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# Dynamic fracture in a semicrystalline biobased polymer: an analysis of the fracture surface

Jean-Benoît Kopp  · Jeremie Girardot

**Abstract** The fracture behaviour of a semi-crystalline bio-based polymer was studied. Dynamic fracture tests on strip band specimens were carried out. Fracture surfaces were observed at different scales by optical and electron microscopy to describe cracking scenarios. Crack initiation, propagation and arrest zones were described. Three distinct zones are highlighted in the initiation and propagation zone: a zone with conical markings, a mist zone and a hackle zone. The conical mark zone shows a variation in the size and density of the conical marks along the propagation path. This is synonymous with local speed variation. Microcracks at the origin of the conical marks in the initiation zone seem to develop from the nucleus of the spherulites. In the propagation zone with complex roughness, the direction of the microcracks and their cracking planes are highly variable. Their propagation directions are disturbed by the heterogeneities of the material. They branch or bifurcate at the level of the spherulites. In the arrest zone, the microcracks developed upstream continue to propagate in different directions. The surface created is increasingly smoother as the energy release rate decreases. It is shown that the local velocity of the crack varies in contrast to the macroscopic speed. A

specific setup allowing to estimate the minimum fracture energy of the material in order to maintain the rapid propagation of the crack is proposed for materials with antagonistic behaviour: ductile at initiation and brittle in propagation.

**Keywords** Dynamic fracture · Rapid crack propagation · Fracture surface analysis · Semi-crystalline · Polymer

## 1 Introduction

There are numerous studies in the literature on the fracture behaviour of materials and structures (Beguelin et al. 1997, 1998; Yoffe 1951; Broberg 1960; Freund 1972; Cros et al. 2000; Irwin et al. 1979; Sheng and Zhao 2000; Rosakis and Zehnder 1985; Ponsson and Bonamy 2010; Fineberg and Bouchbinder 2015; Lebihain et al. 2020; Le Barbenchon et al. 2020; Ravi-Chandar 1998; Sharon and Fineberg 1999). Approaches in the analysis of the mechanism vary widely depending on the point of view. Experimenters tend to replicate the mechanism more or less rigorously in the laboratory (Fond and Schirrer 2001; Kopp et al. 2018; Ravi-Chandar and Knauss 1984a; Kolvin et al. 2017). They describe it with ever more sophisticated tools and sometimes different interests. Some are interested in crack initiation (Bisoffi-Sauve et al. 2019; Rittel and Maigre 1996), some in crack propagation (Kopp et al. 2018; Fond and Schirrer 2001; Dalmas et al. 2013; Bonamy and Ravi-Chandar 2005), others in

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crack arrest (Imachi et al. 2020), and a comprehensive approach is often proposed by studying the mechanism at the macroscopic scale.

As introduced in Guerra et al. (2012), when a fast crack propagation is studied, some discrepancies can be observed between theoretical LEFM-based models and real measurements. Indeed, the study of local mechanisms at the microscopic scale such as micro cracks, micro-branches, and conical marks is then required and has been widely described for different kind of materials in the literature: (Sharon and Fineberg 1999; Arakawa and Takahashi 1991; Johnson and Holloway 1966; Ravi-Chandar and Knauss 1984b; Kies et al. 1950; Yang and Ravi-Chandar 1996; Ponson 2016; Ponson et al. 2006; Fineberg et al. 1991; Kolvin et al. 2017; Cambonie et al. 2015). The numerical tools that have significantly evolved over the last few decades largely complement the experimental observations : (Bisoffi-Sauve et al. 2019; Varela Valdez et al. 2018; Coré et al. 2018; Nishioka 1995; Imachi et al. 2020; Zhou et al. 2005). They are very useful where experimental tools are limited, such as for taking into account heterogeneities Villette et al. (2019), dynamic effects, micro- and macro-branches (Bleyer et al. 2016), micro-cracks, or for dimensioning structures.

When a cracking mechanism is studied in the laboratory, it is generally to describe the different mechanisms observable at different scales, to quantify the fracture parameters that will feed predictive models or to validate a numerical model (or method). From the micro- to the macro-scale, the description of the mechanisms is necessary although complex. This makes it possible to rigorously evaluate and predict the mechanisms that may lead to the collapse of a structure. Indeed, the appearance of micro- and macro-cracks is largely correlated to the microstructure and heterogeneities of the material, the mechanical stress or even the effects of the environment (Fineberg and Bouchbinder 2015). To analyse a dynamic fracture mechanism in mode I (opening mode), the formalism of linear elastic fracture mechanics (LEFM) advises a global approach with the energy release rate  $G$  or local with the stress intensity factor  $K$ . In dynamic regime and for most materials, the size of the fracture process zone remains negligible compared to the crack length. This can be very different for a supposedly ductile material when a crack propagates slowly. In this last case, the formalisms of fracture mechanics then suggest a local approach with the contour integral  $J$  (Rice 1964).

