cemented carbide twist drills, designed to work with MWF. The results show that drill performance under cryogenic cooling is strongly affected by its geometry. The axial force, drilling torque and tool wear/failure are higher under cryogenic cooling when compared to conventional MWF. Therefore, in order to take advantage of the cryogenic machining, new drill design is required, which currently is not available on the market.

Keywords Drilling · Metal working fluid · Cryogenic · Thermo-mechanical phenomena · Tool wear · Drilling simulation · Flow simulation

1 Introduction

Current research in metal cutting are carried out to increase the efficiency of machining operations and the quality of machined parts while reducing the environmental impact of such operations. Cryogenic machining is a way to address that issue. This technology has shown for turning operation the possibility to decrease tool wear [1, 2] and increase compressive residual stresses in the machined part [3–5]. Moreover, it has the advantage to offer a clean and non-toxic process, because of the properties of liquid nitrogen (LN₂), mainly used in this kind of assistance. The LN₂ evaporates in the atmosphere after contacting the cutting zone (it doesn't need reprocessing) and is safe for the operator (no skin or lung injuries).

Cryogenic machining opens up new industrial perspectives in machining difficult-to-cut materials such as nickel and titanium based alloys. These materials offer interesting properties such as high temperatures strength and good corrosion resistance, but those same characteristics become a barrier when these materials have to be machined. There are no studies available on the influence of cryogenic cooling in drilling difficult-to-cut alloys such as IN718 nickel-based alloy. This study is of great industrial importance, because the drilling operation generates greater thermo-mechanical loadings on the tool and on the workpiece when compared to external machining (turning, milling). Therefore, tool life, hole geometry and surface integrity are greatly affected.

All studies on cryogenic machining performed up to now have used existing (standard) commercial cutting tools, developed to work with common metal working fluids (MWF) or near dry conditions. These studies have shown a large scatter in tool wear (thus tool life), which can be partially attributed to the subpar performance of the existing cutting tools under cryogenic temperatures.

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Moreover, most of these studies compare the performance of cryogenic machining with dry or near dry conditions [3], which is not the case in most industrial applications.

The objective of the present study is to analyse tool wear (thus tool life) generated by drilling of IN718 under cryogenic cooling conditions, using standard coated cemented carbide twist drills (designed to work with high pressure MWF), and compare it to tool wear generated by drilling under MWF (present industrial reference). Thermo-mechanical phenomena generated during drilling will be analysed and used to explain the differences in tool performance observed between cryogenic cooling (hereinafter referred to as LN₂ cooling) and MWF conditions.

2 Experimental and numerical procedures

2.1 Experimental set-up and parameters

Drilling tests were performed in two three-axes CNC milling machines: one MAZAC FH-580-40 (dedicated to the cryogenic machining) and one DMG model DMU 65V (used for both cryogenic machining and MWF), both equipped with a designed experimental set-up for forces/torque and temperature measurements. These tests were performed on nickel-based alloy work material, Inconel 718 (hereinafter referred to as IN718, solution-treated and age-hardened, having a hardness equal to 44 HRC), using standard coated cemented carbide (TiAlN coating) twist drills. It is worth pointing out that these drills are designed to work with high pressure MWF, delivered to the cutting zone using the cooling channels in the drill (see Fig. 1).

Drill geometry was inspected according to the ISO 3002-1/2 and DIN 1414-1/2 standards, as described by

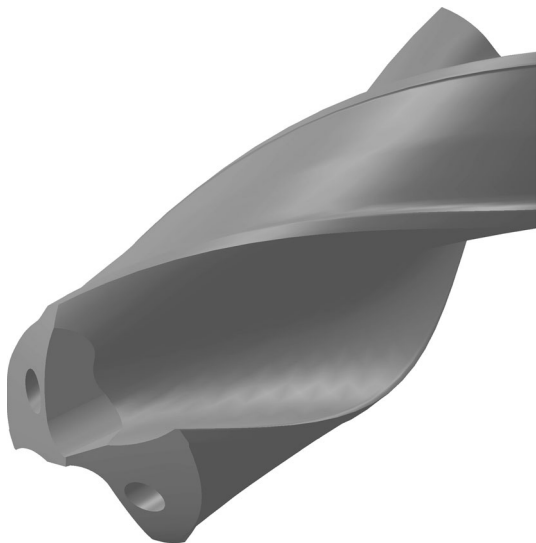


Fig. 1 Twist drill

Astakhov [6], using both ZOLLER (models Genius3 and 3DCheck) and ALICONA (model InfiniteFocus) equipments. These equipments permitted to scan the tool geometry, which was used for tool inspection and to generate the drill CAD model for the numerical simulations (see Fig. 1). The tool inspection permitted to measure the following drill geometric parameters: drill diameter of 12.015 mm, back taper of 0.09°, helix angle of 30°, (four) margins width of 0.837 mm, point angle of 143.4°, drill runout of 0.007 mm, chisel edge angle of 56.7°, chisel edge length of 0.397 mm, chisel edge centrality of 0.013 mm, web thickness of 0.173 mm, gash face angle of 64°, gash radius of 1.420 mm, normal rake angle varying from -10° to 32°, clearance angle varying from 10° to 18° and an average edge radius of 55 μm. Figure 2 shows the variation of the rake/clearance angles and cutting edge radius in the function of the distance from the drill center.

The drilling tests were performed varying the cutting speed (v_c), feed (f) and type of coolant (MWF and LN₂). The values of these parameters were identified based on the toolmaker recommendation and after performing preliminary drilling tests under wide range of drilling conditions. Table 1 shows the cutting and cooling conditions used in the experimental drilling tests.

The MWF was composed by 95 % of water and 5 % of a synthetic cutting fluid (supplied by TOTAL, commercial designation VULSOL 5000 S) at 20 bar pressure. As far as cryogenic cooling is concerned, LN₂ at 10 bar pressure was delivered to the cutting zone. Special designed cryogenic equipment developed by MECACHROME company was used to deliver the LN₂ to the drill bit. This equipment was composed by a LN₂ reservoir, 20 bar pump, rotary union, phase separator and insulated pipe.

During the drill tests axial force and drilling torque were measured using two piezoelectric dynamometers from KISTLER, models 9123C and 9273. Several drills were instrumented with thermocouples type K of 0.25 mm diameter. In order to measure the temperatures as closest as possible of the cutting edge but at different locations, the thermocouples were placed at 1 mm from this edge and at two locations: 0.74 mm (temperature T_1) and 3.54 mm (temperature T_2) from the drill margins (Fig. 3). During the temperature measurement tests the drill was kept static and fixed to the CNC milling machine table, while the work-piece was rotating and attached to the spindle using a designed fixation system, as shown in Fig. 4. Special attention was paid in centering the tool in relation to spindle axis in order to minimize runout errors.

