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ORTHOTROPIC STRAIN RATE POTENTIALS USING MULTIPLE LINEAR TRANSFORMATIONS

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ABSTRACT

This paper reviews a class of anisotropic plastic strain-rate potentials, based on linear transformations of the plastic strain-rate tensor. A new formulation is proposed, which includes former models as particular cases and allows for an arbitrary number of linear transformations, involving an increasing number of anisotropy parameters. The formulation is convex and fully three-dimensional, thus being suitable for computer implementation in finite element codes. The parameter identification procedure uses a micromechanical model to generate evenly distributed reference points in the full space of possible loading modes. Material parameters are determined for several anisotropic, fcc and bcc sheet metals, and the gain in accuracy of the new models is demonstrated. For the considered materials, increasing the number of linear transformations leads to a systematic improvement of the accuracy, up to a number of five linear transformations. The proposed model fits very closely the predictions of the micromechanical model in the whole space of plastic strain-rate directions. The r -values, which are not directly used in the identification procedure, served for the validation of the models and to demonstrate their improved accuracy.

KEYWORDS: Anisotropy, Strain rate potentials, Linear transformations, Plasticity, Sheet metal forming.

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1. Introduction

Numerical simulation has become an invaluable tool in sheet metal forming applications and several commercial computer codes are available for this purpose. The accuracy of the simulations directly depends on the ability of the simulation codes to describe the plastic behavior of the material during forming. The description of the initial anisotropy is one of the key factors in improving the reliability of the finite element simulations of forming processes. This is particularly true when final part properties like springback or forming limits are to be predicted.

The plastic anisotropy of sheet metals can be assessed by means of micromechanical calculations, considering the material as a collection of grains of different orientations, subject to a given loading path and obeying the Schmid law. Nevertheless, the large computing times associated with this method have prevented its wide utilization in an industrial environment. Alternatively, continuum mechanics provide a general theoretical framework for the so-called phenomenological description of plastic anisotropy. This approach is classically based on the use of yield functions $\phi(\boldsymbol{\sigma})$ and associated flow rules (1) for the computation of stresses and strain rates:

$$\dot{\boldsymbol{\varepsilon}} = \dot{\lambda} \frac{\partial \phi}{\partial \boldsymbol{\sigma}'} \quad (1)$$

where $\boldsymbol{\sigma}'$ designates the deviatoric part of the stress tensor $\boldsymbol{\sigma}$, $\dot{\boldsymbol{\varepsilon}}$ is the plastic strain rate tensor while $\dot{\lambda}$ is the plastic multiplier. However, a potential can be defined either as a function of stresses (yield criterion) or as a function of strain rates (strain-rate potential). (Ziegler, 1977) and (Hill, 1987) have shown that, based on the plastic work equivalence principle, a meaningful strain rate potential can be associated with any convex stress potential (or yield surface). The yield criteria act as potential functions for the determination of the plastic strain rate using the flow rule. Equivalently, plastic potentials $\psi(\dot{\boldsymbol{\varepsilon}})$ are defined in the space of plastic strain-rates and their gradient (2) defines the deviatoric stress (only associated flow rules are considered in the current work, although the theory on hand is not restricted to this particular case):

$$\boldsymbol{\sigma}' = \tau \frac{\partial \psi}{\partial \dot{\boldsymbol{\varepsilon}}} \quad (2)$$

where τ is a reference stress (e.g., the yield stress in uniaxial tension along a chosen direction). Formally, the two approaches are identical. For some applications (rigid-plastic FEM simulations (Yoon *et al.*, 1995; Chung *et al.*, 1996; Lee *et al.*, 1997; Ryou *et al.*, 2005), minimum plastic-work path calculations (Chung and Richmond, 1992a; b; 1994; Chung *et al.*, 2000), analytical calculations of simple forming processes etc.) the strain-rate potential approach can be computationally more suitable. Several fourth order and sixth order strain-rate potentials have been proposed as an adjustment of crystallographic texture functions (Van Houtte *et al.*, 1989; Arminjon and Bacroix, 1991; Arminjon *et al.*, 1994; Savoie and MacEwen, 1996; Van Bael and Van Houtte, 2003; Van Houtte *et al.*, 2008). Virtually any

mathematical function used to define a yield criterion can be transformed in order to describe a plastic potential in the plastic strain-rate space (Barlat and Chung, 1993; Zhou and Wagoner, 1994).

A useful method to generate both yield criteria and strain-rate potentials is based on the linear transformation of the stress tensor or the plastic strain-rate tensor, respectively. Yield functions using the linear transformation of the stress tensor were proposed in the early 90s by (Barlat *et al.*, 1991) and (Karafillis and Boyce, 1993). In an attempt to increase the number of parameters, two independent linear transformations have been used in the formulation of the plane stress potential Yld2000-2d (Barlat *et al.*, 2000; Barlat *et al.*, 2003). Full 3D yield functions employing two linear transformations have been proposed by (Barlat *et al.*, 2005) and (Bron and Besson, 2004) – the later also proposed a generic form of yield function as a sum of several functions.

In parallel, the strain rate potential Srp93 (Barlat and Chung, 1993; Barlat *et al.*, 1993), which is the pseudo-conjugate of the Yld91 stress potential (Barlat *et al.*, 1991), was developed using a linear transformation of the plastic strain rate tensor. The strain rate potential Srp2003-2d, which is the pseudo-conjugate of the Yld2000-2d stress potential (Barlat *et al.*, 2003), was proposed by (Kim *et al.*, 2003a) subsequently. Recently, (Barlat and Chung, 2005; Kim *et al.*, 2007) proposed the two-transformation strain-rate potentials Srp2004-18p and Srp2006-18p, inspired from the expression of the yield criterion Yld2004-18p (Barlat *et al.*, 2005).

The increased flexibility of these potentials allowed both the uniaxial yield stresses and the corresponding r-values to be taken into account simultaneously for parameter identification. The later versions describe accurately such uniaxial tensile test results performed every 15°. Finite element simulation of springback as well as forming limit predictions have been performed by (Kim *et al.*, 2003b; Chung *et al.*, 2005) with Yld2000-2d and by (Li *et al.*, 2003) and (Hiwatashi *et al.*, 1998) with the sixth order potential developed by (Van Houtte *et al.*, 1989) with very good results. Also, the number, position and relative height of the ears in cylindrical cup drawing are better predicted with recent yield criteria (see e.g. (Yoon *et al.*, 2006)). In particular, (Rabahallah *et al.*, 2006; Rabahallah *et al.*, 2008a) have shown that the Srp2004-18p potential predicts the initial anisotropy better than most of the existing phenomenological potentials for a very wide range of materials. This is a potentially interesting property since a unique mathematical function could be used for all the forming applications, while some former mathematical functions were known to perform better e.g. for either bcc or fcc sheet materials, but not for both (Bacroix *et al.*, 2003).

The aim of this paper is to explore more systematically the use of linear transformations in the formulation of plastic strain-rate potentials. In section 2, a general formulation is proposed involving an arbitrary number of linear transformations. This formulation includes former plastic strain-rate potentials as particular cases. The number of parameters is increasing with the number of linear transformations; their identification is tackled in section 3 for a number of sheet metals – both bcc and fcc. Section 4 shows the ability of the different models to accurately predict the yield surface, the curves of plastic potential iso-values as well as the r-values for the selected materials. The mathematical details for the complete calculation of the plastic potential and its derivatives are given in appendix.