The fracture behaviour of polymeric materials has been extensively studied in the literature. Environmental effects (temperature and strain rate for example) can significantly modify the emerging behaviour of the material (Fond and Schirrer 2001; Kopp et al. 2018). By increasing the strain rate, a polymer can change from a visco-elastic plastic ductile to a elastic brittle behaviour. Studying the resistance to initiation (or slow propagation) or to rapid propagation can be significantly different for the same polymer material. The formalisms of fracture mechanics also. Homalite 100 and polymethylmethacrylate (PMMA) have regularly served as model materials for studying materials with brittle linear elastic behaviour. Their fracture facies have been widely described. Different characteristic zones exist. At crack initiation, conical markings can be observed (Kies et al. 1950; Yang and Ravi-Chandar 1996; Dalmas et al. 2013). They result from the interaction between a macro crack front and micro crack fronts that develop downstream of the main crack. The analysis of these marks in terms of density and size makes it possible to estimate the crack velocity (Guerra 2009). During the rapid propagation of the crack, the fracture surface is known as a hackle zone. This zone is chaotic in terms of roughness. Micro-branches, which Sharon and Fineberg (Sharon and Fineberg 1996) describe as the origin of non-trivial roughness, develop from a critical speed. Between these two zones (initiation and propagation) there is an intermediate zone, called mist. For homalite 100, it is established that in the mist zone, several small cracks propagate simultaneously and the front of the overall crack is almost straight (Ravi-Chandar and Knauss 1984a). In the hackle zone, crack growth occurs by the same physical process as in the mist zone, except that the size scale of the microfracturing increases. For PMMA, it has been observed that in the hackle zone, and for cracking speeds above about 500 m/s, the fracture surface becomes very rough with periodic microbranch-induced marks (Fineberg and Marder 1999). They generate arrest marks spaced about 1 mm apart, commonly called “ribs markings” because of their geometrical shapes. The high roughness observed in the hackle areas is generally not taken into account in the estimation of the fracture energy. It is nevertheless admitted that the higher the energy release rate, the rougher the fracture surface is (Kopp et al. 2014b, 2015, 2018; Fond and Schirrer 2001).

Rubber toughened polymers (Fond and Schirrer 2001, 1997; Kopp et al. 2014b) and semi-crystalline

(Kopp et al. 2018) are widely used for industrial applications. Their ductility is useful for absorbing energy induced by external impact. Nevertheless, under certain conditions (loading, temperature, hygrometry, etc.) they can present the critical appearance of rapid crack propagation. Quasi-static or fatigue-type loading (Raphael et al. 2019) generally induces plasticity and cavitation phenomena (Rolland et al. 2018; Castagnet et al. 2000b). On the contrary of a dynamic solicitation which induces brittle fractures with the appearance of micro cracks, micro- and macro-branches (Kolvin et al. 2017; Fineberg et al. 1991). For semicrystalline polymeric materials, spherulites composed mainly of crystalline phase are heterogeneities with rather brittle behaviour (Schultz 1984; Cotterell et al. 2007; Yu et al. 1998). The amorphous phase is quite soft and ductile. Under quasi-static loading it is assumed that the amorphous phase deforms plastically and therefore the material has a high ductility. Semicrystalline are rather resistant to crack initiation and are therefore suitable for industrial applications subject to external impacts such as the transport of a fluid in polymer pipes (Mason and Chen 2006; Greenshields et al. 2000; Williams and Venizelos 1999; Kopp et al. 2014a, 2018).

In this work, dynamic fracture tests were performed on strip band specimens (SBS) of a bio-based semicrystalline polymer. The material under investigation is relatively undescribed in the literature in terms of the fracture mechanism and especially in dynamic. More generally, the link between the specific microstructure of semi-crystalline polymers and cracking mechanisms at micro-scale is poorly referenced. The fracture surface were analyzed by optical and electron microscopy in different zones (initiation—propagation—arrest) in order to propose cracking scenarios related to the microstructure of semicrystalline polymer. The link between the mechanisms observed at different scales with the local and global cracking velocity and the fracture energy is discussed.

## 2 Material and methods

### 2.1 Material

The material studied is polyamide 11 (PA11), the Rilsan BESNO TL grade supplied by Arkema. The monomer is a castor oil derivative. It is therefore considered as a semi-crystalline bio-based polymer. The degree of

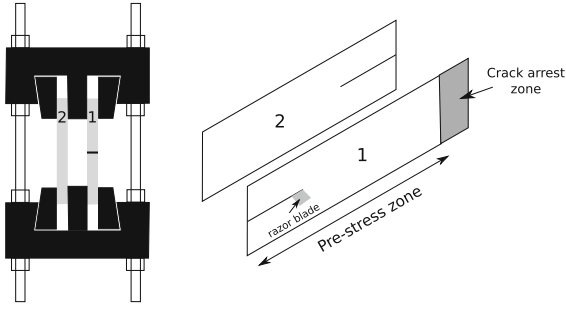
crystallinity of the polymer is 22%. It was measured by differential scanning calorimetry. The strip band specimens were machined from pre-injected plates. The dynamic modulus  $E_d$  was obtained by measuring the average ultrasonic velocity in the material  $< v_u >$  which is equal to  $2100 \pm 46 \text{ m s}^{-1}$ . As a dynamic modulus, it can be also taken as the ‘relaxed’ modulus of the material which avoid viscous effect in the estimation of the internal energy (see Eq. (2)). The value  $E_d = 1620 \pm 82 \text{ MPa}$  is obtained from Eq. (1), where  $\nu = 0.43$  and  $\rho = 1040 \text{ kg m}^{-3}$ . For the estimation of the fracture energy in dynamic propagation regime, only  $E_d$  and  $\nu$  will be considered to describe the behaviour of the material (Bradley et al. 1997).