2.2 Numerical models and parameters

In order to understand the thermal phenomena occurring during drilling under MWF and LN₂ cooling conditions,

Fig. 2 Variation of the rake/clearance angles and cutting edge radius of the drill in function of the distance from the drill center

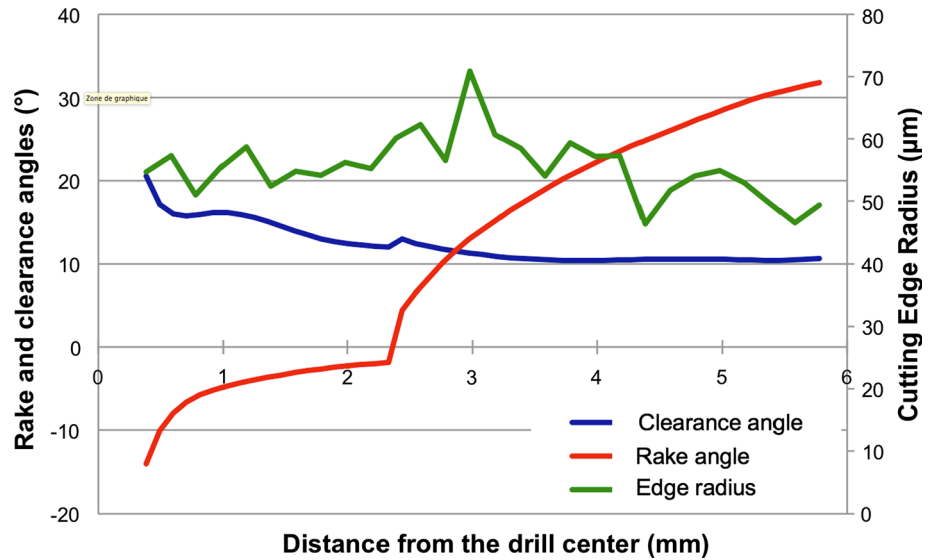


Fig. 3 Drill instrumentation with thermocouples type K for temperature measurements. T_1 and T_2 show the location of the thermocouples

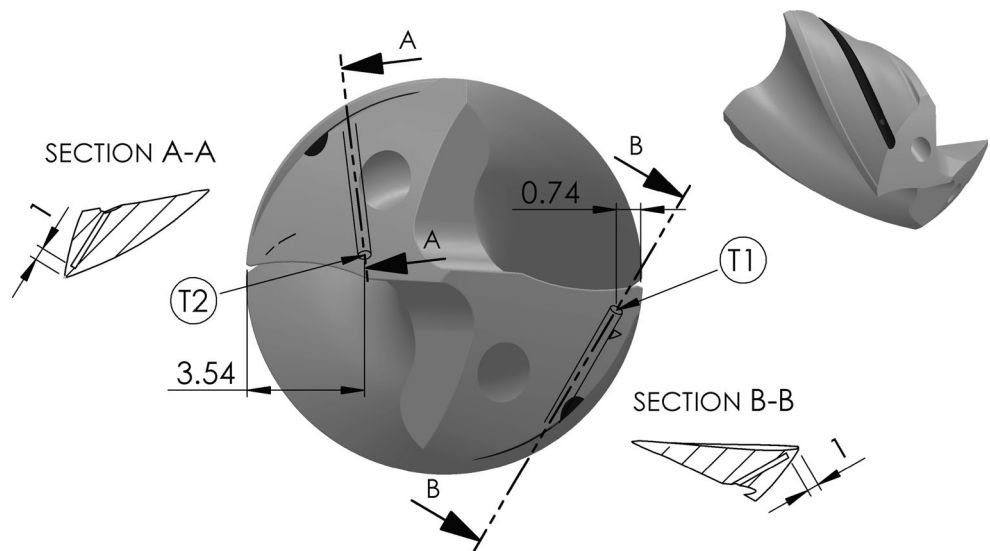


Table 1 Cutting parameters and coolant conditions

Coolant conditions		Cutting parameters		
Fluid	Pressure (bar)	v_c (m/min)	f (mm/rev)	Drilled hole depth (mm)
MWF	20	10–30	0.08–0.11	10
LN ₂	10	5–24	0.08–0.11	10

the commercial FEA software DEFORM-3D version 11, a Lagrangian implicit code, was used to simulate the three-dimensional cutting process of IN718 alloy. A finite element model was developed for the drilling operation, and this was consisted of the workpiece and tool, as shown in Fig. 5. The simulation was started with the tool cutting edges fully engaged in the workpiece to decrease the simulation time. A coupled transient thermo-mechanical analysis (corresponding to the chip formation and with a

duration of 0.15 s) was performed, followed by a steady-state thermal analysis to predict the tool temperature for longer drilling time.

The workpiece was modeled as thermo-viscoplastic and the tool as elastic. They were meshed using 60,000 and 200,000 tetrahedral elements, respectively. To model the thermo-viscoplastic behaviour of IN718 alloy, the Johnson–Cook constitutive model was employed [7], which is represented by the following equation:



Fig. 4 Experimental set-up for temperature measurement

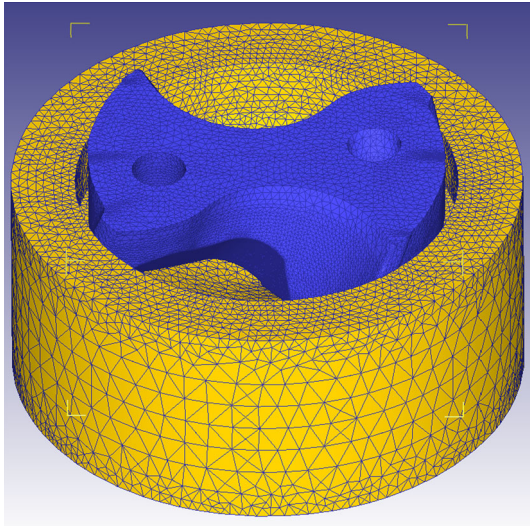


Fig. 5 Drilling operation model, meshed with 60,000 (workpiece) and 200,000 (tool) tetrahedral elements

$$\bar{\sigma} = \underbrace{(A + B\bar{\epsilon}^n)}_{\text{Strain hardening effect}} \underbrace{\left[1 + C \ln\left(\frac{\dot{\bar{\epsilon}}}{\dot{\bar{\epsilon}}_0}\right)\right]}_{\text{Strain-rate (viscosity) effect}} \underbrace{\left[1 - \left(\frac{T - T_{room}}{T_m - T_{room}}\right)^m\right]}_{\text{Thermal softening effect}} \quad (1)$$

where $\bar{\sigma}$ is the equivalent stress (MPa), $\bar{\epsilon}$ is the equivalent plastic strain, $\dot{\bar{\epsilon}}$ is the equivalent plastic strain rate (s^{-1}), $\dot{\bar{\epsilon}}_0$ is the reference equivalent plastic strain rate ($0.001 s^{-1}$), T is the temperature ($^{\circ}C$), T_m is the melting temperature of the work material ($1500^{\circ}C$) and T_{room} is the room

temperature ($-200^{\circ}C$). A , B , C , n and m are material coefficients, which were obtained from experimental quasi-static and dynamic compression tests using a Gleeble machine at different strain-rates and temperatures, including negative temperatures. A detailed description of the experimental set-up and procedure is provided in [8]. They are equal to 605 MPa, 1280 MPa, 0.0117, 0.139 and 3.98, respectively. The elastic and thermal properties of the IN718 and of the drill are given in Deform software database.