2. Formulation of the proposed model

As mentioned in the introduction, linear transformation of the stress tensor $\boldsymbol{\sigma}$ by means of an anisotropic operator \mathbf{B} provides a straightforward way to generalize isotropic yield functions to anisotropy (Barlat *et al.*, 1991; Karafillis and Boyce, 1993; Barlat *et al.*, 2005). The same technique can be applied to the plastic strain-rate tensor $\dot{\boldsymbol{\epsilon}}$ in order to generalize isotropic expressions of plastic potentials. The following linear transformation has been used by (Barlat and Chung, 2005; Kim *et al.*, 2007), which enforces the deviatoric character of the plastic strain-rate tensor in a convenient way:

$$\tilde{\dot{\boldsymbol{\epsilon}}} = \mathbf{B} \cdot \mathbf{T} \cdot \dot{\boldsymbol{\epsilon}} \quad (3)$$

In Eq. (3), \mathbf{T} designates the unit tensor in the space of fourth order symmetric deviatoric tensors while the fourth order array \mathbf{B} contains anisotropy coefficients. For the case of orthotropic symmetry, these tensors can be represented as the following 6×6 arrays:

$$\mathbf{B} = \begin{bmatrix} 0 & -b_{12} & -b_{13} & 0 & 0 & 0 \\ -b_{21} & 0 & -b_{23} & 0 & 0 & 0 \\ -b_{31} & -b_{32} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & b_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & b_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & b_{66} \end{bmatrix}; \quad \mathbf{T} = \begin{bmatrix} 2/3 & -1/3 & -1/3 & 0 & 0 & 0 \\ -1/3 & 2/3 & -1/3 & 0 & 0 & 0 \\ -1/3 & -1/3 & 2/3 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad (4)$$

In order to use these compact notations, the $\dot{\boldsymbol{\epsilon}}$ -like tensors are written here as 6-component vectors; e.g., $\dot{\boldsymbol{\epsilon}} = [\dot{\epsilon}_{xx} \quad \dot{\epsilon}_{yy} \quad \dot{\epsilon}_{zz} \quad \dot{\epsilon}_{yz} \quad \dot{\epsilon}_{zx} \quad \dot{\epsilon}_{xy}]^T$, with components in the frame of material symmetry.

The following scalar functions are used in defining the strain-rate potentials Srp93, Srp2004-18p and Srp2006-18p:

$$\begin{aligned} \varphi_1(\mathbf{B}, \dot{\boldsymbol{\epsilon}}) &= |\tilde{E}_1|^b + |\tilde{E}_2|^b + |\tilde{E}_3|^b \\ \varphi_2(\mathbf{B}, \dot{\boldsymbol{\epsilon}}) &= |\tilde{E}_2 + \tilde{E}_3|^b + |\tilde{E}_3 + \tilde{E}_1|^b + |\tilde{E}_1 + \tilde{E}_2|^b \end{aligned} \quad (5)$$

where \tilde{E}_i are the principal values of tensor $\tilde{\dot{\boldsymbol{\epsilon}}}$ defined by the linear transformation of Eq. (3). The notations in Eq. (5) allow rewriting the existing members of the Srp-family of strain-rate potentials in the following compact forms:

$$\begin{aligned}
\text{(a) Srp93:} \quad \psi(\dot{\mathbf{\epsilon}}) &= \left\{ \frac{1}{2^{1-b} + 1} \varphi_1(\mathbf{B}, \dot{\mathbf{\epsilon}}) \right\}^{\frac{1}{b}} = \dot{\bar{\epsilon}} \\
\text{(b) Srp2004-18p:} \quad \psi(\dot{\mathbf{\epsilon}}) &= \left\{ \frac{1}{2^{2-b} + 2} \left[\varphi_1(\mathbf{B}^1, \dot{\mathbf{\epsilon}}) + \varphi_2(\mathbf{B}^2, \dot{\mathbf{\epsilon}}) \right] \right\}^{\frac{1}{b}} = \dot{\bar{\epsilon}} \\
\text{(c) Srp2006-18p:} \quad \psi(\dot{\mathbf{\epsilon}}) &= \left\{ \frac{1}{2^{2-b} + 2} \left[\varphi_1(\mathbf{B}^1, \dot{\mathbf{\epsilon}}) + \varphi_1(\mathbf{B}^2, \dot{\mathbf{\epsilon}}) \right] \right\}^{\frac{1}{b}} = \dot{\bar{\epsilon}}
\end{aligned} \tag{6}$$

where $\dot{\bar{\epsilon}}$ is the effective plastic strain rate, which is the conjugate of the effective stress $\bar{\sigma}$ under the plastic work rate equivalence principle.

Eqs. (6)b and (6)c represent two different extensions of Eq. (6)a, each of them using two linear transformations. The Srp2006-18p expression uses function φ_1 twice, which may rise uniqueness problems during parameter identification. In (Kim *et al.*, 2007), Srp2004-18p and Srp2006-18p have shown almost identical predictions and convergence behavior. Therefore, any of them could be used to further increase the number of linear transformations in the plastic potential expressions. In this perspective, Srp2006-18p has the advantage of a unique definition for odd number of transformations and to yield the most compact formula for a multiple transformation potential.

In this work, the following generalization is proposed, using multiple linear transformations of the plastic strain-rate tensor:

$$\psi(\dot{\mathbf{\epsilon}}) = \left\{ \frac{1}{N} \frac{1}{2^{1-b} + 1} \sum_{k=1}^N \varphi_1(\mathbf{B}^k, \dot{\mathbf{\epsilon}}) \right\}^{\frac{1}{b}} = \dot{\bar{\epsilon}} \tag{7}$$

The expressions of Srp93¹ and Srp2006-18p are particular cases of the function proposed above, for $N=1$ and $N=2$. Larger N -values lead to new expressions, involving an increased mathematical flexibility – associated with an increased number of parameters. All these expressions can be designated as Srp2007- $N \times 9$ p potentials.

The strain rate potentials ψ are proven to be convex (Rockafellar, 1970) in the space of the principal transformed strain rates \tilde{E}_i (note the sum of two or more convex functions is also a convex function) and it is easy to show that they are also convex with respect to the plastic strain rate tensor (Kim *et al.*, 2007). Thus, the series of potentiels generated with Eq. (7) are convex functions.

3. Parameter identification

¹ The original expression of Srp93 (Barlat and Chung, 1993) is slightly different since a simpler anisotropy matrix has been used at that time (involving seven parameters, instead of nine). However, the current equation can be considered as the final version of Srp93.

Successful parameter identification is a key problem for the advanced potentials involving an increasing number of parameters. Moreover, the need for specific experimental measures that often differ from one model to another makes it almost impossible to consistently compare the predictions of different models.

It has been recently shown by (Plunkett *et al.*, 2008) that the identification of yield functions based on multiple linear transformations can be performed using experimental data obtained by mechanical tests. However, a more consistent approach for model comparison is provided by the texture-based identification introduced in the early 90s by (Van Houtte *et al.*, 1989; Arminjon and Bacroix, 1991). In this case, a very large number of reference points is generated by means of a micromechanical model. These points are evenly distributed in the space of plastic strain-rate directions. For this purpose, the plastic strain-rate directions $\mathbf{N} = \dot{\boldsymbol{\epsilon}}/|\dot{\boldsymbol{\epsilon}}|$ are represented by five-component unit vectors (Lequeu *et al.*, 1987), as described in appendix. Such unit vectors can be described in the 5D space by four angles $\theta_1, \theta_2, \theta_3$ and θ_4 (Gilormini *et al.*, 1988):

$$\begin{aligned} N_1 &= \cos \theta_1 \sin \theta_2 \sin \theta_3 \sin \theta_4 \\ N_2 &= \sin \theta_1 \sin \theta_2 \sin \theta_3 \sin \theta_4 \\ N_3 &= \cos \theta_2 \sin \theta_3 \sin \theta_4 \\ N_4 &= \cos \theta_3 \sin \theta_4 \\ N_5 &= \cos \theta_4 \end{aligned} \tag{8}$$

where $0 \leq \theta_1 \leq 2\pi$ and $0 \leq \theta_i \leq \pi$, for i between 2 and 4. Consequently, the element of area on the unit hypersphere defined in this way equals

$d\theta_1 d \cos \theta_2 d(\theta_3/2 - \sin 2\theta_3/4) d[(2 + \sin^2 \theta_4) \cos \theta_4/3]$. The orthotropic symmetry of the texture of rolled materials allows for a reduction of the range of each of the four angles as follows (Arminjon and Bacroix, 1991): $0 \leq \theta_1 \leq 2\pi$; $-1 \leq \cos \theta_2 \leq 1$; $0 \leq \theta_3/2 - \sin 2\theta_3/4 \leq \pi/4$; $0 \leq (2 + \sin^2 \theta_4) \cos \theta_4/3 \leq 2/3$. These variation ranges are swept with regular intervals, yielding a discretisation of $40 \times 20 \times 10 \times 10$ points, which correspond to unit vectors in the space of plastic strain-rates. Consequently, the number of reference points for the identification (80,000) is much larger than the number of parameters of the models. Moreover, this approach allows one to investigate the models' ability to describe the through-thickness anisotropy of the materials. Indeed, this type of anisotropic response is difficult (and most often impossible) to address by means of experimental testing. While most sheet metals are strained in the plane of the sheet during forming, several applications (e.g. multi-pass forming, thick sheet forming, hemming etc.) may involve non-negligible through-thickness shear strains.