$$E_d = \rho v_u^2 \frac{(1 + \nu)(1 - 2\nu)}{1 - \nu} \quad (1)$$

### 2.2 Dynamic fracture test

The strip band specimen (SBS) geometry (Nilsson 1972; Fond and Schirrer 2001) is used to study rapid crack propagation (RCP) and crack arrest in PA11 plates. This geometry allows precise control of the boundary conditions during propagation. It generates very few inertia effects induced by rapid crack propagation. An experimental device based on these studies (Fond and Schirrer 2001; Kopp et al. 2014b, 2015) has been designed.

Two notched head-to-tail plates are prestressed (see Fig. 1). One plate is cracked (the plate 1). The second one ensures the symmetry of the load during propagation. The specimens are initially uniaxially prestressed to a constant deformation using a universal tensile-compression machine. The loading is imposed by moving the crosshead. Once the prestress is reached, the displacement is maintained. The system is then locked by means of nuts mounted on 4 threaded rods. The rods pass through the jaws. The nuts stop the jaws to block the movement in the axis of the rods. The flexibility of the system is then limited. The stop of the crack is generated on the plate 1. This plate is deliberately longer than the jaw such that an unloaded zone exists. The energy release rate is almost nil and therefore very significantly lower than the fracture energy of the material. The crack is stopping at this zone and to access this arrest zone, the plate was cut with a band saw.

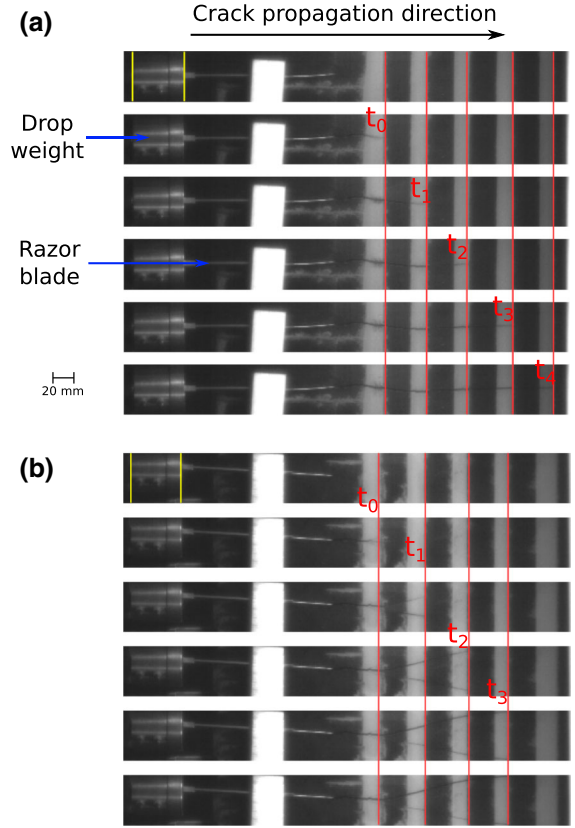


**Fig. 1** Strip band specimen loading system

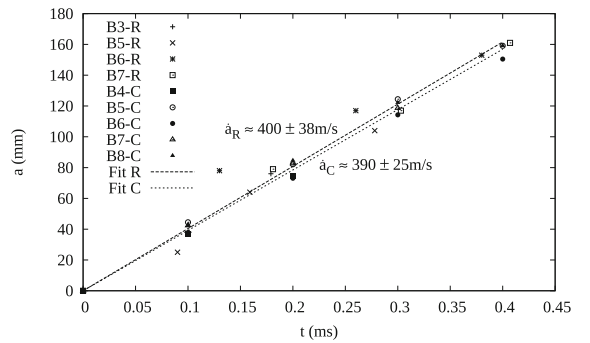
To neglect viscous effect of the material, a relaxation time of the specimen (about 15 times the pre-load time of the specimen) is considered before crack initiation. Crack initiation is then generated by the impact of a mass on a razor blade in contact with the tip of the crack. The test is carried out at ambient temperature. Six polyamide plates were cracked. The dimension of the plates is:  $L = 300$  mm (length),  $H = 80$  mm (height),  $b = 4$  mm (thickness) and  $l_n = 120$  mm (notch length). The quasi-static energy release rate in mode I, noted  $G_{I0}$ , is defined as a function of the stress  $\sigma_{zz}$  ( $z$  is the direction of transverse crack propagation) by considering a plane stress state and the propagation of a single longitudinal crack (see Eq. 2).

