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The macroscopic behavior of pantographic sheets depends mainly on their microstructure: experimental evidence and qualitative analysis of damage in metallic specimens

Abstract Recently the exotic properties of pantographic metamaterials have been investigated, and various mathematical models (both discrete and continuous) have been introduced. However, the experimental evidence available up to now concerns only polyamide specimens. In this paper, we use specimens printed using metallic powder. We prove experimentally that the main qualitative and quantitative features of pantographic sheets in planar deformation are independent of the constituting materials, at least when they can be regarded as homogeneous and isotropic at micro-level. Of course, the absolute value of Young's modulus of constituent

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material affects the overall reaction force needed to the hard device to impose a given displacement: A first investigation on this effect is also attempted.

Keywords Pantographic structures · Additive manufacturing · Tomography · Generalized continua

1 Introduction

In this work, we investigate the mechanical properties of metal-printed specimens of a promising microstructured material, referred to as pantographic *metamaterial*. It is remarkable that this substructure results in a material with an exotic macroscopic behavior which can be subjected to large deformation while remaining in an elastic regime [1–4]. Notably, the design of the microstructure has been conceived so that its deformation energy depends on the second gradient of the displacement [5–12]. Morphologically, the substructure can be described as a double array of mutually orthogonal beams, also called fibers, interconnected by elastic cylinders at intersection points, also called pivots [13, 14]. This survey, specifically, focuses upon reporting and analyzing the results gathered from extensional tests performed on two different samples of specimens with pantographic substructure which consist of (1) three aluminum-printed specimens and (2) four steel-printed specimens, respectively. The experiments establish the fulfillment of the so-called BIAS extension test for all the specimens. (This test is specifically called BIAS extension and not only extension, because it is performed along a biased direction respect to the fiber direction.) In addition, some of the tests include several load–unload cycles with increasing amplitude as well as compression loading. It is notable that the experimental evidence for pantographic sheets gathered up to now concerns only specimens printed in polyamide, and it was immediately evident that it is necessary to extend the available collection of data to specimens constituted of different materials.

Earlier investigations had given the motivation to a series of papers (see, e.g., [13, 15–17]) in which the problem of determining the main exotic properties of pantographic *metamaterials* has been carefully investigated. Various mathematical models have also been proposed, with the aim of finding a reasonable compromise between predictive capacity and computational feasibility. The models introduced up to now can be classified into two types (1) discrete, as in [13, 16, 18–21], wherein a finite set of rotational and extensional springs are introduced to describe the complex deformation phenomenon occurring in the microstructure, and (2) continuous, as in [13, 19, 22–24], which can be further distinguished into purely continuous ones, wherein generalized plate models are used (of the same kind of those proposed, e.g., in [25–29]) and into hybrid discrete/continuous ones, wherein beams (i.e., 1D continua) form lattices by means of interconnecting pivots placed at finite distances (see [30–35]).

The relationship between discrete and continuous models can be established via homogenization methods as mentioned in [5, 7, 13, 30, 36–41]. Also, interesting results have been found in statistical mechanics which prove how, using precise mathematical argument, fluid continua can be derived from discrete microscopic system via homogenization methods (see, e.g., the reviews [42, 43]). However, we remark that the standard procedures used in [44, 45] cannot be used when three point interactions at micro-level are not negligible or when relevant bending energy arises in beam lattices. In spite of the relevant and rigorous results obtained in homogenizing microscopically inhomogeneous systems (also when thermal phenomena are involved), for systems which are fluids macroscopically as shown, e.g., in [46–49], as well as for different classes of biological systems,

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see, e.g., [50,51]), the problem of homogenizing macroscopically *solid behavior* remains open if rigorous reasonings of statistical mechanics are to be employed. Therefore, heuristic methods, including mixed micro-macro- and *ad hoc* phenomenological approaches, are expected to play a relevant role in the modeling of the structured media which we consider here.

In the research which we describe in this paper, it was possible to use specimens printed using metallic powder. Some of the latest techniques collected under the name of additive manufacturing (AM) have been employed whose challenge was to fabricate the specimens with well-refined pantographic substructure. We are aware of the fact that the obtained micro-material cannot be regarded to have the same micro-mechanical properties as the material obtained by a melting process. The SEM views in Fig. 12 clearly show that at length scales much smaller than the beam cross-sectional size, the material appears to have a porous microstructure; hence, the classical continuum Cauchy model cannot describe its complex deformation phenomena. In view of the above, granular micro-mechanical models should be employed in order to consider the granular nature of the constitutive material [52–59]. Here, we show based upon experimental measurements that the main qualitative mechanical properties of pantographic sheets (considering planar deformation) appear to be independent of the particular constituting materials. Further these mechanical properties can be described mathematically if these materials, at micro-level, can be suitably modeled as being homogeneous and isotropic. In this paper, a first investigation is described to evaluate the elastic range in BIAS extension tests, the resilience to imperfection and micro-damage and nonlinearity, rupture mechanisms and ultimate failure of considered novel metallic specimens. Comparisons are made between specimens fabricated from aluminum and steel, respectively, remarking upon the similarities and differences in their exotic mechanical properties. These observations are further compared with the ones exhibited by polyamide specimens. A preliminary interpretation of the results, considering the existing theoretical model for pantographic structures, is also described.

2 Additive manufacturing of steel and aluminum specimens

Recent advancements in the technical capability of production and designing processes permit fabrication of materials having specific microstructures at small length scales, which have the ability to strongly condition the macroscopic mechanical behavior of the material. The fabrication of the pantographic structure considered herein, and other complex geometries, can be now realized using “3D printing,” also referred to as additive manufacturing (AM). For example, selective laser sintering (SLS) have been already employed for the production of the lattice structures in [60,61]. 3D printing is used to create objects with complex shapes in layer-by-layer manner utilizing some precursor constitutive material. Most 3D printing processes employ wires or powders made up of metallic or polymeric material which assume the designed shape by interacting with an energy source. For fabrication with 3D printing, the object must be designed and its three-dimensional geometry generated using a CAD software. The geometry is then discretized into a triangular/tetrahedral mesh and saved in the form of stl file. Such a file is then used as an input for an AM software where the 3D geometry is sliced into layers, whose thickness can be set according to the needed resolution and machine capabilities, and the object to be built is positioned on the building platform. Before the printing process can start, it is necessary to design the supports which connect the object to the building platform and take on the functions of (1) supporting the part during the printing process, (2) dissipating heat and (3) avoiding thermal distortion. The particular case of metal additive manufacturing requires a specific care to the minimization of overhanging areas where overheating zones usually are located and provoke a deterioration of surface roughness.

The so-called powder bed processes are certainly the most promising among the AM techniques. This category includes the selective laser melting (SLM), also called laser beam melting (LBM), and electron beam melting (EBM). The production process employs a laser (or electron) beam to melt a thin layer of powder. A resolution can be defined for such a process based on the size of the laser beam, being usually in the range between 50 and 100 μm , and the height of the powder layer, being in the range between 20 and 50 μm . Generally, the overlapping of hundreds of welding beds (200–300 μm in width) is needed to build a part (about 500 m of bead/ cm^3), and the melting process is performed under shielding inert gas in order to prevent the oxidation of the powder. The shapes which can be built are complex and the objects, typically, have a satisfactory mechanical behavior.

2.1 Manufacturing of steel pantographic structures

In this survey, the SLM125HL setup from SLM solutions has been used to create the pantographic structure. This machine is equipped with a 400 W YAG laser (YLR-400-WC) at a wavelength of 1070 nm. Scanning speed varies from 400 to 1500 mm/s, while the thickness of the powder layer is in the range between 30 and 100 μm . The minimum diameter of the laser at the focus point is about 70 μm . The powder employed is the 316L stainless steel having spherical particles whose least diameter size is 37 μm (CILAS 920). As mentioned above, the manufacturing of the part is preceded by the proper positioning of the 3D geometry in the printing volume using the MAGICS—Materialise software. As depicted in Fig. 1, the specimens were positioned orthogonally to the building platform even though a tilt angle of 45° would have been preferable for the realization of the pivots. Despite the significant technological achievements represented by such manufacturing technologies, one has to consider that the objects obtained are very sensitive to the location and the number of supports whose inadequate positioning could result in widespread microstructural flaws. Furthermore, the rough surfaces in Fig. 2a, b indicate the possibility of appreciable porosity which, however, potentially can be suppressed by heat treatments such as hot isostatic pressing (HIP), resulting in almost fully dense metallic alloys. (Such postprocessing was not performed on the samples presented in the next sections.)