A rigid-plastic, "full-constraints" Taylor model (Bishop and Hill, 1951) is used to generate the reference values used for the identification procedure. The families of slip systems considered are $\{111\}\langle 110 \rangle$ for fcc metals and $\{110\}\langle 111 \rangle$, $\{112\}\langle 111 \rangle$ for bcc metals. The same critical resolved shear stress was considered on all slip systems; its value is not relevant for the current analysis since the calculated stresses are normalized by the resolved shear stress throughout. Hardening modeling is also not required, nor texture evolution, since only the initial yielding point is calculated. It is noteworthy that any other micromechanical model

can be used to generate these reference yielding points for the parameter identification. Given a unit plastic strain rate tensor \mathbf{N} , the corresponding average plastic work rate $\dot{W}_{Taylor}^P(\mathbf{N})$ and the normalized expression $\Pi_{Taylor}^P(\mathbf{N}) = \frac{\boldsymbol{\sigma}'}{\tau_c} : \mathbf{N}$ can be computed, where τ_c is the critical shear stress associated with the Schmid law on the crystallographic slip systems. The same quantities can be calculated by using the plastic potential. Since the different potentials used in this work are described by homogeneous function of degree one, Eq. (7) can be rewritten in terms of \mathbf{N} , as

$$\psi(\mathbf{N}) = \frac{\dot{W}^P(\mathbf{N})}{\tau} \quad (9)$$

where τ is the reference stress for the plastic potentials. In other words, for any strain rate direction \mathbf{N}_i , the previously defined two functions $\Pi_{Taylor}^P(\mathbf{N}_i)$ and $\psi(\mathbf{N}_i)$ correspond to the plastic work rate associated with a unit-norm strain rate tensor and normalized by the reference stress. The coefficients of the plastic potential ψ can then be identified by minimizing the following objective function:

$$F(\text{material parameters}) = \frac{\sum_{i=1}^{80000} [\Pi_{Taylor}^P(\mathbf{N}_i) - \psi(\mathbf{N}_i)]^2}{\sum_{i=1}^{80000} [\Pi_{Taylor}^P(\mathbf{N}_i)]^2} \quad (10)$$

with respect to the parameters of the chosen potential. The sum is performed over the 80,000 predefined strain rate directions discussed earlier. The values $\Pi_{Taylor}^P(\mathbf{N}_i)$ are computed for all these directions. This is a lengthy task, but it has to be performed only once for each material. In the recent papers (Rabahallah *et al.*, 2008a; Van Houtte *et al.*, 2008), such procedures have been used for the parameter identification of various plastic strain-rate potentials and are described in detail.

4. Application to steel and aluminum alloy sheet metals

4.1 Materials and material parameters

The experimental textures of a set of six polycrystalline materials have been used for the current investigation: three aluminum alloy sheets and three steel sheets. The three aluminum alloy sheets are an aluminum-magnesium-silicium alloy AA6016, an aluminum-magnesium aluminum alloy AA5182 and an AA6022 alloy. The steel sheets are an interstitial free mild steel DC06, a high strength Dual phase steel DP600 and a high strength low-alloyed steel HSLA340. All these materials are widely used in the automotive industry and have been thoroughly investigated in (3DS, 2001; Haddadi *et al.*, 2006). The microstructure of the steel sheets has been investigated in (Nesterova *et al.*, 2001; Gardey *et al.*, 2005a; Gardey *et al.*, 2005b).

Figure 1 shows the yield surfaces and the in-plane variation of Hill's anisotropy coefficient $r = \dot{\epsilon}_2 / \dot{\epsilon}_1$ for the six materials under investigation, as predicted by the crystal plasticity model. The two high strength steels DP600 and HSLA are almost isotropic and their yield surfaces are very close to each other. The three aluminum alloy sheets exhibit r-values smaller than one, with a strong variation for AA6022. In contrast, the mild steel exhibits an average r-value of two, with an in-plane variation close to unity. The experimental r-values for all these materials as well as the predictions of several existing plastic potentials are available in (Rabahallah *et al.*, 2008a).

The values of the material parameters identified for these materials and for the Srp2007 model for up to six transformations are given in Tables 1 to 4. In the next section, these results are analyzed in terms of yield surface plots, strain-rate potential iso-values plots, r-value plots and parameter identification objective function values.

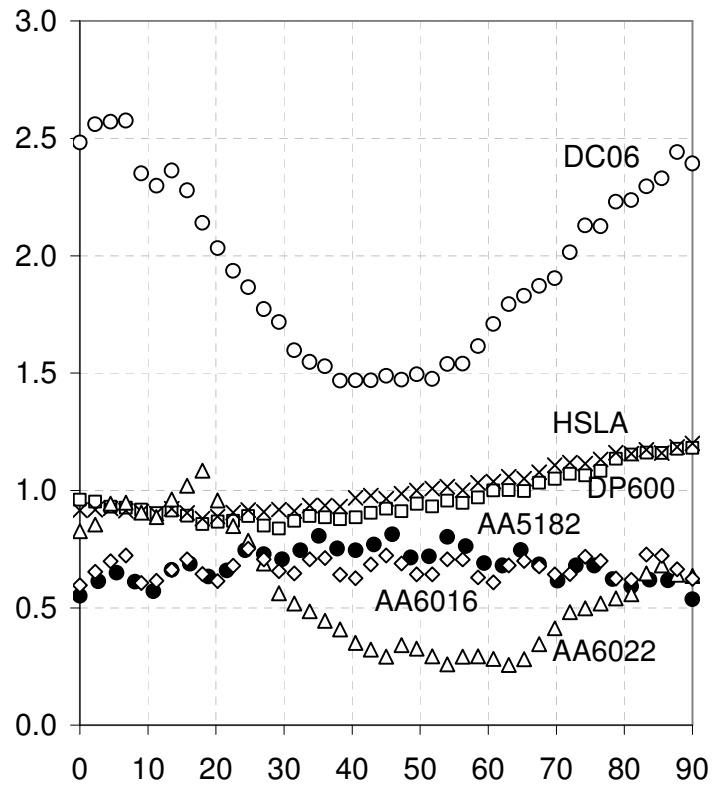
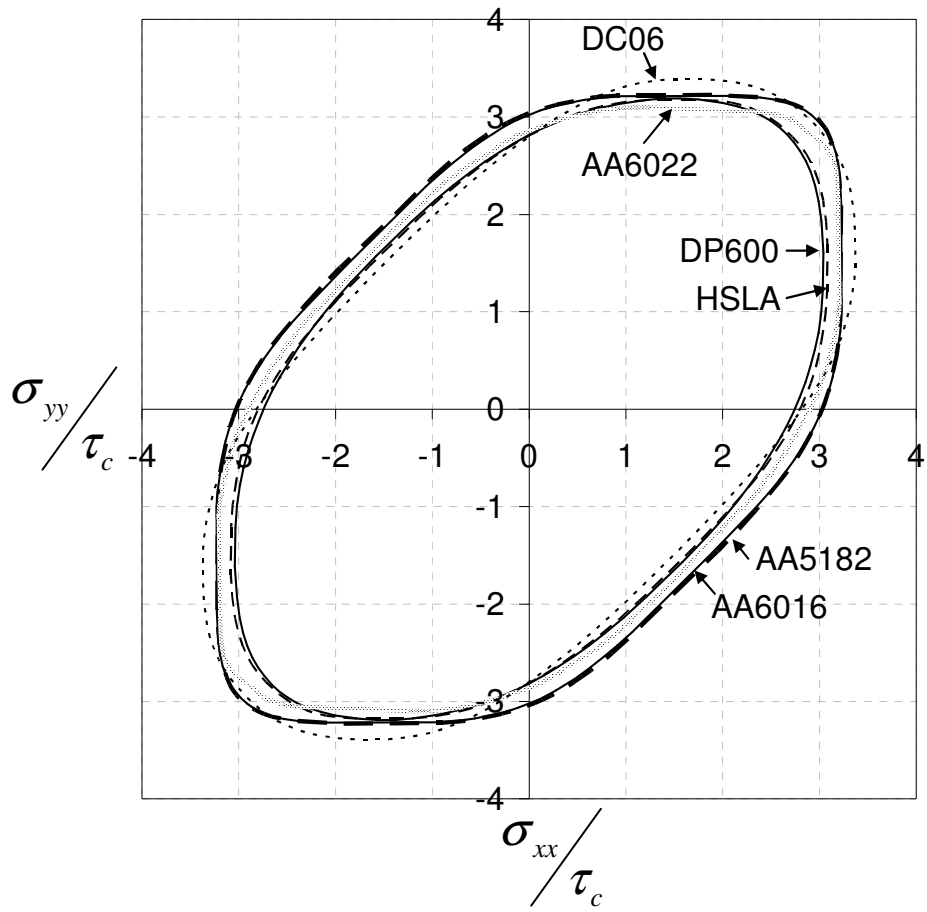


