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Fully integrated multi-scale modelling of damage and time-dependency in thermoplastic-based woven composites

F Praud, G Chatzigeorgiou and F Meraghni

Abstract

In this work, a multi-scale model established from the concept of periodic homogenization is utilized to predict the cyclic and time-dependent response of thermoplastic-based woven composites. The macroscopic behaviour of the composite is determined from finite element simulations of the representative unit cell of the periodic microstructure, where the local non-linear constitutive laws of the components are directly integrated, namely, the matrix and the yarns. The thermoplastic matrix is described by a phenomenological multi-mechanisms constitutive model accounting for viscoelasticity, viscoplasticity and ductile damage. For the yarns, a hybrid micromechanical–phenomenological constitutive model accounting for anisotropic damage and anelasticity induced by the presence of a diffuse micro-crack network is utilized. The capabilities of the overall multi-scale model are validated by comparing the numerical predictions with experimental data. Further illustrative examples are also provided, where the composite undergoes time-dependent deformations under uni-axial and non-proportional multi-axial loading paths. The multi-scale model is also employed to analyze the influence of the local deformation processes on the macroscopic response of the composite.

Keywords

Woven composites, thermoplastic matrices, multi-scale modelling, periodic homogenization, damage, time-dependent behaviour

Introduction

In the automotive industry, thermoplastic-based woven composites appear to be particularly attractive, due their lightweight and good mechanical properties associated with a relative ease of

manufacturing. However, the wide-scale use of these composites in structural applications has been hampered by the difficulty to predict their complex behaviour, especially over long periods of time.

Although the overall behaviour of thermoplastic-based composites can be described in a purely phenomenological manner (Feld et al., 2018; Launay et al., 2011; Mandys et al., 2019; Vasiukov et al., 2015), such a modelling strategy generally leads to a large number of parameters that may be difficult to identify and their values are valid only for a unique microstructure configuration. This is a real limitation towards capturing accurately the local behaviour and deformation processes. To overcome this issue, the composites response can be described with the help of multi-scale modelling approaches, by considering a representative volume element (RVE) of the microstructure. The main advantage of this modelling strategy is that the local constitutive laws of the constituents are directly integrated along with the geometric definition of the microstructure, leading to a more physical description of the deformation processes.

The multi-scale modelling of heterogeneous materials, in which the components exhibit non-linear mechanical response, requires advanced homogenization techniques. Among the existing modelling strategies, two of them appear to be particularly attractive for this purpose, as they can easily account for many types of constitutive laws and microstructures:

- The first one considers the so-called mean-field approaches (Mura, 1987; Nemat-Nasser and Hori, 1999; Qu and Cherkaoui, 2006) based on the Eshelby's solution (Eshelby, 1957) such as the micromechanical scheme of Mori-Tanaka (Benveniste, 1987; Mori and Tanaka, 1973), the self-consistent method (Hill, 1965) or the method proposed by Ponte Castañeda and Willis (1995). These theories usually deal with randomly distributed ellipsoidal inhomogeneities embedded in a matrix material. Therefore, they are particularly adapted to the cases of short and long fibres reinforced composites. Woven composites may be eventually considered if the yarns waviness is neglected, or by discretizing the wavy yarns into smaller but straight segments and replacing them with an equivalent system of ellipsoids (Abdin et al., 2016). While initially developed for linear elasticity, these methods can be extended to the case of non-linear behaviour through an incremental formulation (Gavazzi and Lagoudas, 1990; Lagoudas et al., 1991). Although these methods are based on semi-analytical solutions with fast computations, they unfortunately keep a limited accuracy and must be used with caution, especially when the matrix phase exhibits a non-linear response (Lagoudas et al., 1991). This inaccuracy is mainly caused by the local fields in the matrix that are considered in an average way. This is likely not to give good enough estimates when the non-linearity is matrix-dominated. More accurate solutions are sometimes obtained through specific enhancements that are mostly dedicated to short or long fibres reinforced composites (Barral et al., 2020; Chaboche et al., 2005; Doghri and Ouaar, 2003) rather than the case of woven composites.
- The second strategy deals with full-field approaches, whose most representative case is the periodic homogenization (Michel et al., 1999; Sanchez-Palencia, 1974; Suquet, 1987). By definition, this method is particularly suitable for composites with periodic microstructure, such as woven composites (Courtois et al., 2019; Hofer et al., 2020; Ullah et al., 2019; Xu et al., 2018). Moreover, periodic homogenization allows to properly define the concept of homogenized behaviour through a rigorous framework, which is fundamentally independent of the choice of the local constitutive laws of the different phases (Charalambakis et al., 2018; Chatzigeorgiou et al., 2015). Due to its periodicity, the RVE is represented by the smallest repeating element, commonly referred to as the unit cell, on which well-defined periodic boundary conditions are applied (Li, 1999, 2001; Li and Wongsto, 2004). Except for particular cases, the resolution of such a problem requires the use of numerical techniques, mostly the finite element (FE) method.