2.2 Manufacturing of aluminum pantographic structures

The following investigations were conducted with a commercial LBM system (EOS M 400), equipped with a 1 kW laser unit (YLR series, CW laser, wavelength 1070 nm). All objects were manufactured of AlSi10Mg

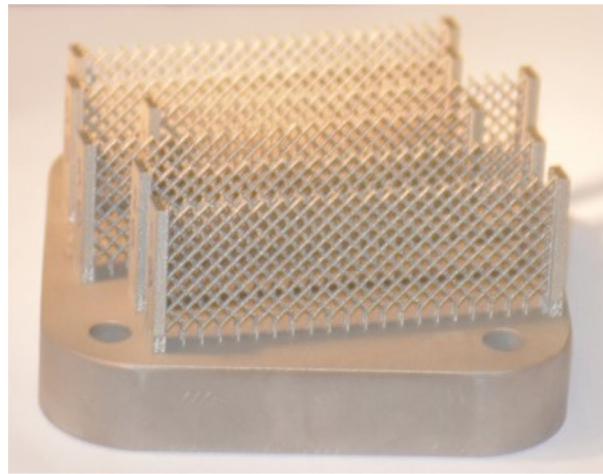
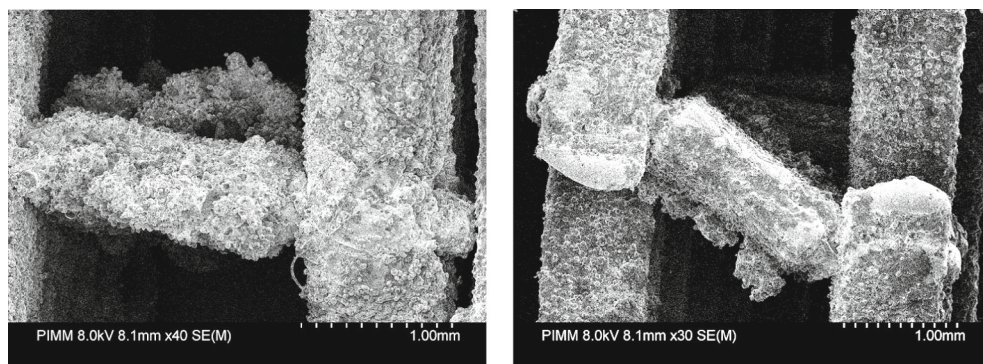


Fig. 1 Manufactured steel samples



(a) connection at the middle of the sample.

(b) connection at the external point of the sample.

Fig. 2 SEM view of the beam pivot connection after tensile testing

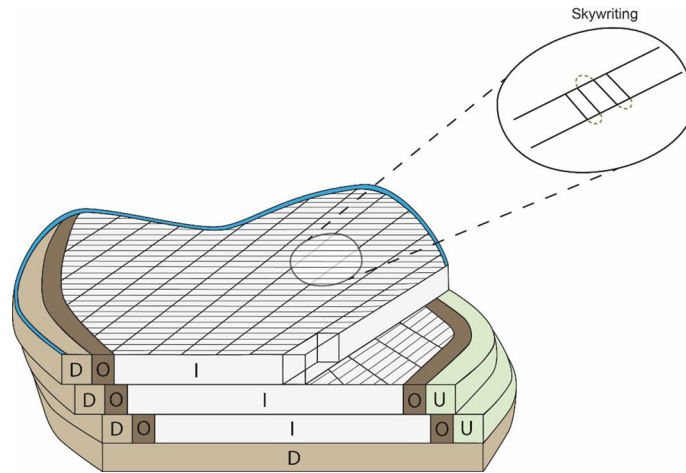


Fig. 3 Example of a basic exposure strategy (stripe strategy) and exposure areas. D: Downskin; U: Upskin; I: Inskin; O: Overlap; Blue: Contour exposure (color figure online)

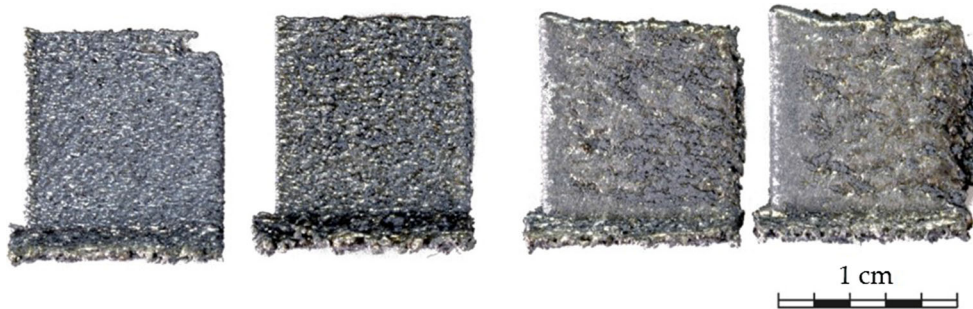


Fig. 4 Lamellas manufactured by a single laser track per layer, showing the impact of inertia (left sides) and interrupt delay (right side). Left to right: increasing energy density

(PSD: D10: 12.28 μm ; D90: 43.22 μm) processed in 90 μm layers under the influence of a heated building platform (165 $^{\circ}\text{C}$). A shield gas flow was applied parallel to the top layer of the powder bed to remove any side products arising from the welding process.

General exposure strategy The process control and resulting material characteristics are intricate due to the incremental creation of material. An exposure strategy (arrangement of laser tracks) is necessary to create a volume using a spot-like energy source like a laser beam. The exposure strategy in combination with exposure parameters like laser power and exposure speed defines the material microstructure and therefore its characteristics. Due to different thermal boundary conditions, a part is usually divided into areas of different parameter settings (see Fig. 3). Areas in a surrounding of low thermal conductivity (e.g., powder) require different parameter settings compared to areas with increased thermal conductivity (e.g., surrounding solid material) in order to create a material of high quality (regarding factors like porosity, homogeneity or microstructure).

Laser track characteristics Usual exposure speeds for the processing of AlSi10Mg can reach 2000 mm/s. The switch on/off time of the laser unit can take up to 50 μs . Therefore, the full laser power is reached after a distance of ~ 0.1 mm. This distance can also be impacted by delays in the electronics controls. This effect can cause different ending points for the laser track (see interrupt delays in Fig. 4). A second effect can be caused by the physical inertia of the projectors mirror, which is resulting in a lower exposure speed in the beginning of the track and therefore in a higher energy input.

Part orientation A proper orientation of a part within the building volume is essential to its quality and error-free producibility. Acute angles between the building substrate and the part's surface require a support structure. This is due to the residual stress within the material resulting from the rapid cooling rates [62]. Without any

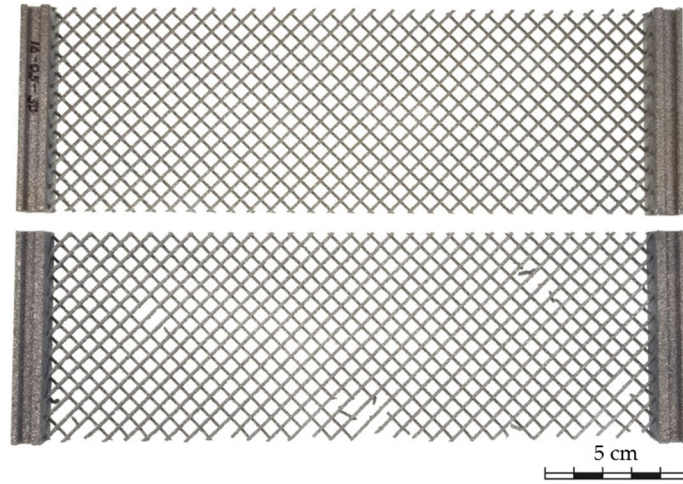


Fig. 5 Pantographic sheet with a beam diameter of 1 mm manufactured of AlSi10Mg. Bottom: Sample manufactured by standard manufacturing parameters. Top: Sample manufactured by adapted exposure parameters and strategy

connection of the part to the substrate, the part would deform within the process causing the coating unit to jam. Furthermore, surfaces with an acute angle result in a poor surface quality regarding roughness, surface cracks and surface porosity. Therefore, it is advisable to avoid part orientations with major surfaces of an acute angle.

Adapted manufacturing parameters for a metamaterial The pantographic sheet was manufactured in a 45° angle rotated around its axial line in order to prevent any acute angles. All surfaces show therefore a 45° angle toward the substrate plate. A further advantage of this orientation is that the exposure cross section within a layer offers more surface than the actual beam cross section and therefore enables longer laser tracks. As a second measurement, a setup of a single exposure area was applied within the lattice. In order to increase the laser track length to a maximum, circular laser tracks were applied instead of a stripe strategy. Furthermore, the exposure speed was minimized, which also required an adaption of laser power and hatch distance (spacing between laser tracks). As a result, it is possible to manufacture the pantographic sheet without any visual damage. A comparison of standard parameters and the adapted manufacturing parameters is illustrated in Fig. 5. The specimens were manufactured under the same building orientation.

3 Tomographic analyses on aluminum samples

3.1 Micro-X-ray CT imaging

A ZEISS micro-X-ray CT machine was used to acquire the images (ZEISS Xradia 410 Versa 2018). This machine uses X-rays to map the microstructure of an object at micrometer to millimeter scales. The imaging modality works on the principle of density contrast. That is, the X-rays would transmit through the sample such that the areas where less X-rays get through are the denser parts and the areas where more X-rays get through indicate less dense parts in the materials. The $10\times$ objective was used to image the samples which results in a digital image with a square field of view of side $\sim 1.5 \times 10^3 \mu\text{m}$ and pixel size $\sim 0.86 \mu\text{m}/\text{pixels}$. A total of 1441 images at the frequency of 4 images per degree of rotation were acquired for tomographic reconstruction. The overall imaging time varied from 8 to 12h depending on the exposure time per image. Subsequently, using the *Reconstructor* software, the images acquired were assembled as a 3D structure shown in Fig. 6. The reconstructed 3D structure has a voxel size of $1.72 \times 1.72 \times 1.72 \mu\text{m}^3$. A visual inspection of the reconstructed structure reveals a smooth internal texture for the aluminum with spherical pores of varying sizes. This observation is not unexpected since the SLM process was used for its fabrication.