$$G_{I0} = \frac{H\sigma_{zz}^2(1 - \nu^2)}{2E} \quad (2)$$

A dynamic correction must be considered to estimate the energy release rate in dynamic regime, noted  $G_{ID}$ . The average crack velocity is required. A fast camera or a conductive coating (Cotterell 1968; Kopp et al. 2014b) can be used to access the spatio-temporal data of the crack tip during propagation. The latest generation of cameras have a completely satisfactory spatial and temporal resolution. The average velocity of the crack tip for this polymer is approximately  $400 \text{ ms}^{-1} \approx 0.6c_R$ . This value was obtained by optical method and resistivity measurement (see Fig. 3). The conductive layer is sprayed on one side of the sample prior to the experiment. The evolution of the resistance of the  $R_s$  layer is recorded during the propagation of the fracture. An approximately constant current  $i$  is imposed with a generator  $G$  and a  $10 \text{ M}\Omega$  resistor in



**Fig. 2** Fast camera images obtained with a sampling rate of  $10^4$  frames per second to visualize the rapid propagation of cracks in a PA11 strip specimen. The time  $t_0$  is chosen as the reference point where the crack starts to propagate in dynamic regime. The time between two images is  $10^{-4}$  s. There is a longitudinal crack without macro branches a-(sample B3) and a main crack macro branch b-(sample B9)



**Fig. 3** The position of the crack tip as a function of time is plotted and modeled by a linear regression  $f(x) = \dot{a}x$ .  $\dot{a}_R = 400 \pm 38 \text{ m s}^{-1}$  and  $\dot{a}_C = 390 \pm 25 \text{ m s}^{-1}$  with  $\dot{a}_R$  and  $\dot{a}_C$  derived from resistivity and fast camera measurements, respectively



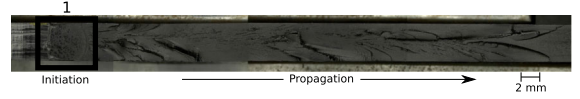
series with the sample which has a significantly lower resistance:  $R_S < 45 \text{ k}\Omega$  [see in (Kopp et al. 2014b)]. A National Instruments USB-6351 data acquisition is used to measure the potential difference  $u$  at a sampling rate of  $1.25 \text{ MS s}^{-1}$  during fracture propagation. The resistance of the conductive layer is then calculated using Ohm's law  $R_S = \frac{u}{i}$ . After calibration, the velocity of the crack tip at the sample scale (macroscopic velocity) is known at  $\pm 38 \text{ m/s}$ .

The Rayleigh wave velocity ( $c_R$ ) in PA11 is about  $698 \text{ ms}^{-1}$  (Kopp et al. 2018). It is known that the dynamic correction classically used for fast propagation which gives the factor  $k = 1 - \frac{\dot{a}}{c_R}$ , is unsatisfactory in the case of a *SBS* (Broberg 1960) test. A numerical model adapted to this specimen geometry has been implemented in (Kopp et al. 2014b) which gives a small dynamic correction of 10% which must be considered at  $0.6c_R$ . In other words, 10% of the energy is dissipated by the structure as inertia effects when the crack propagates at 60% of the Rayleigh wave velocity in the material in the case of *SBS* geometry.

Two cracking configurations are shown in Fig. 2: a single crack propagation perpendicular to the loading axis (see Fig. 2a) and a main crack propagation that branches into two secondary cracks (see Fig. 2b). In dynamic regime and for this type of multiphase materials with strong heterogeneities, the energy is mainly dissipated by surface creation. An increase in the energy release rate thus induces *in fine* macroscopic crack branching. The energy release rate can only be estimated when a longitudinal crack propagates. In this work, only specimens with a longitudinal crack were analysed.

### 2.3 Fracture surface analysis

An optical microscope and a scanning electron microscope (SEM) are used to observe the fracture surfaces of the samples. Samples are taken from the cracked plates. They are embedded in acrylic resin and metallized in order to visualize them with the SEM. The apparatus used for metallization is a Cressington 108 auto. The gold layer is assumed to be of constant thickness on the surface of the sample. The optical microscope used is a Keyence VHX1000. The samples were then observed using a SEM (Zeiss EVOHD 15). An accelerated voltage of 10 keV is used with a current of 200 pA.



**Fig. 4** Observation by light microscopy of the fracture surface of sample B3. Zone 1 represents the crack initiation zone. The arrow indicates the direction of propagation

## 3 Results

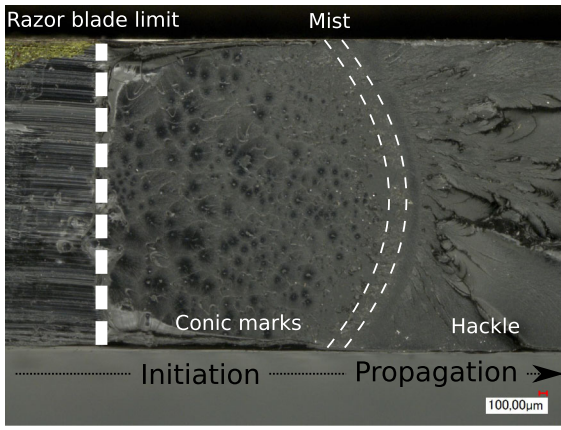
A fracture surface was reconstructed using several observations by light microscopy (see Fig. 4). A long length of cracking in sample B3 was analysed. One can observe in Table 1 some information on the tests carried out on the specimens. Different zones can be distinguished. From left to right, one can observe a zone where the razor blade has penetrated, a so-called initiation zone (zone 1) and a propagation zone. These different zones as well as a crack arrest zone were analyzed to qualitatively describe the majority of the mechanisms observed on a microscopic scale.