Concerning the tribological characteristics of the tool-chip and tool-workpiece interfaces, the Zorev's model was employed [9]. The value of the friction coefficient was determined from tribological tests described in [10, 11]. These tests permitted to determine the apparent friction coefficient (μ_{app}), which includes both contributions of interfacial (local) adhesive phenomena (μ_{adh}) and macroscopic plastic deformation (μ_{plast}). For the numerical simulation, μ_{adh} should be used, which for the range of sliding velocities and contact pressures applied in the machining tests, this coefficient can be represented as a function of the sliding velocity (v_s), represented by the following equation:

$$\mu_{adh} = c_1 \times v_s + c_2 \quad (2)$$

where the coefficients c_i ($i = 1, 2$) are equal to -0.004 and 0.406 , for LN_2 cooling, and equal to -0.004 , 0.340 for MWF. Concerning the limit shear stress (τ_{limit}), this is equal to the yield shear stress (τ_y) and was calculated based on the yield stress (σ_y) and the von Mises criterion.

The determination of the heat exchange with coolant is very critical for an accurate prediction of the temperature distributions in the tool and workpiece. This heat exchange was modeled by defining a convection heat transfer coefficient (h_f) and temperature (T_f) of the coolant. The determination of $h_{cryogenic}$ is particularly difficult, because this coefficient depends on several factors [12]. For such reason, several values of $h_{cryogenic}$ can be found in the literature, varying from 2 to 50 $kW/(m^2 K)$ [13, 14]. These values were estimated based on experimental tests or heat transfer calculations. Astakhov [15] proposed the following equation to estimate h_f in metal cutting:

$$h_f = \frac{0.20}{b^{0.35} \times g^{0.33}} \cdot \frac{v_f^{0.65} \times k_f^{0.67} \times c_{p-f}^{0.33} \times \gamma_f^{0.33}}{v_f^{0.32}} \quad (3)$$

where b is the equivalent length (m), g is the acceleration due to gravity (m^2/s), and the remaining parameters are properties of the fluid, namely: v_f is the velocity (m/s), k_f is the thermal conductivity ($W/m K$), γ_f is the specific weight (kg/m^3), v_f is the dynamic viscosity ($Pa s$) and c_p is the specific heat capacity ($J/kg K$). Based on Eq. (3), an $h_{cryogenic}$ of 6270 $W/(m^2 K)$ was obtained for LN_2 and

h_{MWF} of $930 \text{ W}/(\text{m}^2 \text{ K})$ was obtained for MWF. Based on the experimental measurements, an initial temperature was applied to the drill, being this temperature equal to $20 \text{ }^\circ\text{C}$ for MWF and $-170 \text{ }^\circ\text{C}$ for LN_2 cooling.

In order to understand how tool geometry (including the diameter and location of the coolant channels on the flank face) influences the efficiency of the cooling process, fluid mechanics simulations were performed. The Reynolds average Navier–Stokes (RANS) and Lagrangian equations were used to simulate LN_2 flows in drilling operation by integrating the standard SST k - ω turbulence model [16]. Three-dimensional steady flow model of the incompressible fluids (LN_2) was developed using STAR CCM+ commercial software. Figure 6 shows the model of the drilling operation, composed by three parts: drill, workpiece and fluid. This model was meshed with about 400,000 polyhedron cells for the drill, 450,000 cells for the fluid and 240,000 cells for the workpiece. Small mesh size was applied in the critical regions where strong gradients can occur, as well as at parts surface. In the last case, prism layer mesh is used to increase the accuracy of the fluid—solid (wall) interaction. In this model, the workpiece was considered static while the tool was rotating at a given rotation speed, calculated from the selected cutting speed

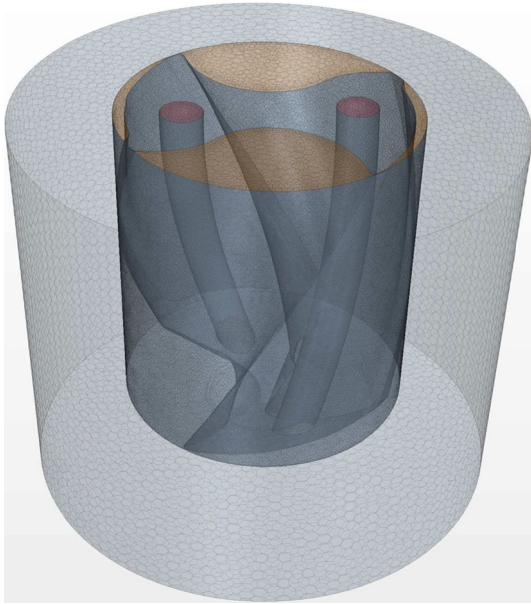


Fig. 6 Fluid mechanics model of the drilling operation, meshed with about 400,000 polyhedron cells for the drill, 450,000 cells for the fluid and 240,000 cells for the workpiece

Table 2 Physical and thermal properties of the fluids [12]

Fluid	Boiling point (K)	Density (kg/m^3)	Specific heat ($\text{J}/\text{kg K}$)	Dynamic viscosity (mPa s)	Thermal conductivity ($\text{W}/\text{m K}$)	Convection coefficient ($\text{W}/(\text{m}^2 \text{ K})$)
LN_2	77.36	807.3	2050	0.158	0.1396	6270

presented in Table 1. Since STAR CCM+ software cannot simulate rotation with deforming mesh, the solution was to consider the rotation with a moving reference frame (MRF) model. Table 2 shows the physical and thermal properties of the LN_2 , while Table 3 shows the coefficients of the SST k - ω turbulence model, all data obtained from the literature [12, 17].

Concerning to the boundary conditions, an inlet pressure of 8 bar and an inlet fluid temperature of $-196 \text{ }^\circ\text{C}$ (LN_2 boiling temperature) were applied. The inlet pressure was calculated based on the pressure loss in the piping. Outlet conditions were taken as ambient pressure of 1 bar (absolute pressure) and temperature of $20 \text{ }^\circ\text{C}$.