The geometry of the unit cell is then represented through a FE mesh integrating the local constitutive equations of each sub-domain. Compared to mean-field approaches, the use of periodic homogenization may lead to an important computational cost, which is nevertheless necessary to accurately and properly describe the behaviour of certain types of composite materials such as woven composites.

In the present work, a fully integrated multi-scale model is utilized to describe and study the cyclic and time-dependent response of thermoplastic-based woven composites, under the small strain assumption and isothermal conditions. Based on the framework of periodic homogenization (Michel et al., 1999; Sanchez-Palencia, 1974; Suquet, 1987), a proper transition is established between the macroscopic and microscopic scales, enabling a direct integration of the local non-linear constitutive laws of the components, namely, the thermoplastic polymer matrix and the yarns. The proposed multi-scale model is thus referred as ‘fully integrated’ as the macroscopic response of the composite is determined from FE simulations on its unit cell. The local behaviour of the thermoplastic matrix is described by a phenomenological multi-mechanisms constitutive model accounting for viscoelasticity, viscoplasticity and ductile damage (Praud, 2018; Praud et al., 2017a). For the yarns, a hybrid micromechanical–phenomenological constitutive model is utilized to represent the anisotropic damage and anelasticity induced by the presence of a diffuse micro-crack network (Praud, 2018; Praud et al., 2017b).

By considering the theory of periodic homogenization and the established constitutive models for the matrix and the yarn phases, the novelty of this work lies within the development of a comprehensive and robust fully integrated multi-scale model to describe the cyclic and time-dependent response of thermoplastic-based woven composites. The accuracy of the proposed multi-scale model is evaluated by comparing the numerical predictions with experiments carried out on a woven composite made of a polyamide 6-6 matrix with an E-glass balanced 2-2 twill weave reinforcement, referred to as the studied composite. The multi-scale model is furthermore employed to understand the local damage mechanisms and deformation processes, and to analyze their influence on the macroscopic response of the composite in relation with its microstructure. Up to the author’s knowledge, such a comprehensive multi-scale analysis, integrating highly complicated constitutive laws for the matrix and the yarns, has never been performed before for this type of materials.

In this paper, the following notation is adopted. Bold lower-case Latin symbols are vectors (\mathbf{a} , $\mathbf{b} \dots$). Bold upper-case Latin and Greek symbols are second-order tensors (\mathbf{A} , $\mathbf{B} \dots \boldsymbol{\alpha}$, $\boldsymbol{\beta} \dots$) and \mathbf{I} denotes the second-order tensors identity tensor. Blackboard symbols are fourth-order tensors (\mathbb{A} , $\mathbb{B} \dots$), and \mathbb{I} denotes the fourth-order tensors identity tensor. All the others standard symbols (neither in bold nor in blackboard) are scalars (a , $b \dots A$, $B \dots \alpha$, $\beta \dots$). Furthermore, \cdot , $:$ and \otimes represent the single contracted, twice contracted and dyadic products, respectively.

Non-linear periodic homogenization

Theoretical background

A periodic medium is defined by a unit cell (the smallest repeating unit element) that is representative of the microstructure. If the dimensions of the unit cell are small enough compared to the dimensions of the macroscopic medium, then a scale separation can be assumed with two scales: a macroscopic one, defined by the macroscopic (or global) coordinates, denoted by $\bar{\mathbf{x}} \in \bar{V}$, and a microscopic one, defined by the microscopic (or local) coordinates, denoted by $\mathbf{x} \in V$. The assumption of scale separation ($\bar{V} \gg V$) allows to consider that the unit cell is representative of a

macroscopic material point. At the macroscopic scale, the heterogeneous medium is replaced by an equivalent homogenized medium (Figure 1). Under quasi-static conditions (the inertia effects are considered negligible), the motion of any macroscopic and microscopic material point $\bar{M}(\bar{x})$ and $M(\bar{x}, \mathbf{x})$, respectively, is governed by the macro-scale and micro-scale equations given in Table 1. The homogenization consists in defining the global constitutive behaviour, described by the operator \bar{F} (see the left part of Table 1), which is implicitly defined by the local operator F (see the right part of Table 1) and the geometrical characteristics of the various constituents in the unit cell. The local models may be non-linear and involve internal state variables. They may also be time-dependent (viscoelasticity, viscoplasticity, etc.).