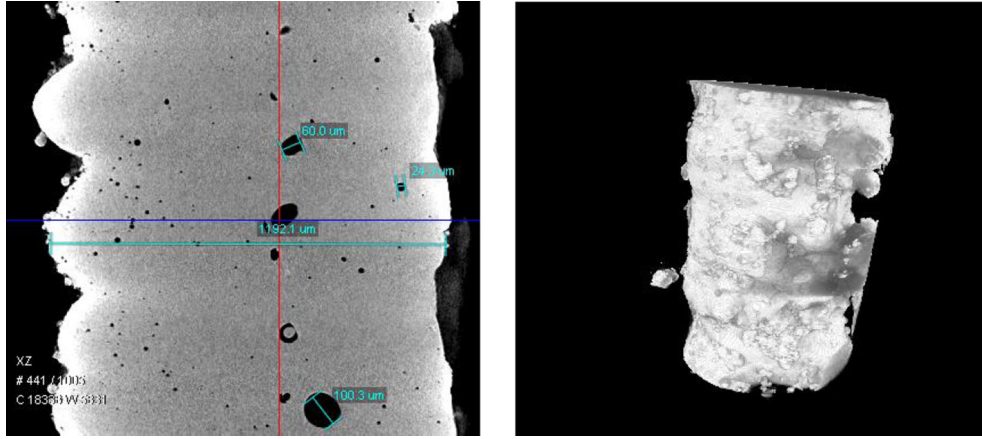


Fig. 6 Reconstructed 10 × Aluminum

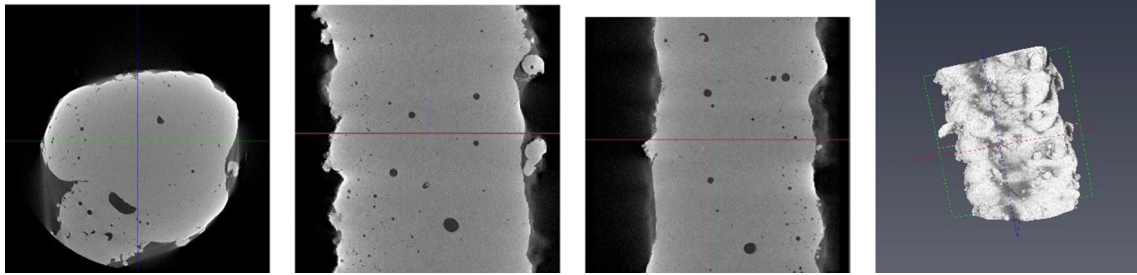


Fig. 7 Selected sections in xy -, xz -, yz -planes and the 3D solid, of the original reconstructed μ XCT image for aluminum specimen, showing irregular boundaries

3.2 Avizo 3D analysis

Porosity analysis was performed using the wizard and image segmentation tool of Avizo (Avizo 9.5.0 software). To ensure that the segmentation tool could identify the interior pore spaces, the reconstructions were cropped down to cubes to avoid the irregular boundary effects. Figure 7 illustrates the boundary irregularity in the original reconstruction for aluminum specimen, shown as selected sections in xy -, xz -, yz -planes and the 3D solid, respectively. Multiple cubical samples were taken from different locations of the original reconstruction to ensure that the major topographic features (i.e., pore spaces) of the original reconstruction were represented. Figures 8 and 9 give three instances of the cubical samples for aluminum specimen of size $400 \times 400 \times 400$ voxels shown as selected sections in xy -, xz -, yz -planes and the 3D solid, respectively. The cubical sample sizes were predicated by the original cross-sectional dimensions of the beam specimens and their orientation in the xy -plane. Avizo's segmentation tool was used to define the labels of the material volume versus the pore volume in the cropped cubical samples. Once the areas were defined, Avizo's label analysis tool was used to calculate the image statistics. The porosity analysis wizard was also used to obtain the pore size distribution. Porosity is defined as the ratio of the pore volume to the total volume. The average porosity of the aluminum specimen was found to be 6.54%. For aluminum specimen, the maximum pore size varied from 167.7 to 194.8 μm , while the median pore size ranged from 4.8 to 7.7 μm for the three cubical samples. Figures 8 and 9 show that the pores in these specimens are mostly spherical.

4 Aluminum-printed structures

Extensional tests were performed on three aluminum-printed specimens of pantographic structure. The microstructure of the aluminum samples is described by the parameters shown in Fig. 10 whose values are reported in Table 1. The force versus displacement graphs are obtained by testing the specimens in a so-called BIAS extension test which can be experimentally performed by clamping one of the two sides of the sheet and imposing a longitudinal displacement to the other side. Herein we analyze the behavior under extension

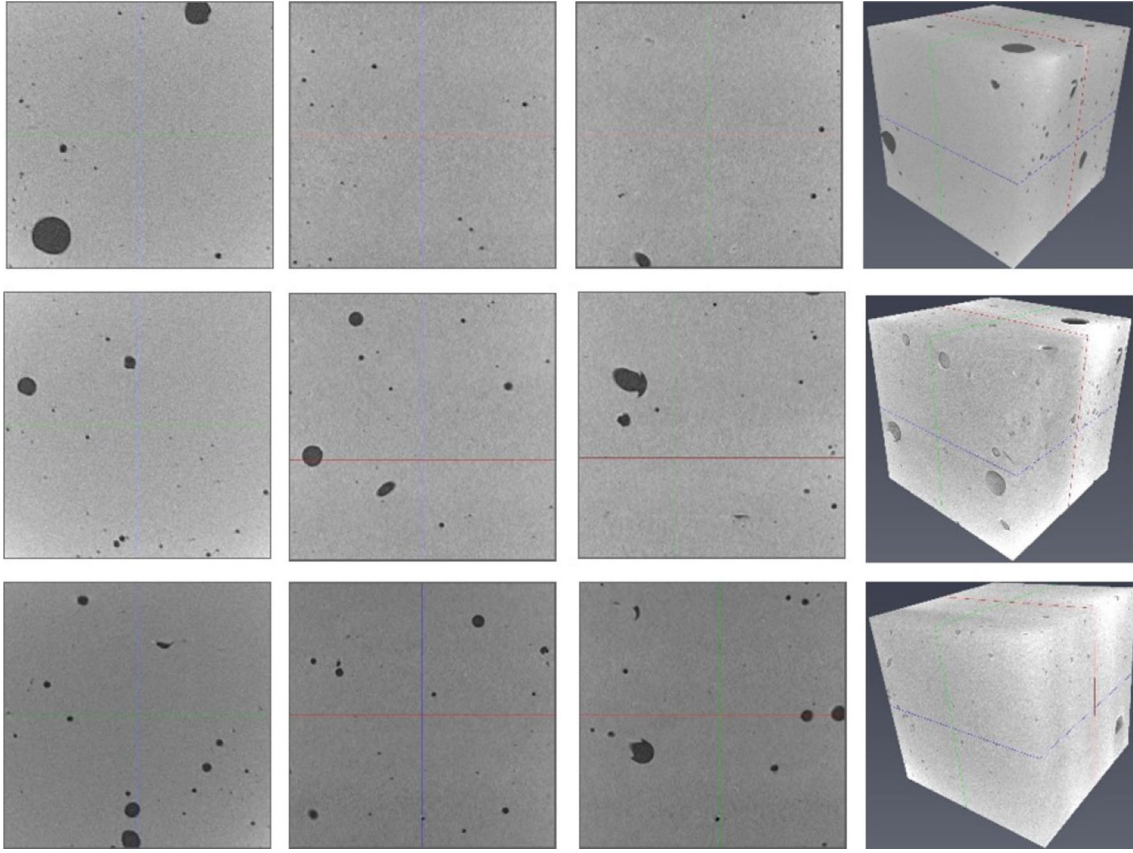


Fig. 8 The columns give selected sections in xy -, xz -, yz -planes and the 3D solid, respectively, for three cubical samples (rows) cropped from the top, mid- and lower regions of the original reconstructed μ XCT image for aluminum specimen

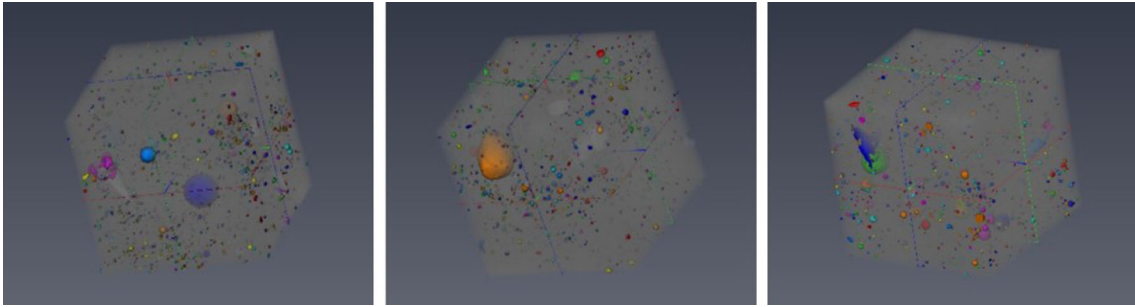


Fig. 9 Pore structures with the three cubical samples cropped from the top, mid- and lower regions of the original reconstructed μ XCT image for aluminum specimen. The mostly spherical shapes of the pore spaces can be readily seen

of the three samples in order to determine (1) their elastic range, (2) the incipient plasticity and (3) the ensuing the damage and failure process. According to the prescribed experimental test conditions, three types of bias tests were performed as summarized in Table 2. The first type of test was designed to evaluate the elastic range of considered specimens. For this aim, cyclical extension tests were performed with loading and unloading phases, on specimen designated as sample A. The complete loading history of the test is depicted by the plot in Fig. 11, but we will show each stage of the experiment separately. In Fig. 12a, b are shown the force–displacement plots corresponding with the first two load cycles performed on sample A. A first stretch step of 1 mm is prescribed, and subsequently, a second load step up to 2 mm is applied. At the end of each step, the unloading phase follows. The deformation rate is 0.1 mm/s to ensure that no inertial contribution occurs. The plots in Fig. 12 clearly show that the trend of both curves is linear, highlighting a direct proportionality between reaction force and imposed displacement. Furthermore, in both graphs the loading and unloading