3 Results

3.1 Tool performance

Tool performance was evaluated by performing tool wear tests under MWF and LN_2 cooling conditions. Two tool wear curves of VB in function of the drilling depth were obtained at the optimal cutting conditions for each cooling strategy. These optimal cutting conditions were determined applying the concept of minimal specific cutting energy, according to the NF E66-520 standard. The corresponding optimal cutting speed and feed are the following: (1) $v_c = 10 \text{ m}/\text{min}$ and $f = 0.11 \text{ mm}$, for LN_2 ($p = 10 \text{ bar}$); (2), $v_c = 24 \text{ m}/\text{min}$ and $f = 0.11 \text{ mm}$, for MWF ($p = 20 \text{ bar}$). Figure 7 shows these two tool wear curves and some images of the tool at the end of the tests. This figure clearly shows, for this particular drill geometry/material, that lower tool life is obtained when drilling under LN_2 cooling (9 min, 240 mm drilling depth), when compared to the tool life obtained under MWF conditions (21 min, 1450 mm drilling depth). However, as shown in Fig. 7, cutting edge (for LN_2) and periphery corner (for MWF) chipping occurred before VB reached the limit of 0.3 mm. Tool images of the flank face and margins show strong tool wear and fracture under LN_2 cooling. In particular, multiple fractures are visible at the

Table 3 Coefficients of the SST k - ω turbulence model [17]

Fluid	σ_{k1}	$\sigma_{\omega1}$	β_1	σ_{k2}	$\sigma_{\omega2}$	β_2	α	β
LN_2	0.85	0.5	0.075	1.0	0.856	0.0828	1	0.09

Fig. 7 Tool wear (VB) in function of the drilling depth, using LN₂ ($v_c = 10$ m/min, $f = 0.11$ mm, $p = 10$ bar) and MWF ($v_c = 24$ m/min, $f = 0.11$ mm, $p = 20$ bar)

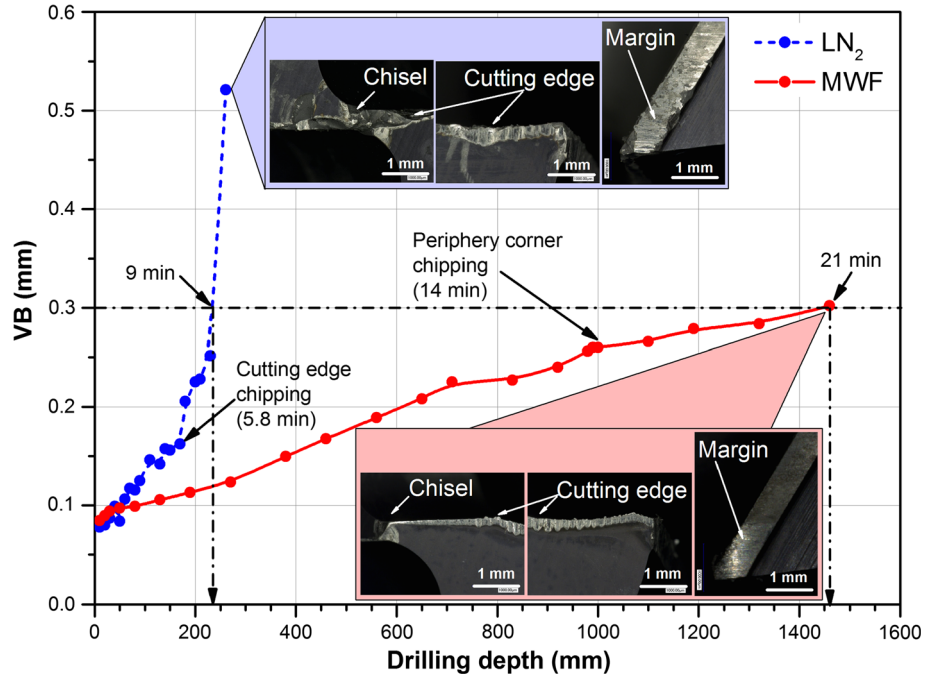
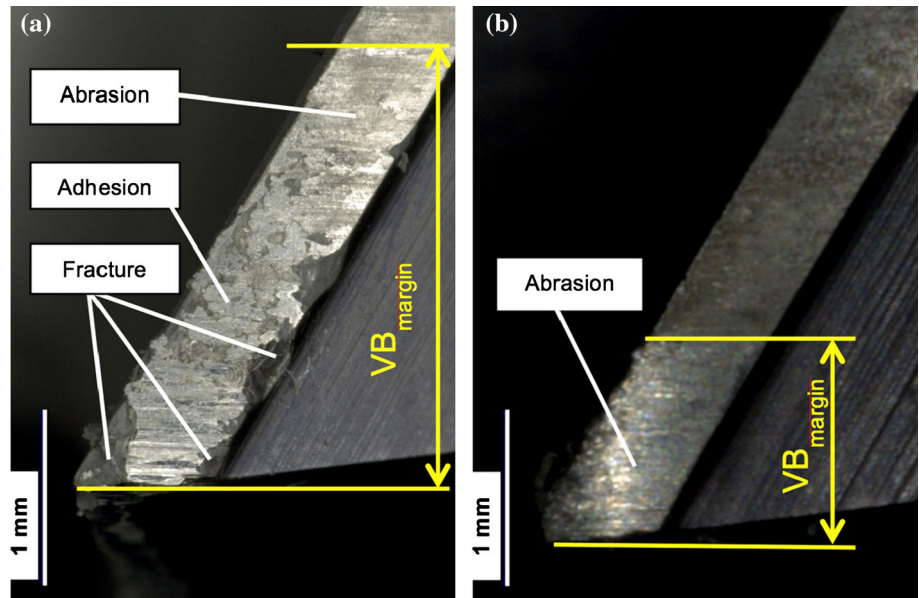


Fig. 8 Tool margins wear at the end of the tool wear tests, using LN₂ ($v_c = 10$ m/min, $f = 0.11$ mm, $p = 10$ bar) and MWF ($v_c = 24$ m/min, $f = 0.11$ mm, $p = 20$ bar)



tool margins, as well as at the cutting and chisel edges. These multiple fractures may be a consequence of the embrittlement of the carbide substrate under very negative temperatures.

Figure 8 shows in detail the principal wear modes at the tool margins, which include both abrasive and adhesive modes, combined with multiple fractures. Moreover, VB at the tool margins under LN₂ cooling is more than twice than the corresponding VB under MWF. In order to understand the causes of this reduction of tool life under LN₂ cooling, mechanical (axial force and drilling torque) and thermal

phenomena (tool temperatures) were investigated, described as follows.