In order to link the micro-scale with the macro-scale equations, a connection between scales is required. To do so, the macroscopic stress and strain fields are identified through volume average of their microscopic counterparts over the unit cell (Hill, 1967; Mura, 1987; Nemat-Nasser and Hori, 1999). Moreover, from the divergence theorem, it can be demonstrated that the stress and strain averages within a unit cell are also connected to the traction and displacement vectors applied on its boundaries

$$\bar{\sigma}(\bar{x}, t) = \frac{1}{V} \int_V \sigma(\bar{x}, \mathbf{x}, t) dV = \frac{1}{V} \int_{\partial V} \sigma(\bar{x}, \mathbf{x}, t) \cdot \mathbf{n}(\mathbf{x}) \otimes \mathbf{x} dS \quad (1)$$

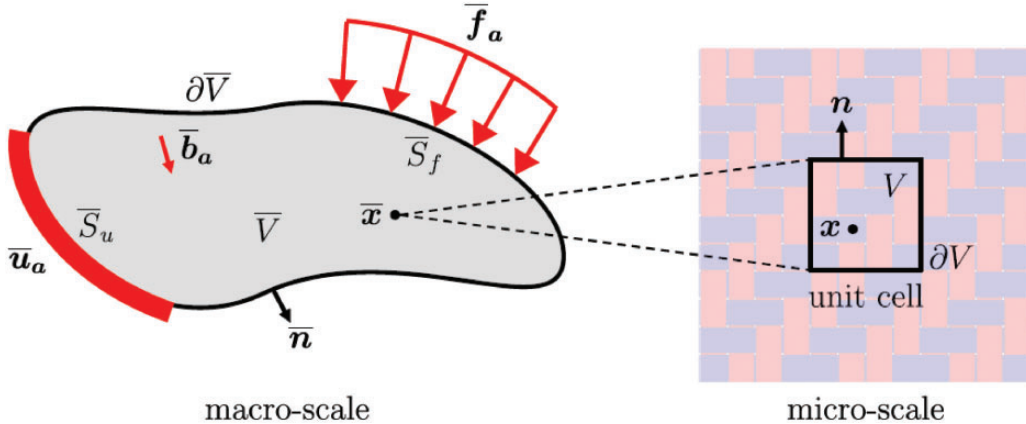


Figure 1. Schematic representation of a heterogeneous material with a periodic microstructure by considering a scale separation.

Table 1. Macro-scale and micro-scale equations. Conversely to the operator \bar{F} , which is explicitly defined, the operator F is implicitly defined through the homogenization scheme.

Equations	Macro-scale	Micro-scale
	$\forall \bar{x} \in \bar{V}, \forall t$	$\forall \bar{x} \in \bar{V}, \forall \mathbf{x} \in V, \forall t$
Equilibrium	$\text{div}_{\bar{x}}(\bar{\sigma}) + \bar{b}_a = 0$	$\text{div}_{\mathbf{x}}(\sigma) = 0$
Kinematics	$\bar{\varepsilon} = \frac{1}{2}(\text{Grad}_{\bar{x}}(\bar{u}) + \text{Grad}_{\bar{x}}^T(\bar{u}))$	$\varepsilon = \frac{1}{2}(\text{Grad}_{\mathbf{x}}(u) + \text{Grad}_{\mathbf{x}}^T(u))$
Constitutive law	$\bar{\sigma} = \bar{F}(\bar{\varepsilon})$	$\sigma = F(\mathbf{x}, \varepsilon)$
Mechanical work	$\bar{W} = \bar{\sigma} : \bar{\varepsilon}$	$W = \sigma : \varepsilon$

$$\bar{\boldsymbol{\varepsilon}}(\bar{\mathbf{x}}, t) = \frac{1}{V} \int_V \boldsymbol{\varepsilon}(\bar{\mathbf{x}}, \mathbf{x}, t) dV = \frac{1}{2V} \int_{\partial V} (\mathbf{u}(\bar{\mathbf{x}}, \mathbf{x}, t) \otimes \mathbf{n}(\mathbf{x}) + \mathbf{n}(\mathbf{x}) \otimes \mathbf{u}(\bar{\mathbf{x}}, \mathbf{x}, t)) dS \quad (2)$$

where \mathbf{n} stands for the outward normal defined on each point of the unit cell borders ($\forall \mathbf{x} \in \partial V$).