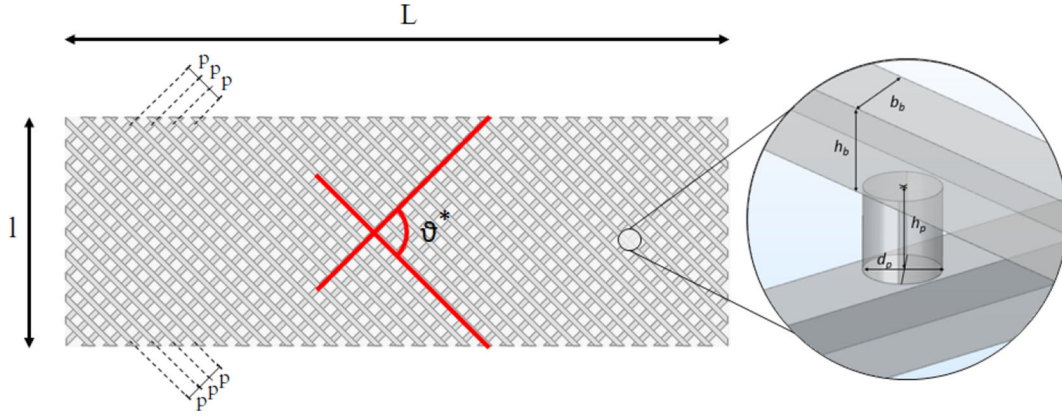


Fig. 10 Geometry and microstructure parameters

Table 1 Fibers and pivot dimensions are measured in millimeter, and angles are measured in radian

b_b	h_b	d_p	h_p	L	l	ϑ^*	p
1.0	0.6	0.9	3.0	210	70	$\pi/2$	4.85

Table 2 Tests performed on aluminum specimens

	Type of test	Cyclic test	Destructive	Deformation rate (mm/s)
Sample A	Extension	Yes	Yes	0.1
Sample B	extension	No	Yes	0.33
Sample C	extension	Yes	Yes	0.05

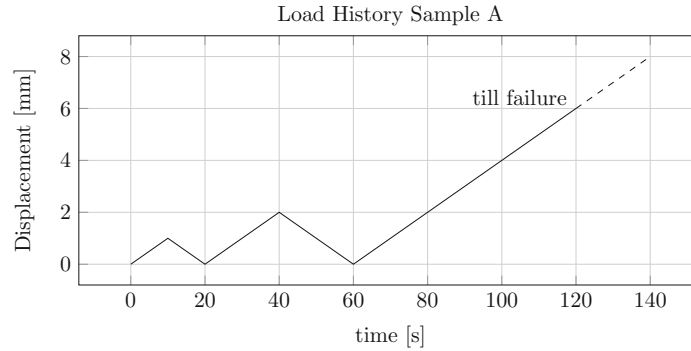
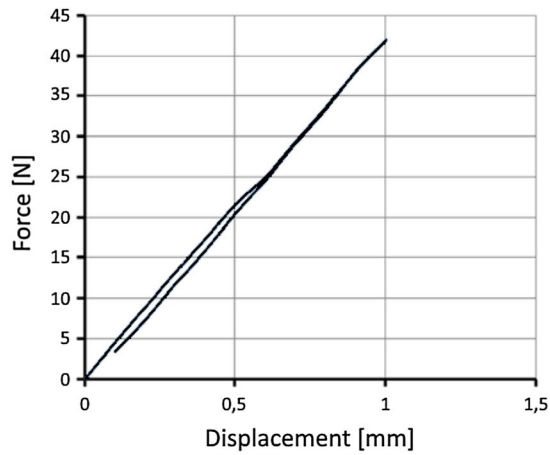
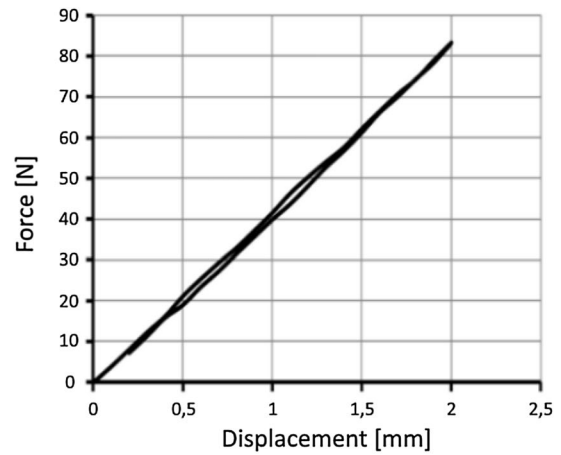


Fig. 11 Displacement versus time plot describing the load history applied to aluminum specimen A

phases almost coincide suggesting a linear elastic behavior. After this cyclic phase, sample A is stretched until complete rupture. As shown in Fig. 13a, a linear stage can be considered up to 3 mm of elongation, while in Fig. 13b we can notice the initiation of a nonlinear stage. Looking at the whole BIAS extension test on sample A shown in Fig. 14, it can be observed that the mechanical behavior is elasto-plastic with strain hardening until a maximum in the reaction force is reached. This can be really observed by unloading the structure and showing that the deformation has been irreversible (see Fig. 21). After that, a softening part occurs before the first rupture. The first rupture event is related to the collapse of one of the external pivots highlighted in the circle in Fig. 15 that are located at about $\frac{1}{3}L$. In the following, we will give an interpretation of this event on the basis of some specific mechanism similar to the ones studied in [63]. Despite this rupture, the specimen still exhibits a certain load capacity, as at least other three breakages occur before the total failure. In Fig. 16, the failure sequence is shown: Every frame displayed corresponds to a rupture point beyond the first break in the graph.

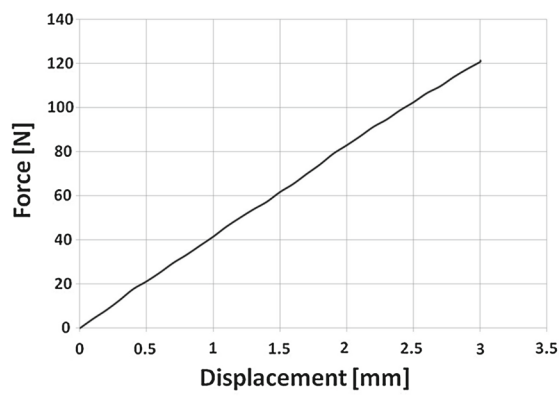


(a) 1 mm stretch and unloading

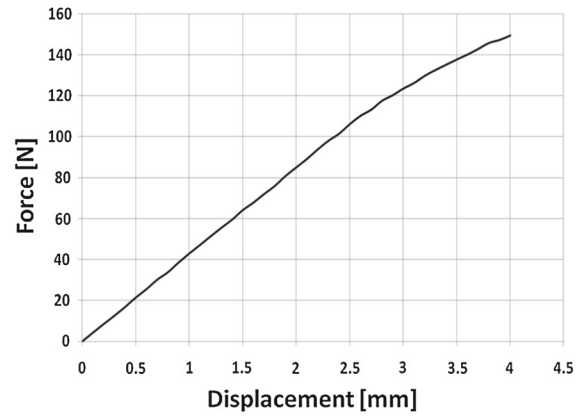


(b) 2 mm stretch and unloading

Fig. 12 Load-unload cycle on aluminum sample A



(a) 3 mm stretch



(b) 4 mm stretch

Fig. 13 Limit of elastic range of aluminum sample A



Fig. 14 Entire extensional test graph of aluminum sample A

We next compare the described results (sample A) to the ones relative to the second sample (sample B). Sample B has been stretched until complete rupture without a previous cyclic test, at a deformation rate of 0.33 mm/s (see Fig. 17). Although for sample B, the elastic phase has not been determined specifically, it is

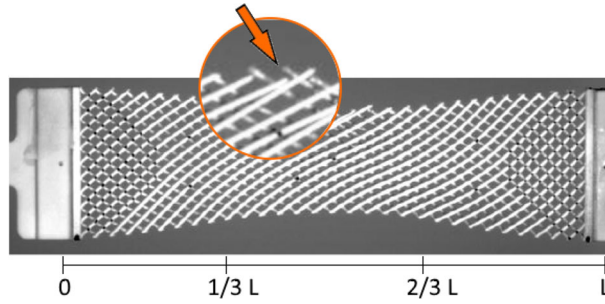


Fig. 15 Aluminum sample A first break

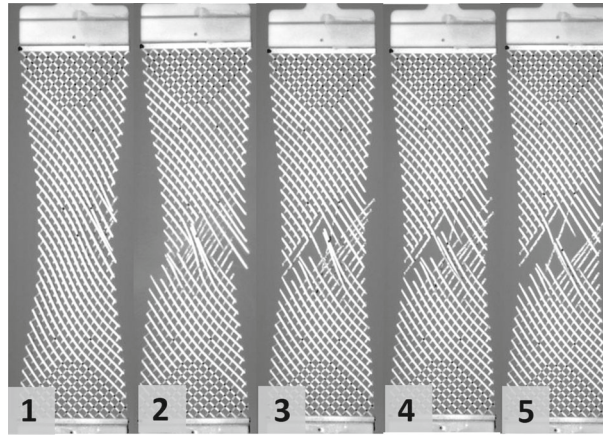


Fig. 16 Aluminum sample A all breakages

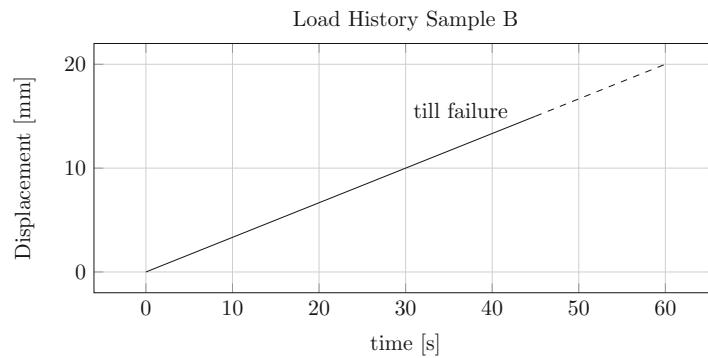


Fig. 17 Displacement versus time plot describing the load history applied to aluminum specimen B