3.2 Axial force and drilling torque

Both axial force (F_a) and drilling torque (M_d) were measured during the drilling operation. Figures 9 and 10 show for both MWF and LN₂, the axial force and the torque generated in drilling IN718, applying the cutting speed and feed presented in these figures. For these conditions, the axial force is almost constant during the drilling process,

Fig. 9 Axial force generated using MWF ($v_c = 24$ m/min, $f = 0.11$ mm/rev, $p = 20$ bar) and LN₂ ($v_c = 24$ m/min, $f = 0.11$ mm/rev, $p = 10$ bar)

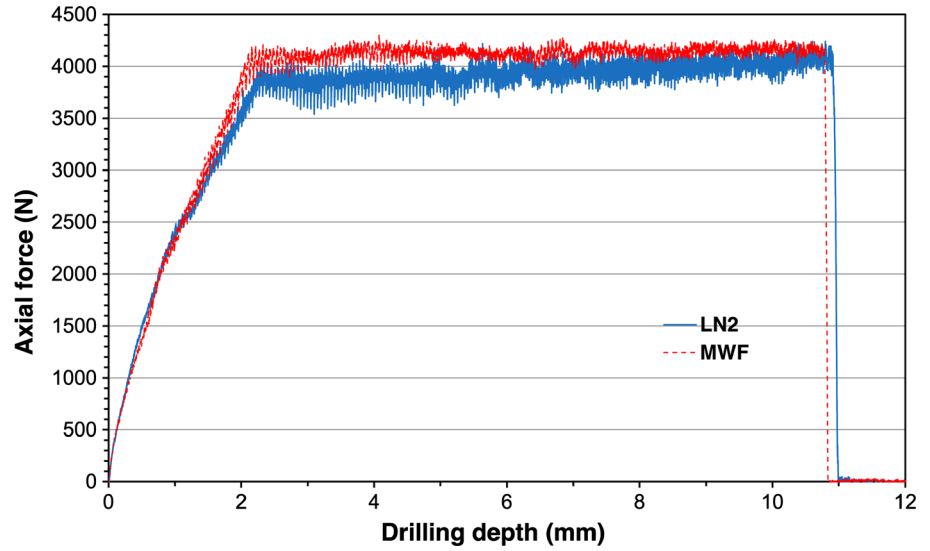
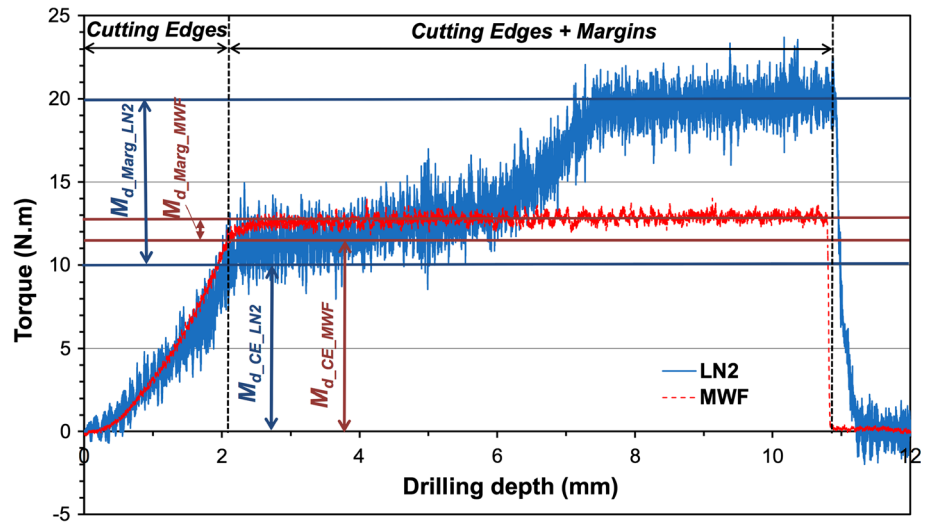


Fig. 10 Drilling torque generated using MWF ($v_c = 24$ m/min, $f = 0.11$ mm/rev, $p = 20$ bar) and LN₂ ($v_c = 24$ m/min, $f = 0.11$ mm/rev, $p = 10$ bar)



being slightly inferior when LN₂ is applied (average values around 4000 N for the LN₂ and 4150 N for the MWF). However, for this very short drilling time (between 10 and 23 s depending on the cutting conditions), the opposite was also observed (see Table 4).

As far as the torque is concerned, the results are different. Applying MWF, the torque is almost constant (average value around 13 N m) during the drilling operation. However, applying LN₂, the torque is initially slightly inferior to the MWF case, but it increases considerably (almost 45 %, from 11 to 20 N m) for a drilling depth greater than 40 % of the drilling diameter. Since the drilling torque results from the contribution of the cutting edges ($M_{d_CE_MWF}$ and $M_{d_CE_LN2}$) and the drill margins ($M_{d_Marg_MWF}$ and $M_{d_Marg_LN2}$), Fig. 10 shows that about 50 % of the total drilling torque is generated at the drill margins for the LN₂ case, when compared to only about

11 % for the MWF case. This increase in drilling torque at drill margins means that friction forces also increase and consequently drill margins wear. As it will be discussed later, these strong friction conditions at the tool margins are mainly caused by the insufficient back taper of the drill for cryogenic cooling conditions. The increase of the torque during drilling using LN₂ reduces with the decrease of the cutting speed and feed.

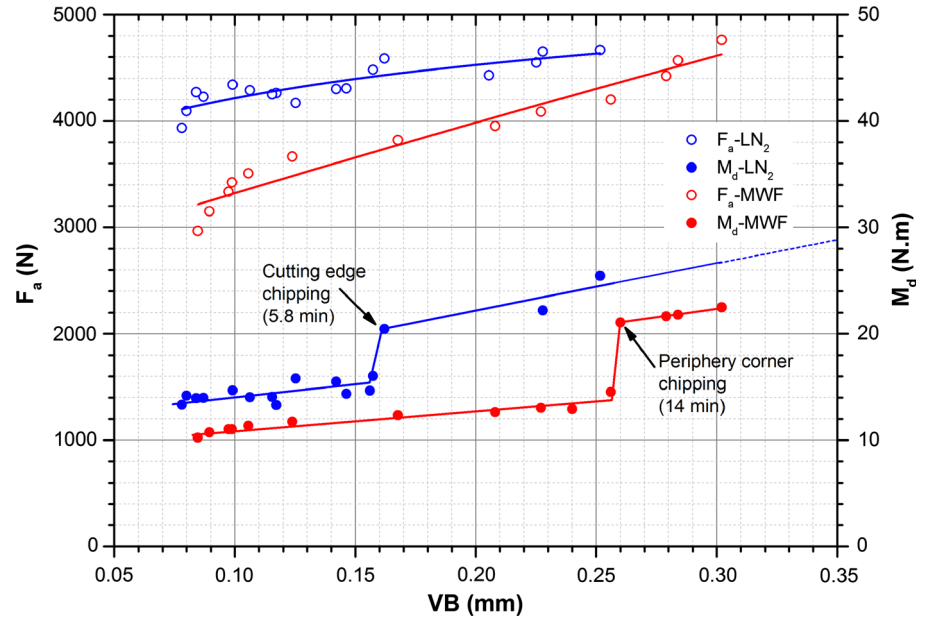
Figure 11 shows the evolution of both axial force (F_a) and drilling torque (M_d) in function of drill wear VB. As shown in this figure, both axial force and torque increase with VB, being higher when LN₂ is used, when compared to MWF. Under LN₂ cooling, the axial force is about 1000 N (25 %) higher than the corresponding axial force under MWF conditions, and decreases as VB increases.