### 3.1 Crack initiation

The initiation zone is complex. The macro-crack will indeed grow in this zone by coalescence of several micro-cracks. The energy brought to the system allowing the crack initiation is composed of the elastic energy stored in the plate and the kinetic energy generated by the impact of the mass on the razor blade. The objective of the dynamic fracture test is to establish as quickly as possible a stable state of propagation characterised by a constant energy release rate during propagation. From the point of view of crack length, this transition zone between initiation and propagation is negligible. This is the interest of a rapid propagation (i.e. dynamic fracture) test, to be able to free oneself from the crack initiation. Nevertheless, on a microscopic scale, the fracture surface reflects this abrupt transition. Several characteristic areas can be observed in Fig. 5. From left to right, we find the zone of penetration of the blade, the zone where conical marks can be observed, an intermediate zone called “mist zone” and a chaotic zone from the point of view of roughness called “hackle zone” (Johnson and Holloway 1966; Ravi-Chandar and Knauss 1982). The area of conical markings and the hackle zone are considered to be associated with crack initiation and propagation, respectively. In the mist zone (see Fig. 6), plastic deformation of the resin is noticeable.

**Table 1** Estimation of the fracture energy  $G_{ID}$  ( $\text{kJm}^{-2}$ ), the quasi-static energy release rate  $G_{I0}$  ( $\text{kJm}^{-2}$ ) as a function of the crack velocity  $\dot{a}$  ( $\text{ms}^{-1}$ ), the temperature  $T$  ( $^{\circ}\text{C}$ ) and the displacement  $\delta$  (mm) imposed during pre-loading

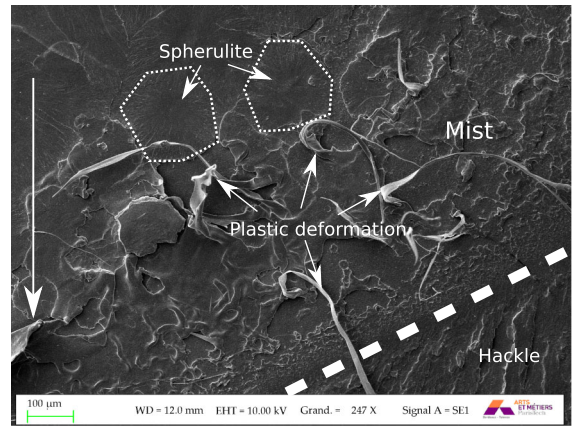
Sample	$\delta$	$T$	$\dot{a}$	$\dot{a}/c_R$	$G_{I0}$	$G_{ID}$
B3	2	19	390	0.55	10.4	9.4
B4	2	19	420	0.60	10.1	9.1
B5	2.3	20	400	0.57	12.2	11.0
B6	2.5	21	410	0.59	15.5	14.0
B7	2.5	20	380	0.54	16.2	14.6
B8	2.7	23	390	0.55	17.3	15.6
B9	2.9	21	440	0.63	NA	NA



**Fig. 5** Several zones can be identified (from left to right): the razor blade penetration zone—the conical mark zone—the intermediate “mist” zone—the chaotic “hackle” zone. The arrow indicates the direction of propagation

This suggests that the material was stressed “slowly” and at a high level of deformation.

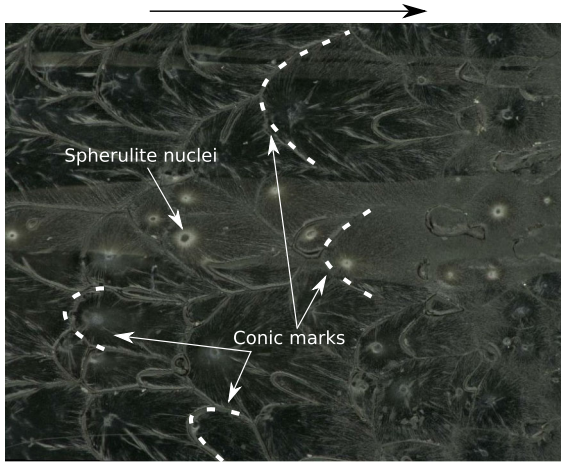
The appearance of the conical markings in the initiation zone is well documented in the literature (Kies et al. 1950; Yang and Ravi-Chandar 1996; Dalmás et al. 2013; Ravi-Chandar and Knauss 1984b). It is established that their interaction is associated with a dynamic propagation regime. Microcracks in this type of semicrystalline material appear to develop from the nuclei of the spherulites. Spherulites are heterogeneities (i.e. geometrical defects) which can be sites for microcrack initiation. They are often considered more brittle than the amorphous phase of the material. The size and density of the conical marks are also indicators of the local crack velocity (Guerra 2009). The higher the density and smaller the size of the conical mark, the faster the crack propagates. Here, it is observed an evolution in terms of density and size from