possible to recognize a linear part of the force–displacement curve. The plot shows an overall strain hardening behavior and a softening branch before the first rupture. After the proportionality limit (settled by hypothesis—by comparing the plot in Fig. 18 with the result observed for sample A—at 2 mm of stretch), the trend becomes nonlinear for higher displacement values, exhibiting strain hardening. For sample B, the softening seems to trigger at 8 mm of elongation and progresses gradually till complete rupture. It is interesting to compare the behavior of samples A and B. It is clear that the shape of the two curves is very similar, and likewise sample B, also sample A has an initial linear part that corresponds to a linear elastic behavior. Despite a very similar overall trend, there are significant differences between the two specimens (Fig. 19). The most obvious is the resistance, in terms of reaction force provided, and the capability to deform. Figure 20 shows that sample B begins to soften much earlier (before 10 mm of displacement) compared to sample A, which stretched twice as much before the commencement of damage softening.

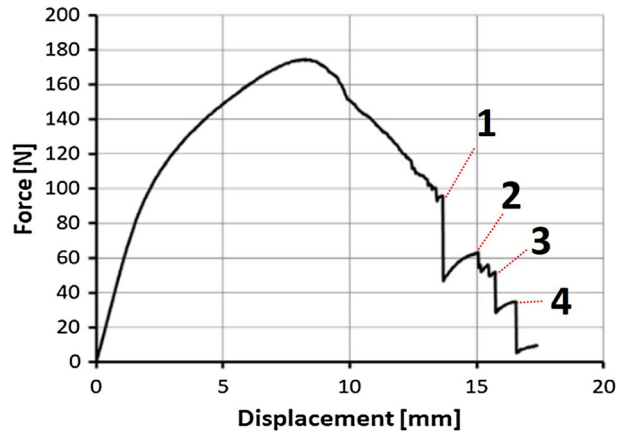


Fig. 18 Entire extensional test graph of aluminum sample B

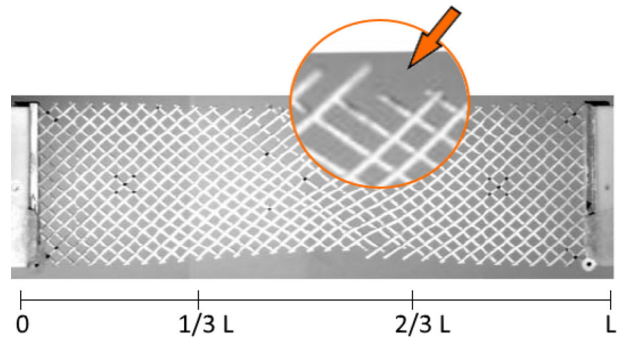


Fig. 19 Aluminum sample B first break

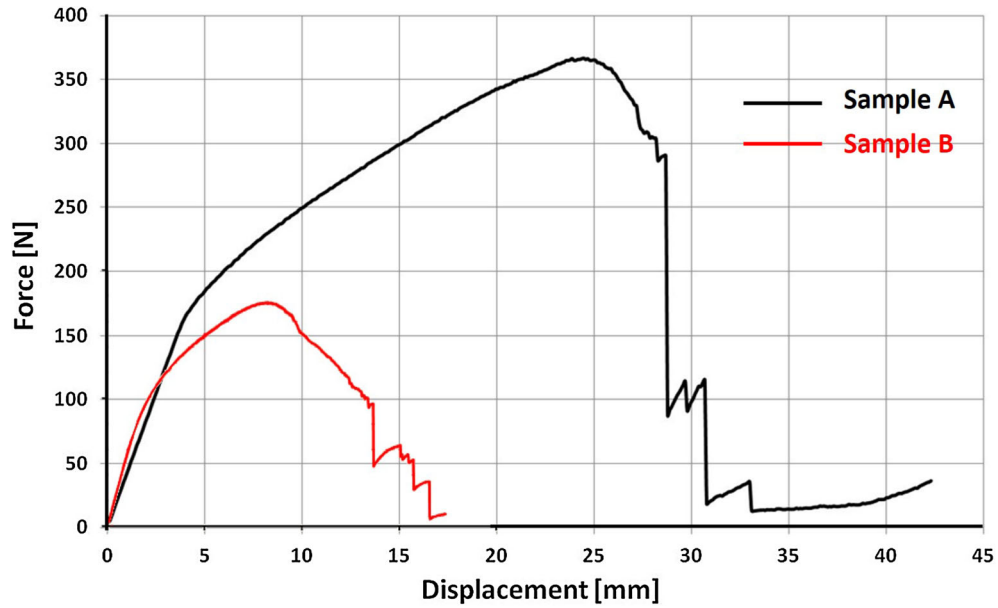


Fig. 20 Comparison between bias test results on sample A and B

We now present the results relative to sample C, subjected to a cyclic extension test. This experiment was designed to examine the behavior beyond the elastic limit of considered specimen. Sample C has been submitted to a higher number of load-unload cycles as given by the graph in Fig. 23. The first two cyclic phases, which

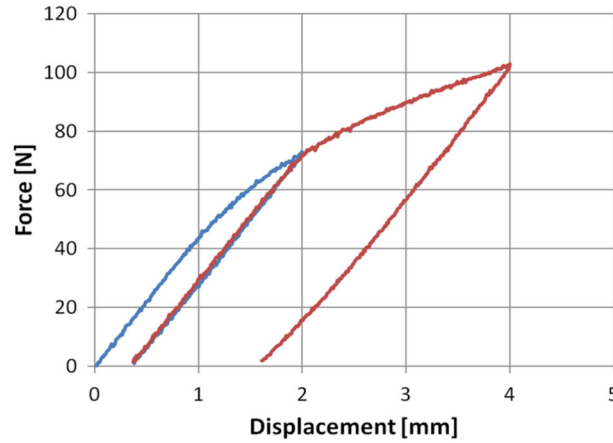


Fig. 21 Two load cycles applied on aluminum sample C

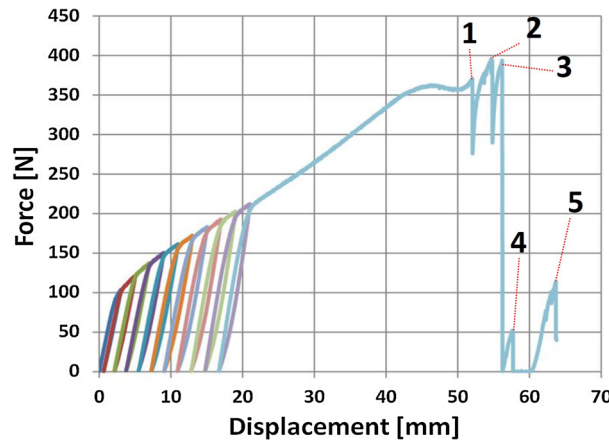


Fig. 22 Cyclic test and stretch until failure of aluminum sample C

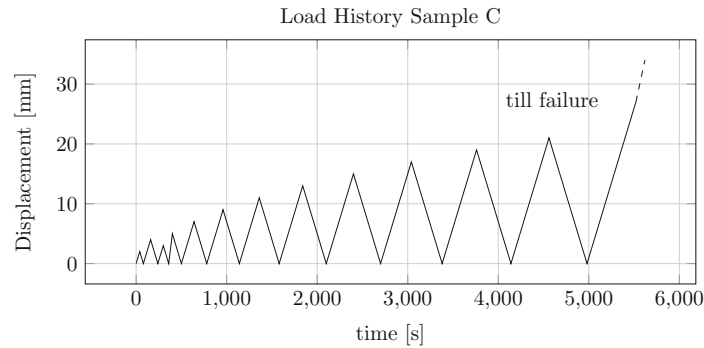


Fig. 23 Displacement versus time plot describing the load history applied to aluminum specimen C

prescribe an elongation up to 2 mm and unloading and subsequently an elongation up to 4 mm and unloading, are summarized by the force–displacement plot in Fig. 21. In first stage, the force–displacement relation is linear (see Fig. 21) up to an elongation of about 1 mm; after that, a nonlinear stage starts. The subsequent cycles are carried out beyond proportionality limit under the condition of plasticized material. Indeed, a residual deformation can be evaluated at the end of each unloading stage. We can remark that, when a greater number of load cycles are carried out, the shape of the resulting force–displacement curve appears to have little influence of the loading cycles as every cycle shows the same overall trend (see Fig. 22). At the end of the cyclic part, the loading is continued until total rupture of the specimen. As for the two previous cases, the