As far as the torque is concerned, it is about 3–4 N m (23 %) higher than the corresponding torque under MWF

Table 4 Predicted and measured results ($v_c = 10$ m/min, $f = 0.11$ mm)

Fluid	F_a (N)	M_d (Nm)	T_{max} (°C)	T_1 (°C)	T_2 (°C)
LN ₂ -SIM	3280	17	410	-5	-48
LN ₂ -EXP	4110 ± 83	16 ± 1	-	-6 ± 5	-48 ± 2
MWF-SIM	3362	16	445	68	61
MWF-EXP	4050 ± 110	15 ± 1	-	32 ± 6	60 ± 1

Fig. 11 Axial (F_a) and drilling torque (M_d) generated using MWF ($v_c = 24$ m/min, $f = 0.11$ mm/rev, $p = 20$ bar) and LN₂ ($v_c = 10$ m/min, $f = 0.11$ mm/rev, $p = 10$ bar), in function of tool wear V_B



conditions. However, before tool wear V_B reaches the limiting value (0.3 mm), drilling torque increases abruptly for both LN₂ and MWF conditions. This increase occurs at V_B of 0.16 mm for LN₂ cooling and at V_B of 0.26 mm for MWF. The reason for the torque jump was the cutting edge (for LN₂) and periphery corner (for MWF) chipping. Apparently, the chipping did not produce also a jump in axial force, which can be justified by the fact that only approximately 30 % of the axial force is generated by the cutting edges, when compared to 60 % of the axial force generated by the chisel edge [6].

3.3 Temperatures

Figure 12 shows the temperatures at the two locations in the cutting tool (temperatures T_1 and T_2 in Fig. 3) in function of the cutting speed and feed, for both MWF and LN₂ cooling conditions. These temperatures were obtained for a drilling depth of 10 mm. Each cutting condition was repeated at least three times and the average values were calculated. The initial drill temperature was equal to 20 °C for MWF and -170 °C for LN₂ cooling.

Except for a cutting speed of 24 m/min, the temperatures at the two locations on the tool are lower when LN₂ is applied, when compared to those obtained using

MWF. Using LN₂, T_2 is negative, because the thermocouple is located closer to the cooling holes when compared to the other thermocouple (T_1) (see Fig. 3). Using a cutting speed of 24 m/min results in an increase of the temperatures at these two locations, especially when LN₂ is applied. Taking into account that for the same conditions higher drilling torque was measured for LN₂ cooling, it seems to be obvious that higher temperatures will be also generated for those conditions. Temperature T_1 is higher when compared to temperature T_2 , because: (1) the cutting speed depends on the considered point position at the cutting edge, being higher at the drill margins; (2) if 50 % of the drilling torque is generated at the drill margins, high friction forces will be also generated at this zone. Therefore, high cutting speeds (thus high sliding velocity between the drill and the wall of the hole being drilled) combined with high friction forces, result in high thermal (friction) energy generated by unit of time. Moreover, taking into account that location 2 (T_2) is closer to the cooling hole, higher temperatures will be obtained at the drill margins region (in this case temperature T_1). This region of high temperatures is visible on the tool flank face (Fig. 13), represented by a dark zone, which means that the reached temperatures were very high.

Fig. 12 Temperature T_1 and T_2 in function of the cutting speed and feed, for both MWF (red bar/dark gray) and LN₂ (blue bar/light gray) cooling conditions. Drilling depth equal to 10 mm (color figure online)

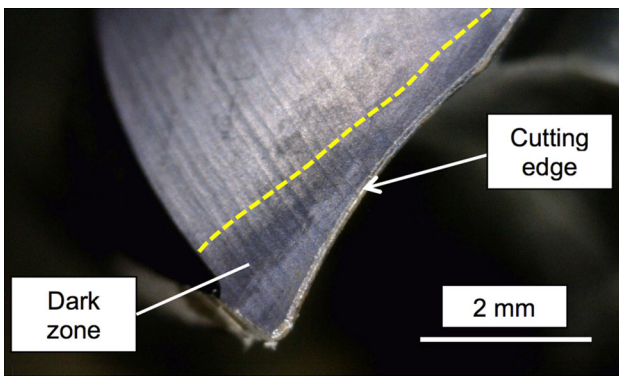
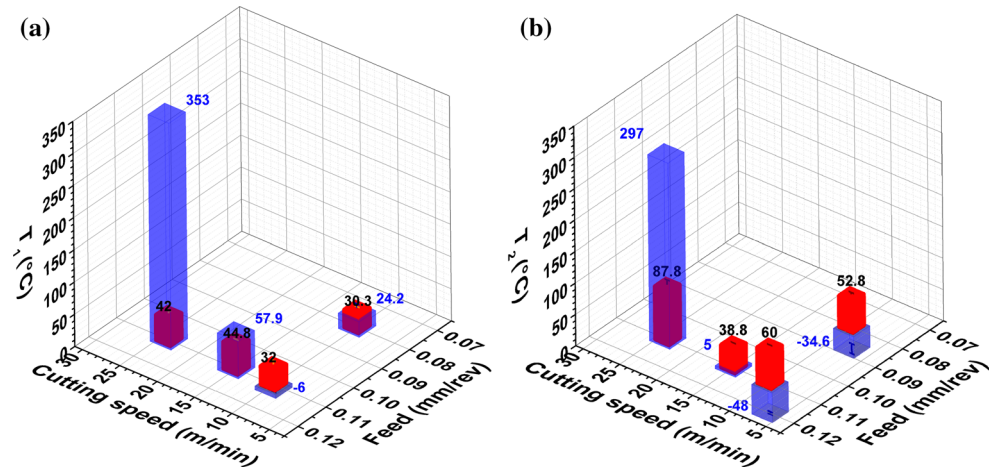


Fig. 13 Flank face of a drill used under LN₂ cooling conditions ($v_c = 10$ m/min, $f = 0.11$ mm/rev, $p = 10$ bar, drilling depth = 10 mm)

Table 5 Influence of thermal and springback effects on final hole diameter

Fluid	Δ_{sb} (mm)	Δ_T (mm)	Δ_c (mm)	D_f (mm)
MWF	-0.079	-0.015	-0.094	11.905
LN ₂	-0.089	-0.028	-0.117	11.883

In order to determine the full drill temperature distribution, two numerical simulations were performed under the same cutting conditions ($v_c = 10$ m/min, $f = 0.11$ mm), one for LN₂ cooling and another for MWF. The predicted and measured results are presented in Table 5 concerning to the axial force (F_a), drilling torque (M_d), maximum tool temperature (T_{max}), and temperatures T_1 and T_2 . In general, the predicted axial force is lower than that measured, while the drilling torque is almost identical. The higher measured axial force can be due to small changes of the chisel edge geometry of the real tool when compared to the CAD model that didn't changed.