Figure 1. Yield surfaces (top) and r -values (bottom) for the six materials of the study; Taylor model predictions.

Table 1. Best fit parameters of the Srp2007-1×9p after identification, for the six materials.

<i>Parameters</i>	<i>DC06</i>	<i>DP600</i>	<i>HSLA</i>	<i>AA5182</i>	<i>AA6022</i>	<i>AA6016</i>
b_{12}	2.9323	3.0078	2.7607	3.0435	3.0101	3.0252
b_{13}	3.0857	2.9925	2.7476	2.9631	2.9905	2.9775
b_{21}	2.9494	3.0437	2.8029	3.048	2.972	3.024
b_{23}	3.1199	3.0643	2.832	2.9721	2.9143	2.9751
b_{31}	3.2562	3.0131	2.7767	2.8872	2.9328	2.9286
b_{32}	3.2733	3.049	2.8189	2.8917	2.8947	2.9274
b_{44}	0.9221	1.0064	0.9170	1.0344	1.1031	1.0369
b_{55}	0.9391	1.0330	0.9449	1.0261	1.0731	1.0345
b_{66}	1.0307	1.0260	0.9352	0.9967	1.0756	1.0038
b	1.6063	1.5517	1.5554	1.3810	1.3296	1.3183

Table 2. Best fit parameters of the Srp2007-2×9p after identification, for the six materials.

<i>Parameters</i>	<i>DC06</i>	<i>DP600</i>	<i>HSLA</i>	<i>AA5182</i>	<i>AA6022</i>	<i>AA6016</i>
b_{12}^1	0.9552	0.1341	0.6176	1.5420	0.3174	1.6189
b_{13}^1	0.9893	0.5141	0.3453	1.5109	0.0152	1.5707
b_{21}^1	1.2842	1.1634	0.0739	1.6337	0.7568	1.5482
b_{23}^1	1.2377	1.0563	0.2236	1.6230	0.2410	1.5707
b_{31}^1	1.2117	0.6356	-0.1288	1.5248	0.4022	1.5328
b_{32}^1	1.2144	0.5963	0.2200	1.5096	0.2673	1.6076
b_{44}^1	1.3448	0.7458	0.4057	1.6772	0.7076	1.5492
b_{55}^1	1.1439	-0.0087	0.4666	1.5940	0.4440	1.7014
b_{66}^1	1.3870	0.5735	0.5414	1.6138	0.1820	1.5902
b_{12}^2	0.5695	1.1936	1.2852	0.2844	1.3642	0.3379
b_{13}^2	-0.4002	1.3097	1.3884	0.2877	1.4038	0.2762
b_{21}^2	0.6464	1.2247	1.2628	0.3904	1.4569	0.0606
b_{23}^2	-0.2051	1.1146	1.3572	0.2079	1.4284	0.1440
b_{31}^2	-0.1529	1.3339	1.3789	0.3413	1.5882	0.2327
b_{32}^2	-0.7111	1.0895	1.4639	0.2916	1.5605	0.1851
b_{44}^2	-0.4046	1.1794	1.3121	-0.0985	1.4803	0.4216
b_{55}^2	-0.8189	1.5432	1.3321	0.2969	1.6225	0.1171
b_{66}^2	0.5119	1.3890	1.2562	0.2574	1.7888	0.2447
b	1.4990	1.5171	1.5000	1.2878	1.2640	1.3333

Table 3. Best fit parameters of the Srp2007-4×9p after identification, for the six materials.

<i>Parameters</i>	<i>DC06</i>	<i>DP600</i>	<i>HSLA</i>	<i>AA5182</i>	<i>AA6022</i>	<i>AA6016</i>
b_{12}^1	1.8108	-0.0246	0.0575	2.8822	0.1250	-0.5474
b_{13}^1	1.7218	0.5083	0.8940	2.9716	-0.0614	0.0567
b_{21}^1	2.5304	0.1561	0.2042	2.2853	0.3366	-0.3624
b_{23}^1	2.3858	0.1758	0.2253	2.3246	0.0481	0.2482
b_{31}^1	0.4730	0.1978	0.5288	2.5734	0.1489	-0.1041
b_{32}^1	0.3670	0.1047	0.2672	2.4389	0.2392	0.2847
b_{44}^1	1.4702	0.3467	-0.5953	2.5841	0.2781	0.6827
b_{55}^1	0.8375	-0.1652	0.2678	2.5184	0.2679	-0.2930
b_{66}^1	2.1585	0.2917	0.4415	2.5755	-0.1696	0.5253
b_{12}^2	0.9707	1.2210	0.3781	0.7458	0.1358	0.2257
b_{13}^2	0.2707	1.1828	-0.1884	0.3105	0.1455	0.0890
b_{21}^2	1.1899	1.2261	-0.1240	0.3701	0.2599	0.4527
b_{23}^2	0.2401	1.1803	0.1874	0.1619	0.2668	0.5054
b_{31}^2	0.2527	1.1463	-0.1556	-0.2877	0.2359	0.2260
b_{32}^2	-0.6716	1.1844	-0.1345	-0.5692	0.2642	0.3974
b_{44}^2	-0.2921	1.2377	-0.2256	0.4969	0.1958	-0.0590
b_{55}^2	-1.2173	1.2074	0.5855	-0.4707	0.3076	-0.6018
b_{66}^2	1.2356	1.2116	0.2920	-0.5076	0.3113	0.4211
b_{12}^3	1.4319	0.1510	0.8628	1.7521	1.2691	3.8280
b_{13}^3	1.6365	0.4542	0.0248	1.6218	1.2875	3.8766
b_{21}^3	1.2132	-0.0358	0.8599	1.7467	1.1933	3.4864
b_{23}^3	1.6117	0.0496	0.4381	1.6898	1.1885	3.4723
b_{31}^3	3.5822	0.0316	-0.0566	1.5237	1.2939	3.5170
b_{32}^3	3.6020	0.3836	-0.0407	1.7249	1.2581	3.4722
b_{44}^3	2.2095	0.1140	-0.5073	1.6036	1.3427	-3.6723
b_{55}^3	2.4475	0.3927	-0.2469	1.9552	1.3301	-3.6449
b_{66}^3	1.5099	0.1827	-0.8895	1.7598	1.3201	3.7146
b_{12}^4	-0.0747	0.2911	1.7859	-0.4852	-0.4186	0.1734
b_{13}^4	-0.2326	0.0889	1.9237	-0.0706	-0.2685	0.2691
b_{21}^4	0.4826	0.3707	1.8286	-0.2912	0.0620	0.2582
b_{23}^4	0.4394	0.1501	1.7781	-0.6406	0.1299	0.2695
b_{31}^4	0.8436	0.1100	1.9411	-0.0894	0.2348	0.0075
b_{32}^4	1.0457	-0.1701	1.7944	0.0108	0.3564	0.1440
b_{44}^4	-0.7906	0.1020	-1.8095	-0.5967	-0.5271	0.1247
b_{55}^4	-0.4953	0.3247	-2.0492	0.2945	0.3420	0.1194

b_{66}^4	0.7161	0.4254	1.8071	0.4361	0.4300	0.0854
b	1.4537	1.4444	1.4580	1.2733	1.1970	1.2884

Table 4. Best fit parameters of the Srp2007-6×9p after identification, for the six materials.