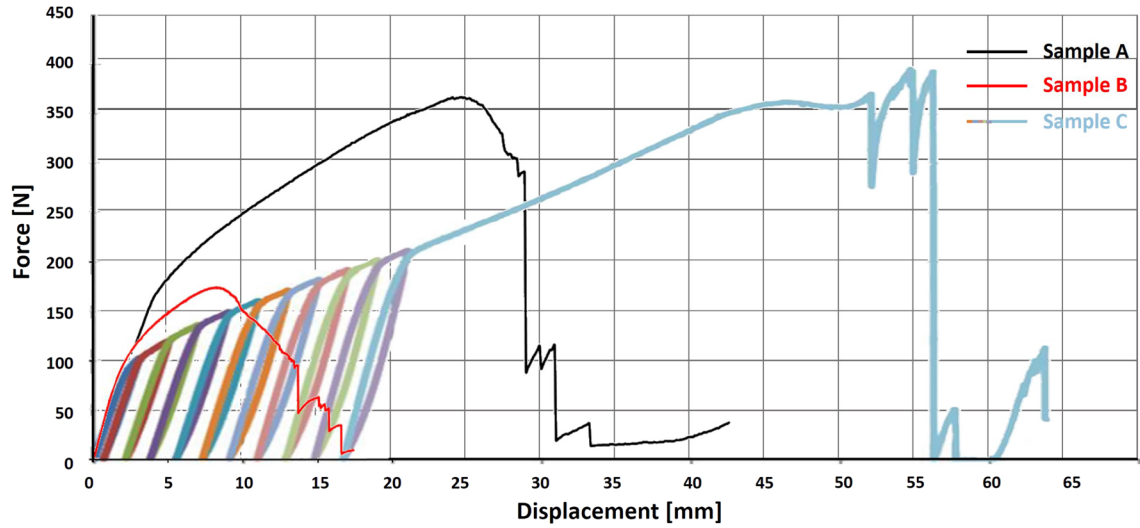


Fig. 24 Comparison between the force–displacement plots relative to samples A, B and C

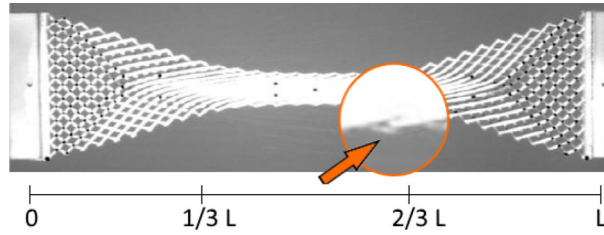


Fig. 25 Aluminum sample C first break

softening represent the beginning of the damage of the specimen and the activation of the rupture mechanism, but the softening phase is much less evident. Indeed, the reaction force does not have a relevant drop and its value even rises again after a small increase in stretch. Also, when the first break occurs the force does not decrease by a significant value. The second and third break happen at force level even higher, reaching 400 N (Fig. 23).

Comparing these results to the previous cases, some similarities and differences emerge (see Fig. 24). The overall trend is very similar to that shown by samples A and B before the commencement of damage. Moreover, in this case also the specimen starts to rupture due to the collapse of a pivot, whose position is highlighted in Fig. 25. Looking at the comparison plots reported in Fig. 24, the main difference is the greater deformation reached by the specimen C compared with sample A and B. It is remarked that the three samples have the same slope for the linear stage but a very different behavior after that, although they have the same microstructure and were fabricated in a single batch.

5 Inox-printed structures

We now describe the results obtained for BIAS extension test performed on inox-printed specimens. As in the case of aluminum specimens, the intent is to evaluate the limit of elastic stage, the behavior in the plastic phase and the initiation of the failure process. The setup for the tests is the same as for the aluminum specimen. In addition, the experiments prescribe both cyclic and monotonic tests. The details of the type of the test performed for every sample are listed in Table 3. The microstructure is same as the aluminum-printed specimens, and it is described by the parameters listed in Table 4 (Fig. 26).

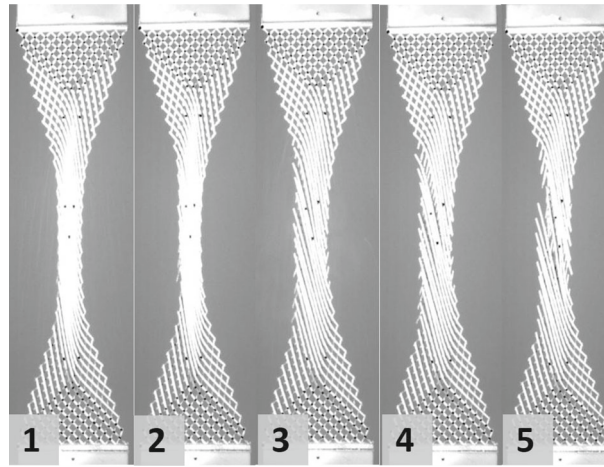
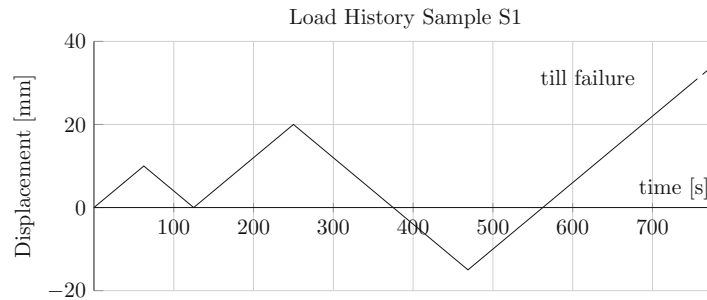
We first discuss the results of the tests performed on sample S1. This specimen has been subjected to different loading stages (see Fig. 28) which are (1) a cyclic extension phase, (2) a compression phase and then (3) a stretch phase up to rupture. The complete load history applied on sample S1 is plotted in Fig. 27.

Table 3 Tests performed on inox-printed specimens

	Type of test	Cyclic test	Destructive	Deformation rate (mm/s)
Sample S1	Extention and compression	Yes	Yes	0.16
Sample S2	Extention	No	Yes	0.5
Sample S3	Extention	No	Yes	0.5
Sample S4	Extention	No	Yes	0.5

Table 4 Fibers and pivot dimensions are measured in millimeter, and angles are measured in radiant

b_b	h_b	d_p	h_p	L	l	ϑ^*	p
0.8	1.0	0.4	0.8	90	30	$\pi/2$	1.48

**Fig. 26** Aluminum sample C all breakages**Fig. 27** Displacement versus time plot describing the load history applied to steel specimen S1

In Fig. 28, the top graph shows the first cyclic stage, for the two extension cycles of 10 mm each. In this stage, the linear elastic behavior cannot be clearly demarcated. Indeed, the curve appears to exhibit nonlinear behavior immediately upon loading. Further, at the first unloading corresponding to 10 mm stretch, a residual elongation is measured upon unloading suggesting the onset of plastic behavior. Referring again to the top graph in Fig. 28, the second cycle seems to underline an isotropic strain hardening given the way the curve resumes its path upon reloading. A second stage involving a compression test on sample S1 is depicted in the middle graph in Fig. 28. Also in this case, there is no linear branch. It appears that the shape of the compression curve has some similarities to the first cycle of tension test reported in the top graph in Fig. 28. Notably, the values of the reaction force are approximately the same but with opposite sign. The bottom graph in Fig. 28 presents the force versus displacement plot up to rupture for the sample S1 under tension. The maximum axial force is about 2500 N at 30 mm of stretch. Overall, the graph shows a work hardening of the specimen,