As far as tool temperature is concerned, Figs. 14 and 15 show the predicted temperature distribution at the flank and

rake faces, respectively. Figure 14b shows that in a qualitative way, the shape of the predicted temperature distribution in the flank face is similar to the experimental shape shown in Fig. 13, which is a good indicator of the quality of the prediction. This is confirmed by the temperature measurements T_1 and T_2 , where both predicted and measured temperatures in both locations 1 and 2 are identical (except for the MWF case at location 1). It is worth pointing out that the predicted temperatures T_1 and T_2 were extracted from the model at the thermocouple locations, by averaging the nodal temperatures within a volume two times bigger than the bottom part of the thermocouple hole (about 0.2 mm³).

Comparing the predicted temperature distribution between LN₂ cooling and MWF, Figs. 14 and 15 show also that the maximum tool temperature (T_{max}) is not significantly reduced when MWF is replaced by LN₂. This temperature is 445 °C for the MWF and 410 °C for the LN₂ (see Table 5), representing a reduction of only about 8 %. The most important change when MWF is replaced by LN₂ is the reduction of the tool region affected by high temperatures.

4 Discussion

Previous results have shown that tool performance under cryogenic cooling conditions was seriously compromised when compared to MWF coolant conditions. In order to understand the reasons for such weak performance under cryogenic cooling, the thermal and mechanical phenomena generated during drilling operations should be considered. Except for very short drilling time (as shown in Fig. 9), the results have shown that higher axial force and torque are generated when drilling under LN₂ cooling (see Fig. 11). This is probably due to the increase of the work material resistance under very low (negative) temperatures.

Fig. 14 Temperature distribution at the drill flank face in drilling using **a** MWF ($T_{max} = 445\text{ }^{\circ}\text{C}$) and **b** LN_2 ($T_{max} = 410\text{ }^{\circ}\text{C}$). $v_c = 10\text{ m/min}$, $f = 0.11\text{ mm}$

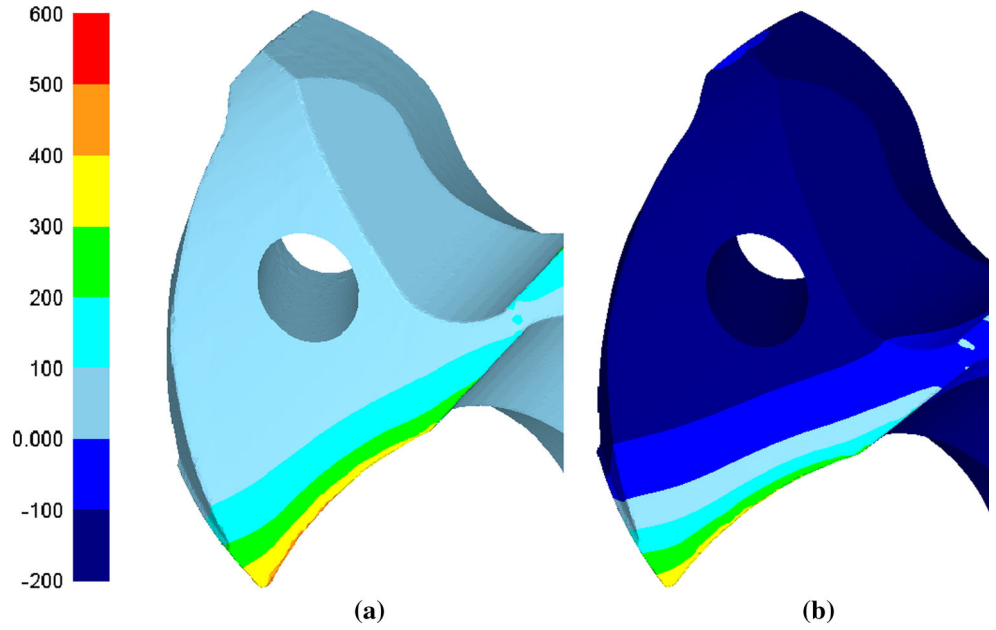
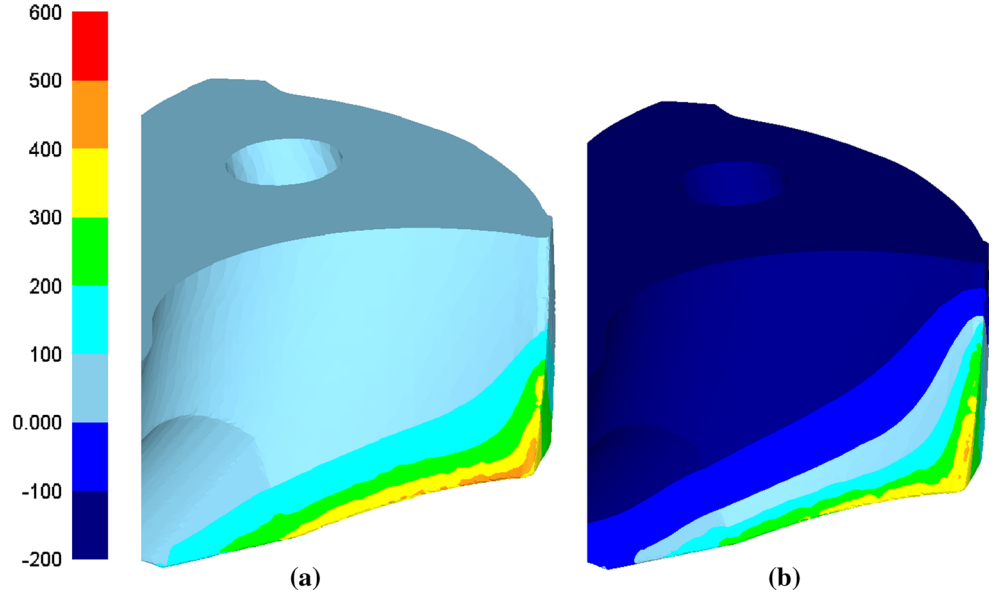


Fig. 15 Temperature distribution at the drill rake face in drilling using **a** MWF ($T_{max} = 445\text{ }^{\circ}\text{C}$) and **b** LN_2 ($T_{max} = 410\text{ }^{\circ}\text{C}$). $v_c = 10\text{ m/min}$, $f = 0.11\text{ mm}$



As far as the axial force is concerned, this force is the sum of the axial forces on the major cutting edges (lips), chisel edge and due to the friction on the margins [6], as follows:

$$F_a = F_{a-lips} + F_{a-chisel} + F_{a-margins} \quad (3)$$

The major cutting edges contribute approximately 30 %, minor cutting edges (margins) 10 %, and chisel edge 60 % of the total axial force [6]. So, the contribution of the margins is negligible when compared to tool major cutting edges and chisel edge. Observing Fig. 7, it is possible to verify that the major tool wear/failure difference between the drills used under LN_2 and MWF conditions is at chisel

edge zone. The chisel edge is completely destroyed under LN_2 cooling, while it is still visible under MWF coolant conditions. The highest axial force generated at the chisel edge under LN_2 cooling is mainly responsible for this excessive tool wear and failure. This high axial force in drilling restricts the penetration rate of the drill, thus productivity. As the chisel edge is the major contributor of the axial force, one should: (1) reduce the length of this edge; and (2) improve the geometry of this edge, in particular under LN_2 cooling conditions [6].