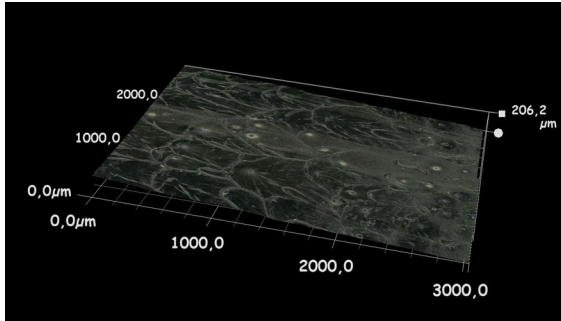
**Fig. 6** Observation by electron microscopy of the mist zone of the fracture surface of sample B4. Several zones can be identified (from top to bottom): the smooth zone with the appearance of spherulites (end of the zone of conical marks)—the mist zone with plastic deformation of the resin—a stop mark of the macro-crack in dotted line—the hackle zone. The long arrow on the left indicates the direction of propagation

left to right in the initiation zone (see Fig. 7). It suggests that the macro-crack velocity was increasing very briefly until reaching the mist zone state. The area of the conical marks is known to be smooth and sometimes mirror-like on a macroscopic scale. This is confirmed by the 3D reconstruction of the fracture surface considered smooth in this area (see Fig. 8).

The additional energy generated by the impact of a mass on a razor blade allows the transition of the crack into a rapid propagation regime where the fracture surface is more chaotic. At this instant, the energy release rate is higher than the critical energy release rate associated with crack propagation in dynamic regime ( $G_I > G_{IDc}$ ).



**Fig. 7** Observation by electron microscopy of the conical marks of the initiation zone of the fracture surface of sample B3. The nuclei of the spherulites are identifiable. The arrow indicates the direction of propagation

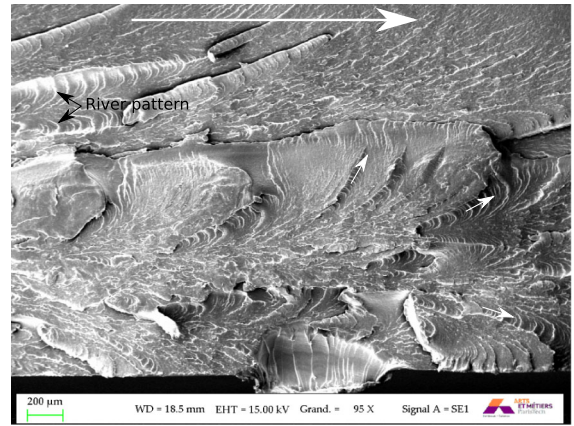


**Fig. 8** 3D reconstruction of the fracture surface of the B3 specimen in the initiation zone at the conical marks using light microscopy observations. The direction of propagation is from left to right

### 3.2 Crack propagation

The analysis of crack propagation is relatively simple from the point of view of external loading and space-time data of the crack tip. The energy release rate is assumed to be constant over almost the entire length of the crack. The crack is in a quasi-permanent regime of rapid propagation. Analysis of the fracture surface is more complex. This makes the estimation of the fracture energy hazardous.

The zone of propagation of the fracture surface of sample B5 is shown in Fig. 9. The main direction of the macrocrack front is indicated by the large white



**Fig. 9** Observation by electron microscopy of the propagation zone of the fracture surface of sample B5. The large white arrow at the top indicates the main direction of propagation of the macrocrack front. The three small white arrows indicate the propagation directions of several microcracks. Characteristic river patterns in multi-phase polymers with high heterogeneity can be observed

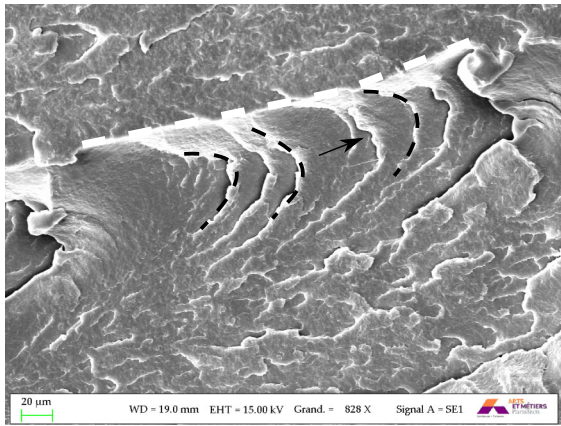
arrow at the top of the figure. The three small white arrows indicate the propagation directions of several microcracks. Characteristic river patterns in polymer resin composites can be seen in (Barbosa et al. 2019).

The description of crack propagation through a macro-front no longer seems at all relevant at this scale. Micro-cracks seem to propagate in different directions and planes. The interaction of several micro-cracks in planes at different altitudes seems to be at the origin of the river markings. Micro branches generating arrest marks are visible. This can be interpreted as a local stick slip phenomenon (see Fig. 10). This observation probably indicates that the microscopic speed of the crack is not constant as opposed to the macroscopic speed (see Fig. 3).