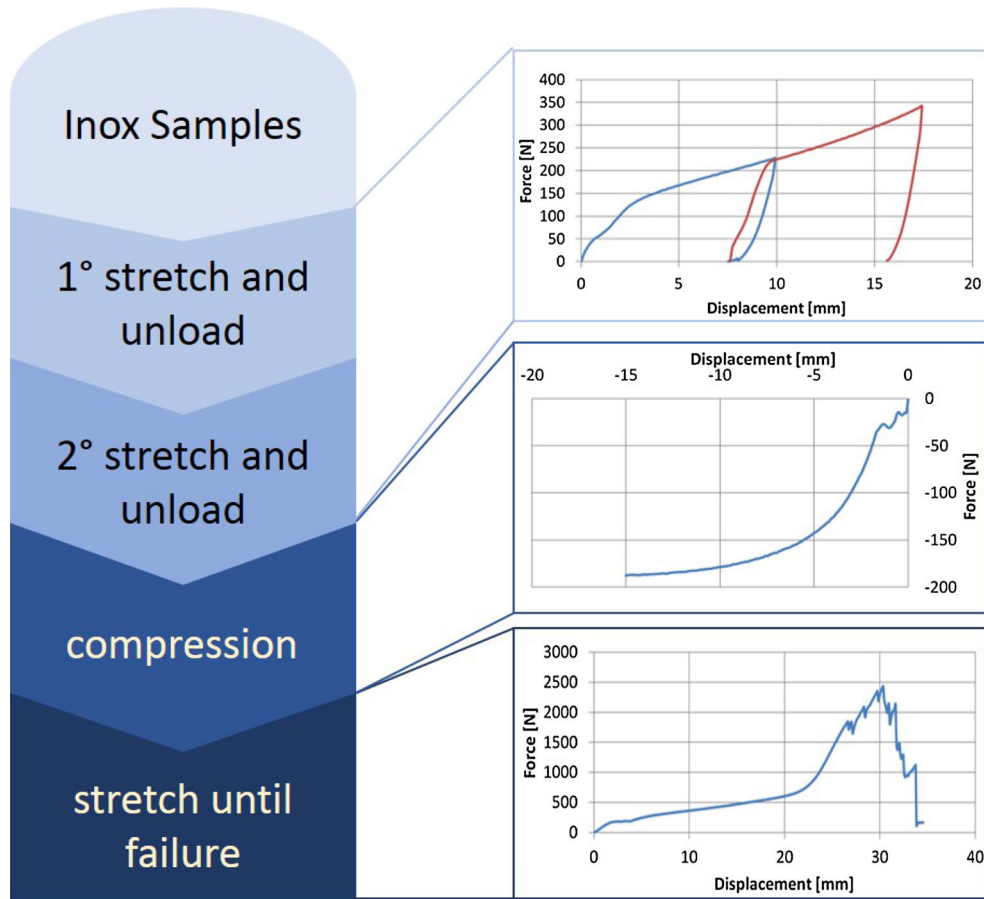


Fig. 28 Summary scheme of all experiments performed on inox sample S1

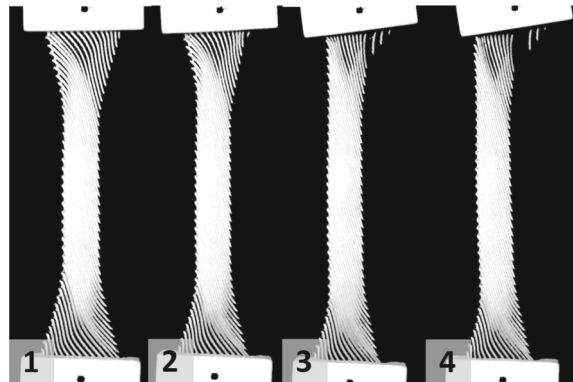


Fig. 29 Propagation of the failure under BIAS extension test performed on inox sample S1

which is much clearer after 22 mm of stretch. Indeed, the rupture phase is preceded by a last step in which the reaction grows very rapidly. Some fluctuations are recorded before the first rupture point, but their trend is still upward, highlighting a typical behavior of pantographic structures. (We will remark resiliency as a feature typical of pantographic structures.) Furthermore, when the first rupture occurs, the sample still has capacity of deformation before the definitive failure. The rupture behavior registered for sample S1 shows a fundamental difference with respect to aluminum samples: In this case, the failure is caused by tensile collapse of the outer fiber on one of the two constrained sides, as shown in Fig. 29.

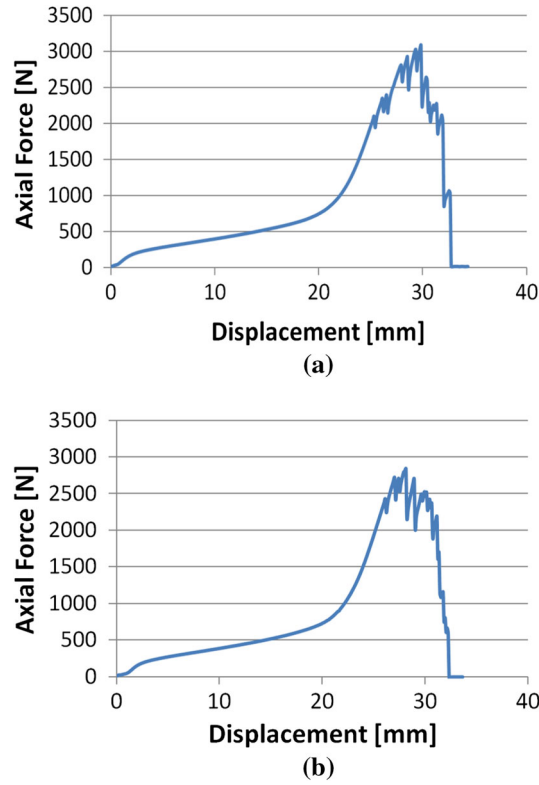


Fig. 30 Force versus displacement plots of BIAS extension test for **a** sample S2, **b** sample S3

A very similar overall behavior has been observed in BIAS extension tests of other inox-printed pantographic structures, as well as the failure mechanism (the extension of the external fibers is always involved), as shown in Fig. 31. In Fig. 30, the force versus displacement plots for the three inox samples are presented: The shapes of the curves are very similar. Likewise, the graphs point an acceleration in the work hardening mechanism around 20 mm of stretch that leads the specimens to exert the maximum reaction force at about 30 mm of stretch. A difference can be noted in the maximum value of the reaction of specimen S1, which is lower than other two, being about 2500 N the former and about 3000 N the latter. This response is likely due to the initial cyclic loading done on S1 specimen. However, strong similarities emerge from Figs. 30 and 31.

Another peculiarity behavior provided by the microstructure emerges from a BIAS extension test performed on inox sample S4, whose force versus displacement plot is shown in Fig. 32. Looking at the graph, it is noticeable that at about 8 mm of stretch the graph has a little dip that it could be related to a structural imperfection. However, this fact does not alter the overall behavior of the specimen that continues its strain hardening in the same way as the other inox samples. This last evidence proves that the pantographic structure is reliable also against constructive defects.

6 Interpretation of experimental results: proposed models

The experimental data described in the previous sections show that two types of rupture mechanisms can occur in the extension test of pantographic structures. Specifically, for the aluminum specimens, the failure, caused by the breaking of pivots, triggers at external point of their longer side. On the other hand, for the inox specimens, the onset of the rupture mechanism is located close to the vertices of the clamped edges. The different behavior can be related to the geometric features of the pivots, which are the most deformed element of the pantographic lattice. When the pivots have a slender shape, as in the case for the presented aluminum specimens, they undergo flexural deformation superimposed on to the twist deformation due to the relative rotation of the beams. Most of the experimental and numerical evidences in the literature consider pantographic structures characterized by short pivots with negligible flexibility. A numerical modeling of the

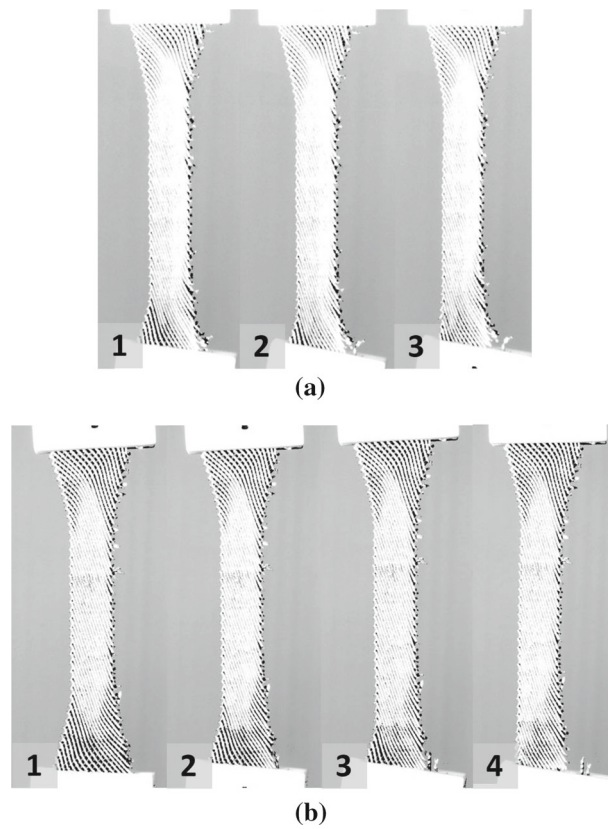


Fig. 31 Failure propagation under BIAS extension test for **a** sample S2, **b** sample S3

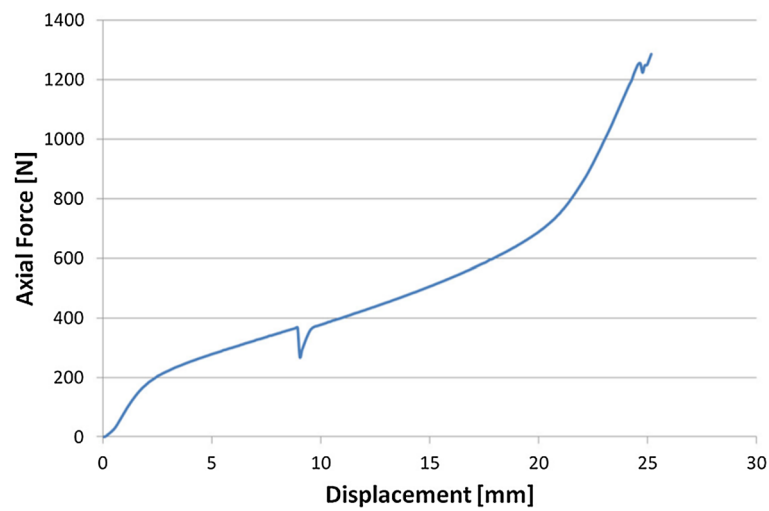


Fig. 32 Force versus displacement graph related to inox sample S4: the constructive defect indicated by the local dip at about 8 mm of extension does not influence the overall behavior of the specimen under BIAS extension test