As far as the drilling torque is concerned, Fig. 10 shows that significant amount of the torque (up to 50 % of the total drilling torque for the severest cutting condition used

in the tests) can be generated at drill margins under LN₂ cooling, when compared to MWF coolant conditions. This high drilling torque generated by drill margins means that high friction forces between these margins and wall of the hole being drilled will be generated. As a consequence, higher drill margins wear will be produced under LN₂ cooling, when compared to MWF conditions (see Fig. 8). In order to understand the increase of the drilling torque at the drill margins when compared to MWF conditions, calculations of thermal (induced by the application of LN₂ cooling) and springback effects on hole diameter were performed. Figure 16 shows schematically the procedure to estimate the final hole diameter based on these two effects. It is worth pointing out that the initial residual stress present in the work material before drilling was not considered in these calculations.

Table 5 shows the results obtained from such calculations when drilling under LN₂ and MWF cooling conditions. The hole contraction (Δ_c) is higher under LN₂ when compared to MWF, and therefore, a smaller final hole diameter (D_f) is produced. This smaller hole diameter combined with lower lubrication capability of the LN₂ when compared to the MWF, more intense friction forces between the wall of the hole being drilled and the drill margins will be generated, thus higher drilling torque.

In order to minimize the friction forces between the drill margins and the wall of the hole being drilled, higher back taper and reduced margins width should be used, in particular under LN₂ cooling conditions.

The parameters associated to the LN₂ and MWF cooling conditions, such as the flow-rate, pressure, temperature, application direction of the fluid jet, have an important function in the thermo-mechanical phenomena, thus in the tool performance. The flow-rate depends on the pressure and also on the diameter of the internal channels for fluid

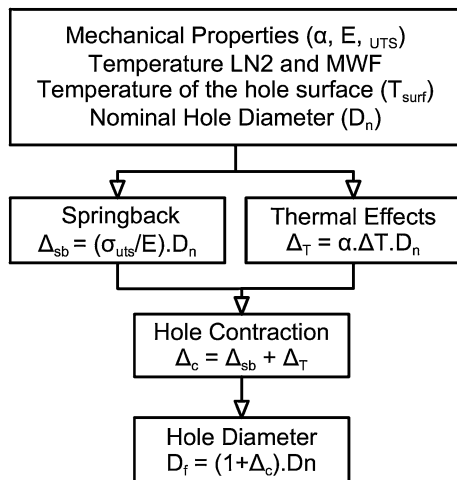


Fig. 16 Flow-chart of the thermal and springback effects on the hole diameter

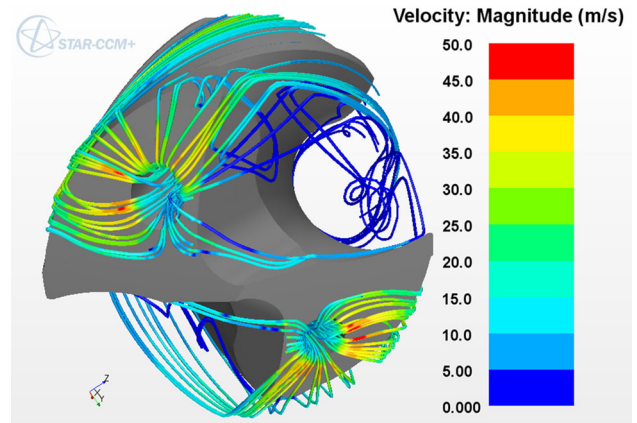


Fig. 17 Direction and magnitude of the LN₂ flow velocity around the drill

supply. The diameter and the location of the coolant channels on the drill flank face are two important parameters in drill design channels for fluid supply. In order to evaluate the adequacy of these two parameters for an efficient cooling process, fluid mechanics simulations were performed. Figure 17 shows the direction and velocity of LN₂ around the drill, through streamlines. As can be seen, the LN₂ flow in the bottom clearance space (space between the clearance or flank drill face and the bottom of the hole being drilled) separates into two principal flows. The first flow goes directly into the chip flute, while the second flow goes through the very narrow gap between the drill body and the wall of the hole being drilled. As a consequence, these flows do not participate in cooling the region adjacent to the major cutting edges, in particular the region adjacent to the drill periphery (zone of high temperatures in Fig. 15), where the fluid is mostly needed. Therefore, to increase the flow through the mentioned region: (1) the bottom clearance space should be increased by modifying the design of the flank face (probably increase the clearance angle); (2) the geometry of the internal channels for fluid supply and its location on the flank face should be modified (they should be placed closer to the major cutting edge and the region adjacent to the drill periphery). If none of these two solutions are sufficient, the flow-rate should also be increased.

5 Conclusions

The results show that tool wear generated during cryogenic drilling of IN718 using standard drill optimized for MWF is higher than tool wear generated during drilling using MWF. The two predominant tool wear modes observed in the drills are abrasion and adhesion, which are more intense and accomplished with multiple fractures when LN₂

is used. These tool fractures are evident in the chisel edge and drill margins, due to the intense thermo-mechanical phenomena observed in these two regions. In general, higher axial force and drilling torque are generated under LN₂ cooling when compared to MWF conditions. Since the chisel edge contributes about 60 % for the total axial force, inadequate chisel edge geometry for LN₂ cooling can originate an excessive axial force and consequently chisel edge wear and fracture. Moreover, the work material springback and the thermal effects induced by the cooling action will produce hole contraction, which are higher under LN₂ cooling when compared to MWF conditions. If the drill does not have sufficient back taper, intense friction forces between the wall of the hole being drilled and the drill margins will be generated, and consequently high drilling torque.

Although the tool temperatures at thermocouple locations 1 and 2 are lower for LN₂ when compared to MWF, the predicted maximum temperature is only 8 % lower for the LN₂. The most important change when MWF is replaced by LN₂ is the reduction of the tool region affected by higher temperatures. This may be the mainly advantage of the LN₂ cooling when compared to the MWF, which become crucial as the drilling time or the penetration ratio (thus productivity) increase. Therefore, to take advantage of drilling IN718 under cryogenic cooling conditions, a new drill design is required. The following recommendations should be taken into account for developing this new design:

- Increase the back taper and decrease the margins width to reduce the friction forces between the wall of the hole being drilled and the drill margins, thus reduce the drilling torque.
- Re-design the chisel edge geometry to reduce the axial force, thus increase the drill penetration rate and consequently productivity.
- Increase the bottom clearance space by modifying the flank face design (including increase the clearance angle).
- Modify the geometry of the internal channels for fluid supply and its location on the flank face.

In addition to the previous tool design recommendations, the selection or development of tool materials suitable to work under a wide temperature range from -196 °C to very high temperatures is necessary. In particular, a carbide substrate more resistance to the thermal shocks (higher toughness) will contribute to reduce tool fracture. Finally, the increase of LN₂ flow-rate may also be required.

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