<i>Parameters</i>	<i>DC06</i>	<i>DP600</i>	<i>HSLA</i>	<i>AA5182</i>	<i>AA6022</i>	<i>AA6016</i>
b_{12}^1	-0.0204	-0.0100	0.0612	-0.5761	-0.6812	-0.3742
b_{13}^1	0.3084	0.7613	1.0441	0.1637	0.2686	0.0627
b_{21}^1	1.3190	0.3470	0.6003	-0.1132	-0.6575	-0.5552
b_{23}^1	1.2147	0.2681	0.5120	0.0555	0.1918	0.1290
b_{31}^1	-0.2862	0.2549	0.4910	0.4228	0.2115	0.1808
b_{32}^1	0.1953	0.1526	0.3995	0.2572	0.2915	0.2631
b_{44}^1	0.6615	0.5271	-0.8141	0.1322	0.4903	0.4056
b_{55}^1	0.2919	-0.2260	0.0911	0.4825	0.5243	0.2273
b_{66}^1	0.7660	0.4525	0.6220	0.3208	0.9135	0.4413
b_{12}^2	-0.1114	1.5669	-0.0889	-0.0486	-0.1880	0.0167
b_{13}^2	-1.2731	1.5727	0.0770	0.1083	-0.1866	0.0852
b_{21}^2	0.1115	1.5991	-0.0155	-0.2365	-0.0182	0.1599
b_{23}^2	1.4648	1.5862	0.3965	-0.2189	0.3353	0.1370
b_{31}^2	-0.2622	1.5302	0.0532	0.1853	0.5295	0.1723
b_{32}^2	-0.4147	1.5473	0.1364	0.1210	0.2721	0.0971
b_{44}^2	0.6427	1.6030	0.0433	0.2917	-0.3748	0.0387
b_{55}^2	0.8681	1.7066	0.4550	0.2968	0.3868	0.2784
b_{66}^2	0.4034	1.5573	0.0837	-0.3332	-0.2853	-0.1511
b_{12}^3	1.6009	0.2751	1.0168	3.0236	0.3185	0.0231
b_{13}^3	1.2314	0.8266	-0.1548	3.0533	0.3787	0.0212
b_{21}^3	1.4942	-0.2177	0.4790	3.6419	-0.3303	-0.1307
b_{23}^3	0.9018	-0.1871	0.3792	3.6506	0.6350	0.4080
b_{31}^3	-0.4587	-0.0070	0.4072	2.9730	0.1504	0.2206
b_{32}^3	-0.2489	0.8061	0.4576	2.8882	0.2497	0.1515
b_{44}^3	0.7198	0.1401	-0.5452	3.4498	0.3423	0.2243
b_{55}^3	1.0187	0.7855	0.5612	3.0239	0.6736	0.2610
b_{66}^3	1.6736	0.4546	-0.5489	3.3195	-0.7504	-0.2695
b_{12}^4	-0.0211	0.5555	2.3387	-0.3374	3.1971	3.6742
b_{13}^4	-0.5574	0.1219	2.3464	-0.2178	2.8152	3.5435
b_{21}^4	-0.0304	0.7721	2.3356	-0.4805	3.2127	3.6711
b_{23}^4	0.3771	0.2846	2.1673	-0.2169	2.7313	3.4480

b_{31}^4	0.5515	0.1519	2.3421	0.5421	2.7563	3.4962
b_{32}^4	0.4170	-0.3576	2.1801	0.0985	2.6202	3.4384
b_{44}^4	0.5728	0.2566	-2.2694	-0.4211	2.8726	3.5866
b_{55}^4	0.0963	0.6901	-2.4028	0.2874	2.9857	3.5437
b_{66}^4	0.5917	0.8071	2.3531	0.4052	3.1534	3.6237
b_{12}^5	1.7587	0.0345	0.4517	0.6316	0.3407	0.5819
b_{13}^5	1.7506	0.7790	0.9307	0.5767	-0.4496	-0.1231
b_{21}^5	1.5999	0.2817	0.2540	0.5757	0.3839	0.2740
b_{23}^5	1.6588	0.1927	0.1037	0.5036	0.4709	0.1226
b_{31}^5	1.8413	0.2452	-0.0447	0.8257	0.3340	0.3014
b_{32}^5	1.7790	0.1044	0.3951	0.9680	0.2198	0.1211
b_{44}^5	1.9096	0.5467	0.5048	0.6466	0.6754	0.5542
b_{55}^5	1.8587	-0.2277	0.7055	-0.9417	0.5226	0.2993
b_{66}^5	1.7113	0.4612	0.6013	-0.6798	0.7848	0.4293
b_{12}^6	0.2847	1.6012	-0.5906	0.4099	-0.5784	-0.0464
b_{13}^6	-0.4844	1.5164	-0.2412	0.6187	-0.7969	-0.2476
b_{21}^6	0.2817	1.6132	-0.6961	0.5359	0.6842	0.2714
b_{23}^6	-0.0092	1.5295	-0.3278	0.0597	0.7985	0.3726
b_{31}^6	-0.0525	1.5291	-0.2991	-0.1592	-0.2348	0.0113
b_{32}^6	-0.3292	1.5643	0.3036	0.0322	0.3294	0.1837
b_{44}^6	-0.3845	1.5876	-0.1323	0.2219	1.1082	0.1047
b_{55}^6	0.8323	1.5116	0.7546	0.4050	0.5963	0.4537
b_{66}^6	0.2364	1.5918	0.7783	0.3244	-0.3460	-0.2862
b	1.3547	1.4685	1.4382	1.2555	1.1530	1.2624

4.2 Analysis of results and discussion

Figure 2 displays the yield surface for the AA6022 aluminum alloy as well as the DC06 mild steel, as predicted by Srp2007-2×9p and Srp2007-4×9p. Figure 3 displays the deviatoric plane of the corresponding dual equipotential surfaces for the mild steel. One can see that Srp2007-4×9p almost perfectly fits the reference points corresponding to the micromechanical model. However, the prediction provided by Srp2007-2×9p is already very close to this reference. A more quantitative comparison can be made by considering the values of the objective-function (10) as a measure of the closeness of each model to the reference data. Figure 4 summarizes the values of the objective functions for the Srp2007 models for up to six linear transformations, for the six materials investigated.