### 3.3 Estimation of the fracture energy

The fracture energy was estimated for 6 specimens (see Table 1). For a macroscopic velocity of the order of  $0.6c_R$ , the fracture energy is not unique and varies from 9.4 to  $15.6 \text{ kJm}^{-2}$ . This can be explained by not taking into account the amount of surface area created by the crack in the fracture energy estimate. Only the amount of projected surface area (crack length multiplied by the



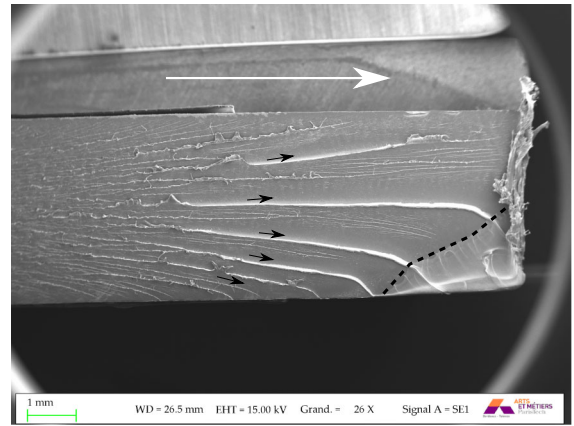


**Fig. 10** Observation by electron microscopy of the microcracks in the propagation zone of the fracture surface of sample B5. The arrow indicates the direction of propagation of the microcrack front. Several parabolic arrest marks of the micro-crack can be observed. The dashed line indicates the boundary between two crack planes at two different altitudes

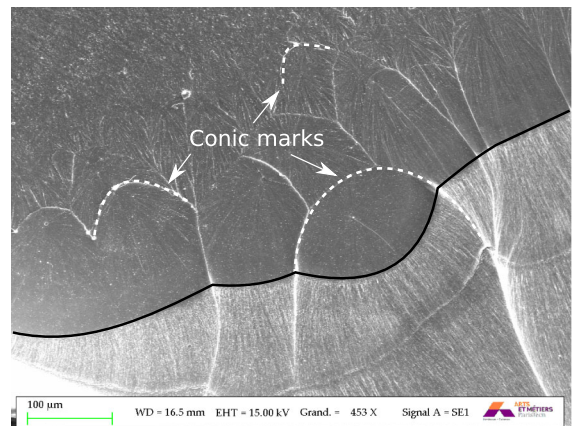
thickness of the specimen) is considered. For sample B9, the fracture energy was not estimated because the main crack has branched.

### 3.4 Crack arrest

Figure 11 shows a crack arrest. The large white arrow at the top indicates the main direction of propagation of the macrocrack front. The five small black arrows indicate the propagation directions of several micro-cracks. The dashed line indicates the area of crack arrest. To the right of the specimen, there is an area where the material has been plastically deformed due to the self-heating induced by the cutting of the specimen. The micro-cracks described in the previous section continue to propagate in different directions. However, they are less and less numerous as they approach the arrest zone. The surface is smoother than during propagation. Nevertheless, cracking planes are still present at different altitudes. Crack arrest is abrupt. The macrocrack front is no longer parabolic. Conventional rib marking known for PMMA cannot be identified. Very locally one finds conical marks (see Fig. 12) and spherulites as in the initiation zone. The energy release rate is no longer sufficient to bypass the spherulites. The crack comes to die in the heart of the spherulites without generating micro branches. The evidence of these marks suggests



**Fig. 11** Observation by electron microscopy of the arrest zone of a crack on the fracture surface of sample B7. The large white arrow at the top indicates the main direction of propagation of the macrocrack front. The five small black arrows indicate the directions of propagation of several micro-cracks. The dashed line indicates the arrest zone of the crack. To the right of the specimen is an area where the material has been plastically deformed as a result of cutting the specimen



**Fig. 12** Observation by electron microscopy of the arrest zone of a crack on the fracture surface of sample B7. Conical markings can be observed. The continuous black line indicates the arrest mark of the macro-crack

that the local velocity is decreasing and is lower than the critical speed of micro-branching.

## 4 Discussion

The initiation areas of the fracture surfaces were analyzed. They confirm three distinct zones: a zone with conical markings, an intermediate zone (mist) and a chaotic zone (hackle). During the static pre-stressing

of the sample, micro-cracks seem to develop from the nuclei of the spherulites. This (crystalline) phase of the material is assumed to be brittle. In contrast to the amorphous phase which brings ductility to the material when it is stressed relatively “slowly”. These micro-cracks coalesce and interfere with a macro-front to generate conical marks which have been observed. The appearance of these micro-cracks, often associated with cavities, is described in the literature (Selles et al. 2017; Poulet et al. 2016). The amorphous intra-spherulitic phase cavitates (or micro-crack) (Castagnet et al. 2000a). When the density of micro-cracks is critical, a macro-crack is created (Zhurkov and Kuskensko 1875; Zhurkov et al. 1972). This crack of a few mm ends up stopping in the mist zone, where plastic deformation of the matrix is found. The ductility of the amorphous phase eventually takes over the brittle (crystalline) phase of the material. This can be explained by the (quasi-static) strain rate and the degree of crystallinity (about 20%). At this moment the energy release rate is lower than the critical energy release rate allowing crack initiation ( $G_I < G_{Ic}$ ). The external impact on the razor blade will provide the energy (and instability) necessary to initiate the crack in a dynamic propagation regime. This is evidenced by the observation of a chaotic zone in the surface roughness. The local strain rate induced by the rapid crack propagation probably causes a significant drop in the ductility of the amorphous phase. The amorphous and crystalline phases are then brittle. The energy release rate is this time higher than the critical energy release rate allowing the rapid propagation of the crack ( $G_I > G_{IDc}$ ).