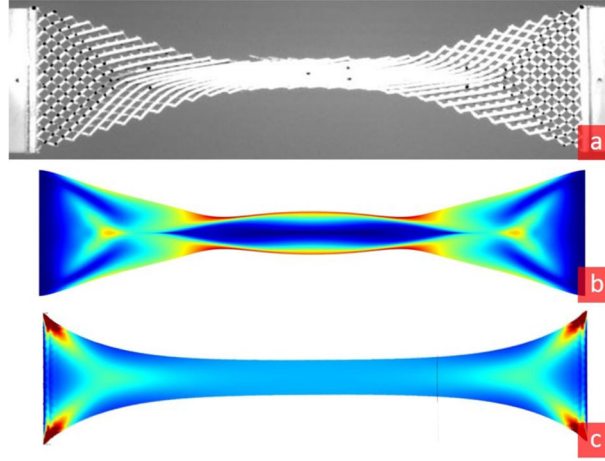


Fig. 33 Comparison between the deformation of an aluminum sample (a) and numerical simulations of a BIAS extension test for b two-placement field strain energy density of Eq. 2 and c one-placement field strain energy density of Eq. 1. Colors indicate strain energy density (color figure online)

mechanical behavior of such pantographic structures is possible using the homogenized expression of strain energy density for an elastic surface with a pantographic microstructure defined in [13], which is

$$\begin{aligned}
 W(\chi) = & \int_{\Omega} \sum_{\alpha} \frac{K_e^{\alpha}}{2} (\|\mathbf{F}\mathbf{D}_{\alpha}\| - 1)^2 d\Omega \\
 & + \int_{\Omega} \sum_{\alpha} \frac{K_b^{\alpha}}{2} \left[\frac{\nabla \mathbf{F} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha} \cdot \nabla \mathbf{F} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha}}{\|\mathbf{F}\mathbf{D}_{\alpha}\|^2} - \left(\frac{\mathbf{F}\mathbf{D}_{\alpha}}{\|\mathbf{F}\mathbf{D}_{\alpha}\|} \cdot \frac{\nabla \mathbf{F} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha}}{\|\mathbf{F}\mathbf{D}_{\alpha}\|} \right)^2 \right] d\Omega \\
 & + \int_{\Omega} \frac{K_p}{2} \left| \arccos \left(\frac{\mathbf{F}\mathbf{D}_1}{\|\mathbf{F}\mathbf{D}_1\|} \cdot \frac{\mathbf{F}\mathbf{D}_2}{\|\mathbf{F}\mathbf{D}_2\|} \right) - \frac{\pi}{2} \right|^{\gamma} d\Omega
 \end{aligned} \quad (1)$$

The expression in Eq. 1 depends upon a single placement field χ , being $\mathbf{F} = \nabla \chi$, which does not consider the sliding between the two families of beams. Further investigations were the motivation for a series of papers [17,22,32,64,64] concerning numerical simulations of BIAS extension tests performed by employing Eq. 1 as strain energy density. These works demonstrate that the homogenized model is able to describe the behavior of polyamide pantographic structures (i.e., the homogenized model predicts that the concentration of strain energy is located where the samples break, as shown by the plot in Fig. 33a). For different geometries of the microstructural elements, such as the case of the aluminum specimen, the flexibility of the pivots is no more negligible, and the strain energy density must also consider that the no sliding constrain between the two arrays of fibers does not hold. In [63], in order to describe the kinematics of the pantographic structure with slender pivots a modified version of the bi-dimensional elastic surface model has been presented, which, in contrast to [13], takes into account relative displacements between the two families of fibers. This assumption results in a homogenized form of strain energy which depends on two different placement fields and it is defined by

$$\begin{aligned}
 W(\chi^{\alpha}) = & \int_{\Omega} \frac{K_e^{\alpha}}{2} (\|\mathbf{F}^{\alpha}\mathbf{D}_{\alpha}\| - 1)^2 d\Omega \\
 & + \int_{\Omega} \frac{K_b^{\alpha}}{2} \left[\frac{\nabla \mathbf{F}^{\alpha} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha} \cdot \nabla \mathbf{F}^{\alpha} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha}}{\|\mathbf{F}^{\alpha}\mathbf{D}_{\alpha}\|^2} - \left(\frac{\mathbf{F}^{\alpha}\mathbf{D}_{\alpha}}{\|\mathbf{F}^{\alpha}\mathbf{D}_{\alpha}\|} \cdot \frac{\nabla \mathbf{F}^{\alpha} | \mathbf{D}_{\alpha} \otimes \mathbf{D}_{\alpha}}{\|\mathbf{F}^{\alpha}\mathbf{D}_{\alpha}\|} \right)^2 \right] d\Omega \\
 & + \int_{\Omega} \frac{K_p}{2} \arccos \left(\frac{\mathbf{F}^1\mathbf{D}_1}{\|\mathbf{F}^1\mathbf{D}_1\|} \cdot \frac{\mathbf{F}^2\mathbf{D}_2}{\|\mathbf{F}^2\mathbf{D}_2\|} \right) - \frac{\pi}{2} \right|^{\gamma} d\Omega \\
 & + \int_{\Omega} \frac{K_{int}}{2} \|\chi^1 - \chi^2\|^2 d\Omega
 \end{aligned} \quad (2)$$

where the superscript α indicates the considered family of fibers. In Eq. 2, we used $\mathbf{F}^{\alpha} = \nabla \chi^{\alpha}$ and no sum over repeated α is intended. We refer to [63] for the comparison between the constants in Eqs. 1 and 2. This

expression for the strain energy density describes the behavior of the pantographic system by means of two independent placements for each of the two fiber arrays, whose interaction is governed by the last term of Eq. 2, that is,

$$\int_{\Omega} \frac{K_{\text{int}}}{2} \|\chi^1 - \chi^2\|^2 d\Omega \quad (3)$$

By introducing the interaction term in Eq. 3, the rupture mechanism of pantographic structures can be numerically reproduced to provide a good match with experimental measurements. Indeed, in [63] it is shown that by employing Eq. 2 in a numerical simulation of extension test, higher values of strain energy density are found to be located precisely at external points on the longest sides. Clearly, the interaction term is necessary when the restrictive assumption in [13] does not hold. A qualitative comparison between strain energy density plots referring to one-placement field model and two-placement field model is shown in Fig. 33. It is noteworthy that Eq. 3 is characterized by the modulus K_{int} which has to be related to the deformation of the pivots. As reported in [63], for high values of K_{int} , which is the case of very stiff pivots, the model produces the same results as that of the one-placement model found in [13]. Furthermore, the dependence of the stiffness K_{int} upon the modulus of the relative displacement of the fibers can be employed to describe the deterioration of the mechanical properties of the specimen, i.e., for the definition of stepwise function in which K_{int} changes depending on $\delta = |\chi^1 - \chi^2|$. With the aim of forecasting the behavior of pantographic lattices and of defining their failure criteria, it can be remarked that to use a modified version of the strain energy density allows us to evaluate more cases as the one-field model results to be the limit of the two-field model for high values of K_{int} .

Further, we must remark that some similarities in behavior emerge when we compare results from polyamide specimens with the inox specimens. The pantographic microstructure of polyamide samples, as the inox ones, is designed with short pivots and, despite the great difference existing between the mechanical properties of the constituent material (i.e., the Young's modulus) which result, obviously, in much more stiffer specimens in terms of reaction force exerted, the rupture mechanism triggers near the clamped edges in both cases.

7 Conclusion

The experimental data regarding pantographic structure have been extended to new constitutive materials. The most innovative and promising manufacturing techniques have been used to print aluminum and inox–steel specimens, whose qualitative behavior (focusing on the determination of the elastic limit and plastic and failure process) under BIAS extension test has been tested. The acquired data about this novel metal-printed specimens are added to those already available regarding polyamide specimens. Comparisons can be made between the sets of pantographic structures shown in this work. Both the samples demonstrate the great compliance of the material which can reach large deformations. This feature is shared with the polyamide specimens tested in previous works, so it is possible to relate it to the specific pantographic microstructure rather than the constitutive material. Furthermore, the specimens tested exhibit reliability toward the failure process which never happens suddenly, but once triggered it gradually spreads. Clearly, the different material affects some of quantitative properties: As fundamental example, consider the range of the measured reaction force, influenced by the different Young's modulus. Furthermore, one has to notice that the inox–steel specimens have a capacity of greater deformation rather the aluminum samples if we consider that the long side of the inox specimens is less than half long as the aluminum ones. A main difference between the rupture nature of the two sets of specimens emerges. While in the case of aluminum specimen the resistance of the pivots is involved, in the inox case the failure must be related to the tensile strength of the fibers. Also, the region where the rupture triggers is different. Two models in the literature have been recalled with the aim of relating the type of failure to the mathematical model suitable to predict it. Strain gradient modeling has proved to be useful also in regularizing mesh-dependent problems in continuum damage and fracture mechanics, where localization of deformations is frequently observed. Implementation of such regularization in second gradient materials would be straightforward, also in view of parameters identification carried out in [65–69]. By means of a variational asymptotic procedure, in [70] it has been derived a one-dimensional continuum model for the description of finite motions of elastic planar slender pantographic structures, whose highly exotic features are discussed. We show that, remarkably, the deformation energy density of such continuum depends, like the *Elastica*, not only on the Lagrangian curvature but also on the elongation gradient. Such one-dimensional continuum exhibits phase transition and negative stiffness as well.

Apart from the models considered here, an independent and novel approach to understand the large deformation of beams and networks of beams as pantographic structures to be investigated in the future is to regard a beam as the boundary curve of a two-dimensional manifold in a three-dimensional space. For this purpose, the curve is to be endowed with its own energy similar to the one not only in the context of lower-dimensional energetics [71] but also in a geometrically nonlinear framework [72] and in accordance with higher gradient elasticity accounting for boundary energetics elaborated in [73]. The advantage of this approach, particularly from a computational viewpoint, is that the bulk material acts to regularize the behavior of the beam allowing in this way to analyze the instabilities associated with thin beams, which seem to be very similar to the instabilities of thin films on an elastic foundation [74]. One could be interested in studying the behavior of pantographic structures when embedded in softer matrices. Indeed, for potential applications it could be necessary to consider multiphase pantographic metamaterials. For this aim, it would be interesting to refer to [75,76] for the calculation of the effective properties of a planar alignment and of a bundle of fibers in a softer matrix. For some more general results, one can refer to [77–79].

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