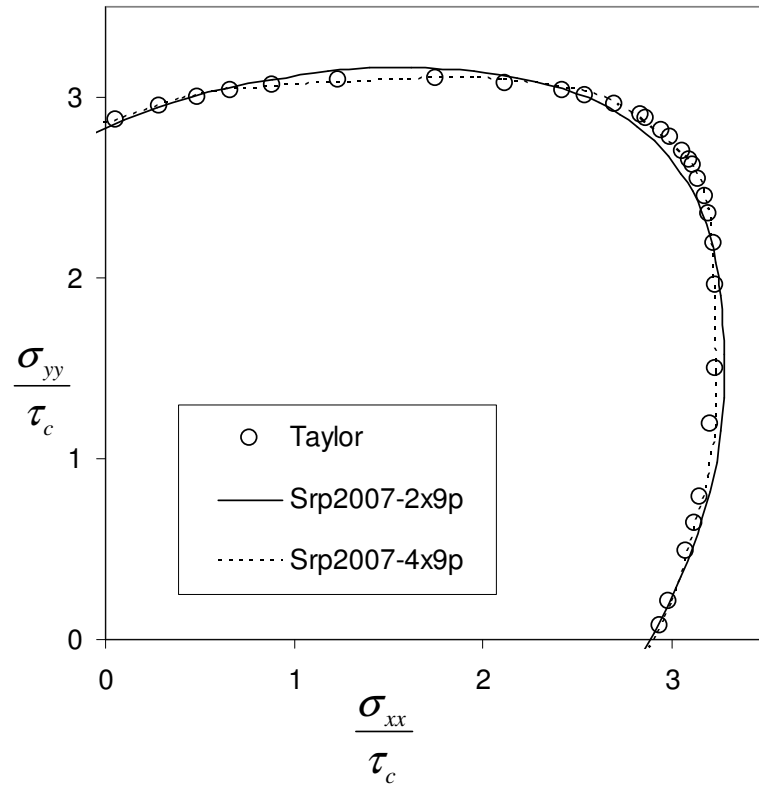
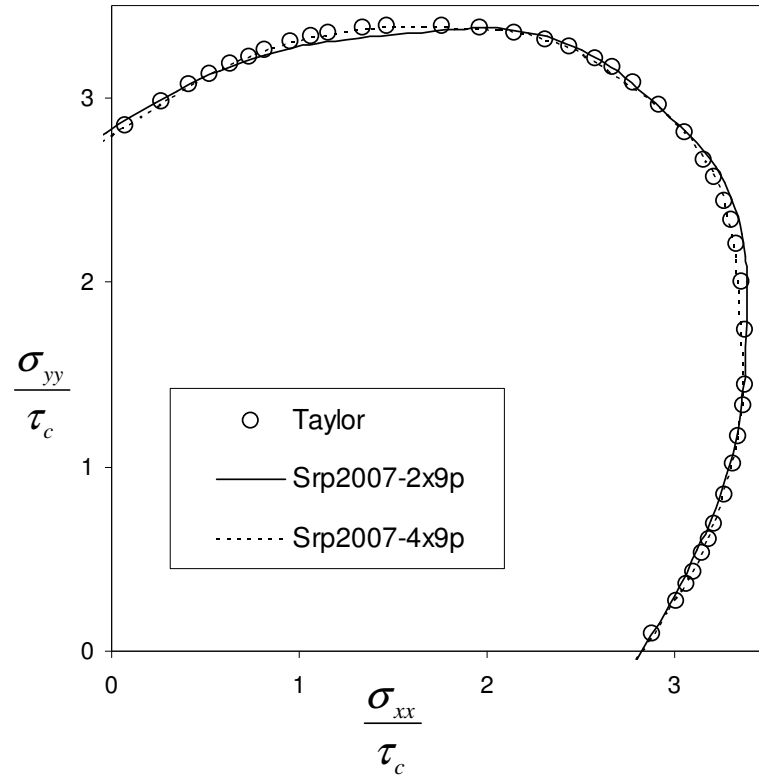


Figure 2. Normal plane stress yield surface for a DC06 mild steel (top) and an AA6022 aluminum alloy (bottom).

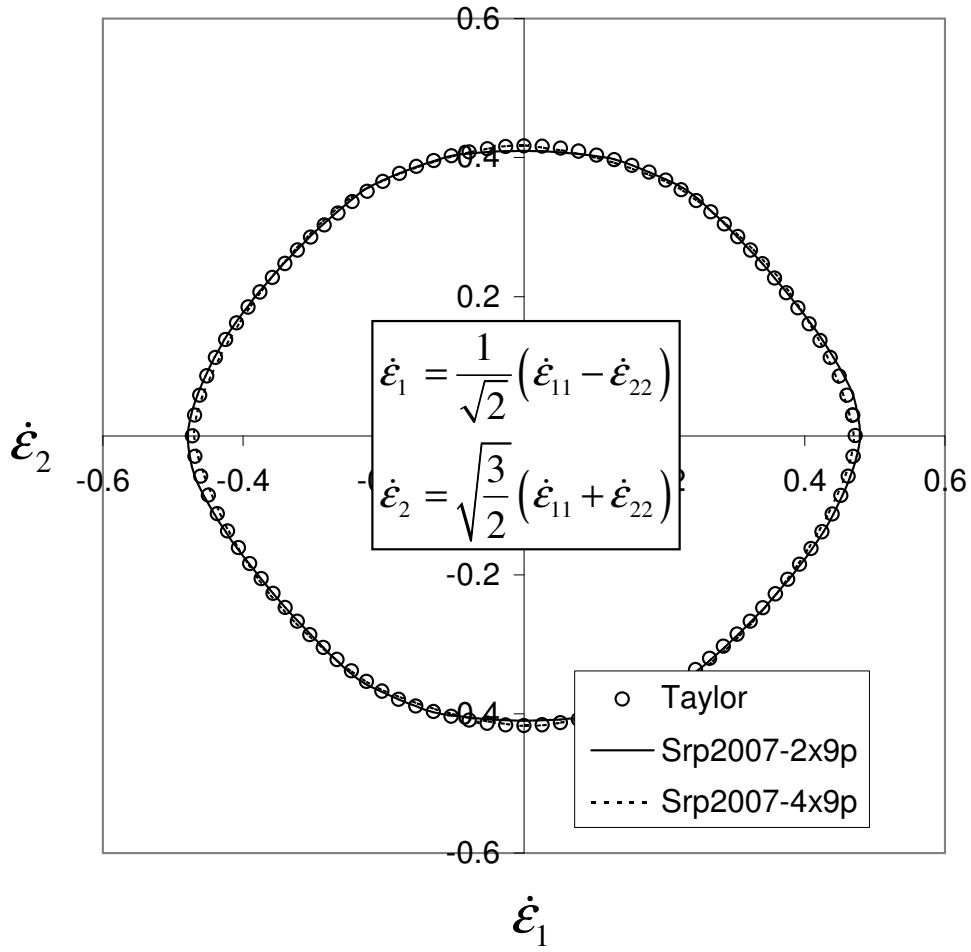


Figure 3. π -plane plot of plastic strain-rate potentials for the mild steel DC06.

Figure 4 gives a global picture of the respective ability of the various models to describe the plastic anisotropy of sheet metals. It appears clearly that considering up to four or five linear transformation in the Srp2007 expression allows for an improvement in accuracy and flexibility. However, the addition of the sixth transformation brings almost no improvement for all the materials and it appears useless to increase complexity beyond this value.