The difference in behaviour between crack initiation and rapid crack propagation for this type of material is considerable. Initiating a crack requires an energy release rate that is often very high compared to that which the material would require to sustain rapid crack propagation. This is due to a significant difference between the resistance to slow propagation (initiation) and rapid propagation of the material:  $G_{Ic} > G_{IDc}$ . These significant differences have been reported for other industrial materials (Fond and Schirrer 2001). In the area of rapid propagation, the propagation velocity of the macrocrack front is relatively constant ( $\dot{a} \approx 0.6c_R$ ). This critical velocity is a priori the limit at which the crack branches due to inertia effects (Yoffe 1951). The specimens studied show a longitudinal crack. Analysis of the fracture surface reveals a complex roughness. Numerous micro-cracks,

micro-branches and arrest marks are observed. They appear in different crack planes. A single macro-crack front seems to be no longer identifiable. The material seeks to dissipate a significant amount of energy ( $G_I \gg G_{IDc}$ ) by cracking mostly in the amorphous phase. Spherulites, i.e. the crystalline phase, are heterogeneities that disturb the local stress field of the micro-crack tips. This induces micro-branches and micro-cracking phenomena in different planes in large numbers. This allows the material (i.e. the individual cracks) to dissipate *in fine* a large amount of energy. One could postulate that the material dissipates as much or more energy with a single crack with many micro-cracks and micro-branches than with macro-branches. This is probably why a longitudinal macro-crack could be generated in several samples despite  $G_I \gg G_{IDc}$ .

The fact that  $G_I \gg G_{IDc}$  during fast propagation induces a maximum macroscopic speed ( $0.6c_R$ ) and a high roughness. The estimation of the fracture energy is thus complex.  $G_{ID}$  is not unique at  $0.6c_R$  (see Table 1). This estimation is made by applying the LEFM formalism. The quantity of projected surface area (the thickness times the crack length) is considered. With the observation of the fracture surface, it turns out that this consideration is erroneous. It would also appear that the local crack velocity is less than  $0.6c_R$  but probably higher than the critical micro-branching velocity. A fine estimate of the amount of surface area created by the crack improves the estimate of  $G_{ID}$  (Kopp et al. 2014b). However, it is difficult to access the amount of sub-surface area created by the micro-branches.

A relevant avenue of study would be to limit the energy release rate during rapid propagation. For a large number of industrial polymer materials, there is a significant difference between resistance to crack initiation and resistance to rapid crack propagation. It is sufficient to note the numerous studies on the influence of the strain rate on the behaviour of the material. For many semi-crystalline materials, an increase in the strain rate leads to a drop in ductility. For these materials, the study of cracking mechanisms is complex. They must be dissociated: initiation-propagation-arrest. When the energy release rate is limited (in the crack arrest zones), the surfaces observed on a macroscopic scale are smooth and the cracking speeds seem to vary (conical marks). A suitable fracture test setup is suggested. Two minimum loading levels would be required along the crack length. One level where the energy release rate is higher than the crack initi-

ation resistance ( $G_I > G_{Ic}$ ). Another loading level where the energy release rate is close to the minimum fracture energy allowing dynamic material fracture ( $G_I \approx G_{IDc}$ ). This would make it possible to limit the micro-branching mechanisms which generate complex roughnesses difficult to measure and to apprehend by the formalism of the LEFM. With a variable zone loading in terms of energy release rate, materials with antagonistic fracture behaviour (ductile-fragile) that depend significantly on the strain rate could be rigorously studied. The surfaces created by the crack would be smooth. The velocity of the macro-crack would vary. The micro-cracking and macro-cracking mechanisms would be limited. It would therefore be possible to give a fine analysis of the fracture behaviour (initiation-propagation-arrest) for many materials as is the case for one of the most studied brittle materials, PMMA.

## 5 Conclusions

The work described in this article focuses on the qualitative analysis of fracture surface. The cracks were generated by a dynamic fracture test. Strip band specimens known to generate very few inertia effects were used. The material studied is a semi-crystalline industrial biobased polymer: PA11. Its complex fracture behaviour ultimately resembles that of a large number of polymers used in industry. There is a significant difference in fracture behaviour between initiation and rapid propagation. This was evidenced by the analysis of the fracture surfaces. The mechanisms observed in the initiation and propagation zones are relatively well known. The influence of the highly heterogeneous microstructure of a semi-crystalline and the cracking regime induces a signature different from those described for the well-known homalite 100 and PMMA. The random organization of spherulites in the material confers relatively singular small-scale fracture mechanisms. The estimation of relevant material parameters is therefore complicated. Nevertheless, these parameters are indispensable in the development of predictive behaviour models used to dimension structures with respect to cracking mechanisms. A new set-up is suggested as a perspective to this work to further study the resistance to rapid crack propagation of this kind of material.

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## Compliance with ethical standards

**Conflicts of interest** The authors declare that there are no conflicts of interest regarding the publication of this paper.

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