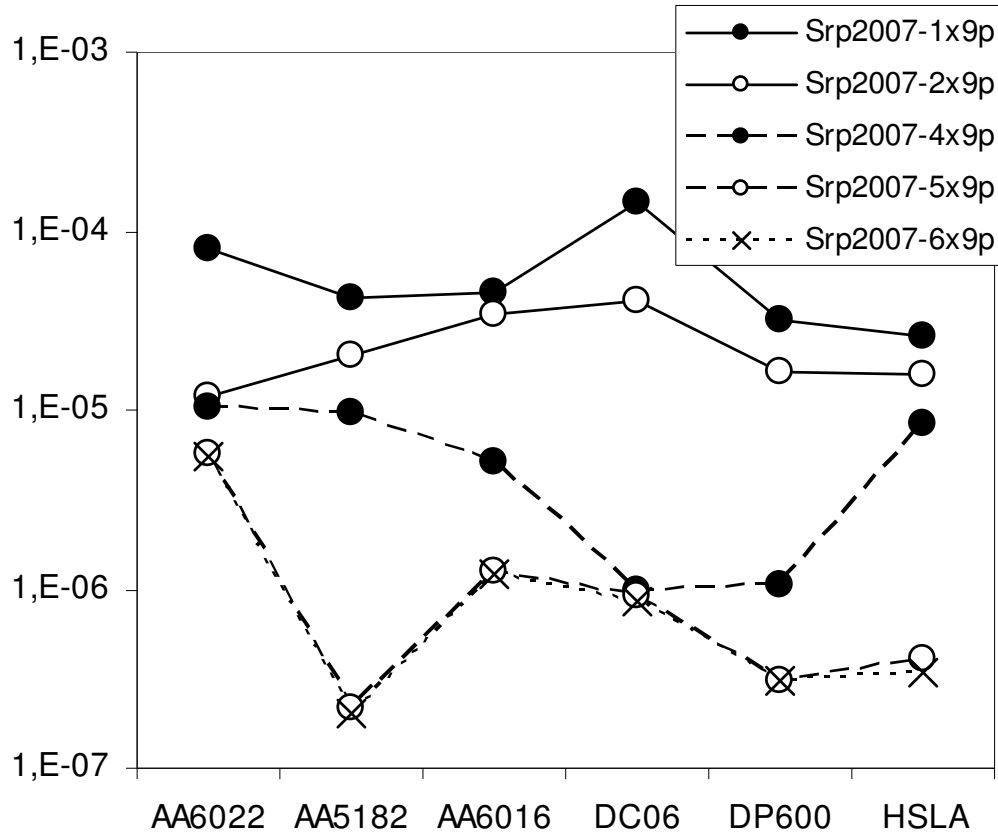


Figure 4. Values of the minimum objective function after parameter identification of different versions of the Srp2007 model, for each of the six materials.

While these conclusions are clearly reproduced for all the materials in this study, it is not obvious from Figure 2 and Figure 3 that a significant improvement has been obtained in the shape of the yield locus, *e.g.* when four linear transformations are used instead of only two for the DC06 mild steel sheet. Figure 5 provides a different graphical representation of the five-dimensional equipotential surface predicted for the DC06 mild steel: a two-dimensional cut is made in this surface through a plane containing the two through-thickness shear components². It appears clearly from this graph that the use of more than two linear transformations improves the predictions in the whole five-dimensional space of possible plastic strain-rate directions, which explains the diminution of the corresponding error function by more than one order of magnitude.

² The variables on the two axes are scaled in such a way that a von Mises model would be represented by circles in all these graphs. More details about this scaling are given in appendix.

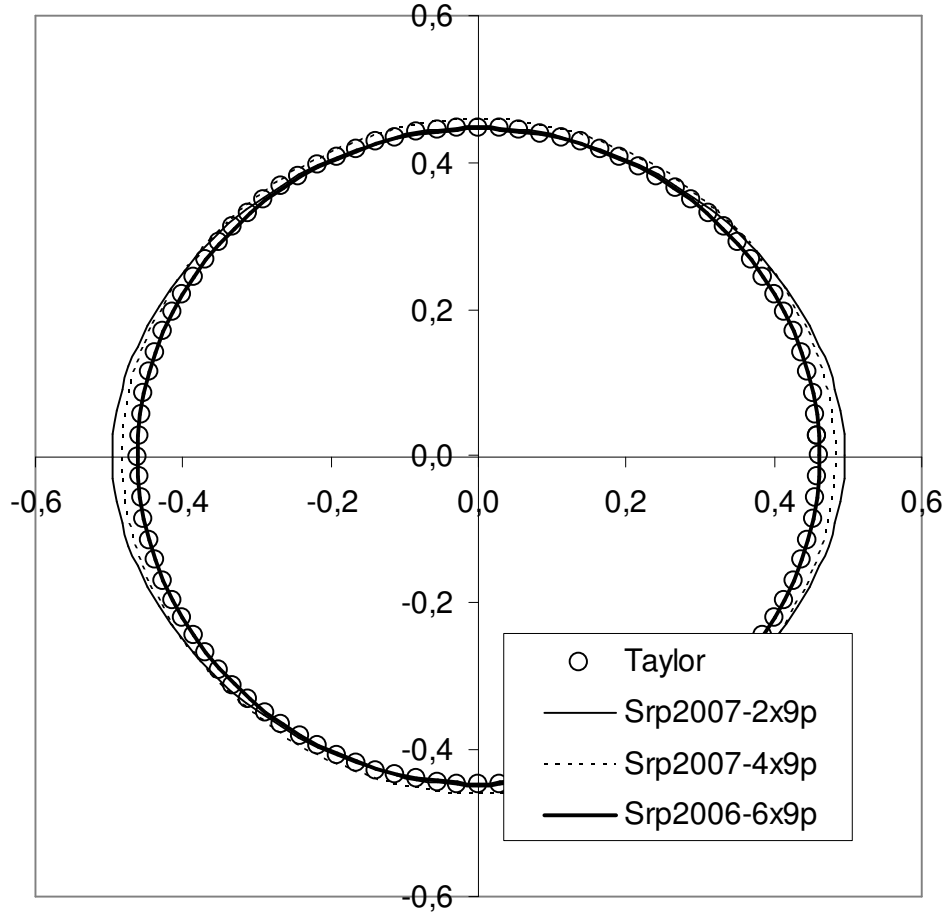


Figure 5. Scaled $\dot{\epsilon}_{xz} - \dot{\epsilon}_{yz}$ plot of plastic strain-rate potentials for the mild steel DC06.

In contrast to the regular parameter identification method that uses mechanical test data, it is noteworthy here that the r -values have not been used for the identification. Consequently, they can be used as a means of validation. Figure 6 depicts the predictions of the r -values for all the materials analyzed in this work, as predicted by the Taylor model and by the Srp2007 models with up to six transformations. First, let us note that the Taylor model is known to predict the anisotropy coefficients rather poorly; this prevents the use of this data for the parameter identification. Moreover, the crystal plasticity predictions in Figure 6 are slightly noisy. From this figure and from Figure 1b, it is obvious that for the aluminum alloys, for which only one slip system is used, the r -value variation smoothly oscillates with a period of 10° . This corresponds to the step of discretization of the Euler angles when the orientation distribution function is constructed for each material (2016 crystallographic orientations are used to describe the orientation distribution function).

Nevertheless, it is obvious from these graphs that additional linear transformations in the Srp2007 model improve the prediction of the r -values for most materials. The predictions of the two-transformation model consistently improve the predictions with respect to the one-transformation one; yet they are still inaccurate for some materials. However, for all the materials investigated, the four-transformation and six-transformation versions laid very close to the micromechanical model predictions – remaining in the error range of the Taylor model itself. On the other side, the increased flexibility of the multiple-transformation potential

sometimes led to numerous oscillations of the anisotropy coefficient in the neighborhood the reference curve. Mathematically speaking, these oscillations lay close to the reference data and most of the time they are smaller than the error range of the Taylor model; thus no better result could be expected from the automatic identification procedure. However, the smoothness of the r-value in-plane variation is a pre-requisite for a correct prediction e.g. of the cup drawing ears – more generally the flow anisotropy prediction in finite element simulations (Rabahallah *et al.*, 2008b). As a consequence, the robust parameter identification of the Srp2007 models might require a smoothing procedure in order to enforce the realistic variation of the anisotropy coefficient.

These results also show that, especially for the more usual potentials (*i.e.* with one or two transformations), excluding the r-values from the reference data used for identification may lead to inaccurate results. This observation is well known in the case when a reduced number of experimental data are used for the identification. Here, the same conclusion is obtained even if the number of stress points is very large and evenly distributed in the whole space of possible loading directions.

Due to the restricted range of application of the Taylor model, the use of the current identification technique cannot eliminate completely the experimental results without loss of accuracy. Instead, it provides a consistent method to compare plasticity models and it also allows, in combination with experimental results, for a better identification of the potential parameters affecting the through-thickness shear terms, which cannot be identified by means of experimental data only.

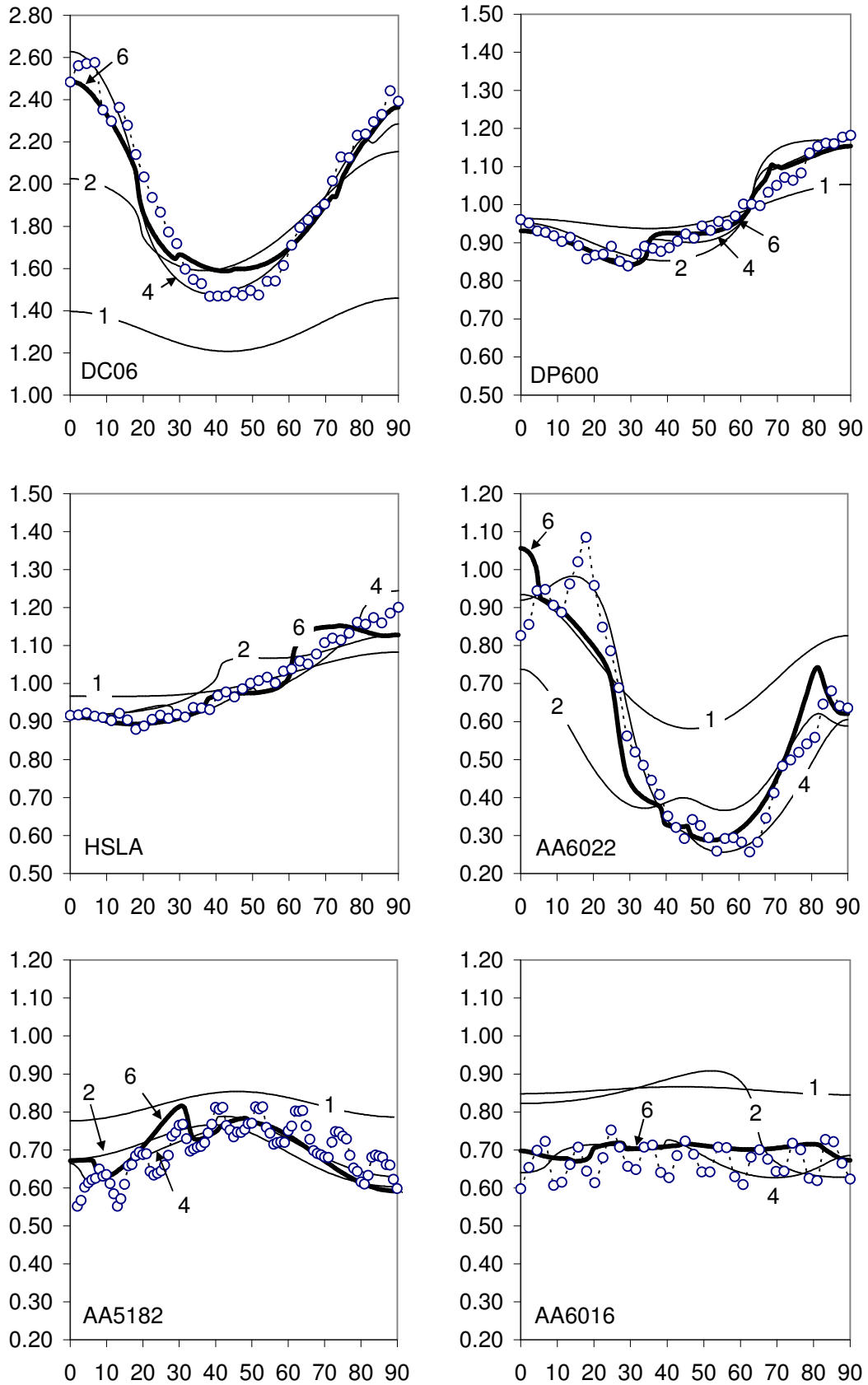


Figure 6. Predictions of the in-plane variation of r-values for the six materials studied in the paper. The reference data (r-values predicted with the Taylor model – represented by open circles) have not been used for the parameter identification. The numbers on the plots (1, 2, 4 and 6) designate the number of transformations (the thick lines designate the six-transformation potential).

5. Conclusions

A new formulation of plastic strain-rate potentials has been proposed that includes as particular cases the previous members of the *Srp*-family of plastic potentials. This expression allows for arbitrarily increasing the number of parameters. It has been shown that each additional linear transformation corresponds to a clear improvement in the flexibility of the obtained model, for a wide range of steel and aluminum alloy sheets, up to five transformations.

The use of the texture-based identification approach has shown that the through-thickness predictions of the *Srp*-models are also improving when additional linear transformations are used. The four-transformation version almost perfectly reproduces the micromechanical model for the particular materials studied in this work. This, as well as the use of a large set of evenly-distributed reference points, is a major advantage of the texture-based identification approach.

In practice, this parameter identification technique is restricted to sheet metals where the considered micromechanical model is known to correctly describe the real plastic anisotropy of the material. In this case, this approach not only generates accurate parameters, but it does so at a much lower cost as compared to the experimental method. For most practical applications, however, experimental data (*r*-values, uniaxial and biaxial yield stresses etc.) shall be used for the identification; if necessary, micromechanical calculations can be added (with a reduced weight in the objective function) to the experimental data set in order to identify all the parameters of the potential (Kim *et al.*, 2007).

Future work concerns the generalization of this approach to the *Yld*-family of yield criteria – as it has already been applied e.g. by (Plunkett *et al.*, 2008) for the CB2006 criterion.

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Appendix 1: Strain rate potential first derivatives

The associated normality flow rule Eq. (2) is used to obtain the stress deviator, in which

$$\frac{\partial \psi}{\partial \dot{\mathbf{E}}} = \frac{1}{N} \frac{\psi^{1-b}}{b(2^{1-b} + 1)} \sum_{k=1}^N \left(\frac{\partial \varphi_1}{\partial \tilde{\mathbf{E}}^k} \cdot \frac{\partial \tilde{\mathbf{E}}^k}{\partial \dot{\mathbf{E}}} \right) \quad (11)$$

For the general expression of Srp2007- $N \times 9$ p shown in Eq. (7), the expressions for $\partial \varphi_1 / \partial \tilde{E}_i^k$, $i = \overline{1,3}$ are

$$\frac{\partial \varphi_1}{\partial \tilde{E}_i^k} = b \tilde{E}_i^k \left| \tilde{E}_i^k \right|^{b-2} \quad (12)$$

The terms $\partial \tilde{\mathbf{E}}^k / \partial \dot{\mathbf{E}}$ are independent of the number of transformations in the potential and their calculation is provided in (Kim *et al.*, 2007).

Appendix 2: Five-component notation for symmetric deviatoric tensors

Any symmetric, deviatoric, second order tensor \mathbf{A} contains only five independent components. Thus, the same tensor can be fully described by a five-component vector $[A_1 \ A_2 \ A_3 \ A_4 \ A_5]^T$. The choice of the five components is not unique. The following choice is made in this paper:

$$\begin{aligned} A_1 &= \frac{1}{\sqrt{2}} (A_{11} - A_{22}) \\ A_2 &= \sqrt{\frac{3}{2}} (A_{11} + A_{22}) \\ A_3 &= \sqrt{2} A_{23} \\ A_4 &= \sqrt{2} A_{31} \\ A_5 &= \sqrt{2} A_{12} \end{aligned} \quad (13)$$

This particular notation has several advantages. First, the norm of the five-component vector is equal to the norm of the tensor that it represents:

$$\|\mathbf{A}\|^2 = A_k A_k = A_{ij} A_{ij} ; \quad k = \overline{1,5} ; \quad i, j = \overline{1,3} \quad (14)$$

More generally, the result of the scalar products of second and/or fourth order tensors (symmetric and deviatoric) corresponds to the scalar products of their five-component vector and/or tensor counterparts. Additionally, this particular notation gives equivalent weights to each component of the plastic strain-rate tensor in the expression of plastic strain-rate

potentials. Consequently, a von Mises-type plastic potential would be represented by identical circles in any two-dimensional representation like the one in Figure 3.

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