In Table 1, the macro-scale equations are supplemented by boundary conditions specific to the treated problem. For the micro-scale equations, the boundary conditions arise from the assumption of periodicity (Suquet, 1987) implying that, within the unit cell, the displacement vector \mathbf{u} of any microscopic material point $M(\bar{\mathbf{x}}, \mathbf{x})$ can be written under the following form

$$\mathbf{u}(\bar{\mathbf{x}}, \mathbf{x}, t) = \bar{\boldsymbol{\varepsilon}}(\bar{\mathbf{x}}, t) \cdot \mathbf{x} + \mathbf{u}'(\bar{\mathbf{x}}, \mathbf{x}, t) + \mathbf{u}_0(\bar{\mathbf{x}}, t) \quad (3)$$

where the first term stands for the affine part of the local displacement field. The latter is directly related to the macroscopic strain $\bar{\boldsymbol{\varepsilon}}$. The second term \mathbf{u}' represents a periodic fluctuation, while the last term \mathbf{u}_0 depicts a rigid body motion that comes out from the macroscopic problem and consequently does not depend on the microscopic problem. As \mathbf{u}' is periodic, it takes the same value on each pair of opposite points \mathbf{x}_+ and \mathbf{x}_- of the unit cell boundaries ($\mathbf{x}_+, \mathbf{x}_- \in \partial V$)

$$\mathbf{u}'(\bar{\mathbf{x}}, \mathbf{x}_+, t) = \mathbf{u}'(\bar{\mathbf{x}}, \mathbf{x}_-, t) \quad (4)$$

By substituting (3) into (4), these periodicity conditions can be expressed in terms of \mathbf{u} instead of \mathbf{u}' , while involving the macroscopic strain tensor $\bar{\boldsymbol{\varepsilon}}$

$$\mathbf{u}(\bar{\mathbf{x}}, \mathbf{x}_+, t) - \mathbf{u}(\bar{\mathbf{x}}, \mathbf{x}_-, t) = \bar{\boldsymbol{\varepsilon}}(\bar{\mathbf{x}}, t) \cdot (\mathbf{x}_+ - \mathbf{x}_-) \quad (5)$$

Note that, due to its periodic aspect, the strain average (within the unit cell) produced by \mathbf{u}' is null. Therefore, the total strain average is well equal to the macroscopic strain as expressed in (2).

Finite element resolution of the unit cell problem

The relationship between the macroscopic stress and strain (operator $\bar{\mathbf{F}}$) results from the solution of the microscopic problem (given in Table 1). The latter can be easily solved by the FE method, using a mesh of the unit cell, on which the periodicity conditions (5) are applied using the generalized methodology proposed by Li (1999, 2001), Li and Wongsto (2004) and Praud (2018), which is described in this section.

Considering a cubic FE unit cell,¹ the aim of this method is to apply a macroscopic strain $\bar{\boldsymbol{\varepsilon}}$, by taking into account the periodic boundary conditions previously described in (5). A displacement gradient is then applied between each pair of opposite boundary nodes, respectively, denoted by the indices i and j . This gradient is directly related to the macroscopic strain tensor $\bar{\boldsymbol{\varepsilon}}$

$$\begin{Bmatrix} u_1^i - u_1^j \\ u_2^i - u_2^j \\ u_3^i - u_3^j \end{Bmatrix} = \begin{pmatrix} \bar{\varepsilon}_{11} & \bar{\varepsilon}_{12} & \bar{\varepsilon}_{13} \\ & \bar{\varepsilon}_{22} & \bar{\varepsilon}_{23} \\ \text{sym.} & & \bar{\varepsilon}_{33} \end{pmatrix} \times \begin{Bmatrix} x_1^i - x_1^j \\ x_2^i - x_2^j \\ x_3^i - x_3^j \end{Bmatrix} \quad (6)$$

In the above expression, u_1, u_2, u_3 and x_1, x_2, x_3 are the components of the displacement and position vectors, \mathbf{u} and \mathbf{x} , respectively. The proposed method introduces the six components of the

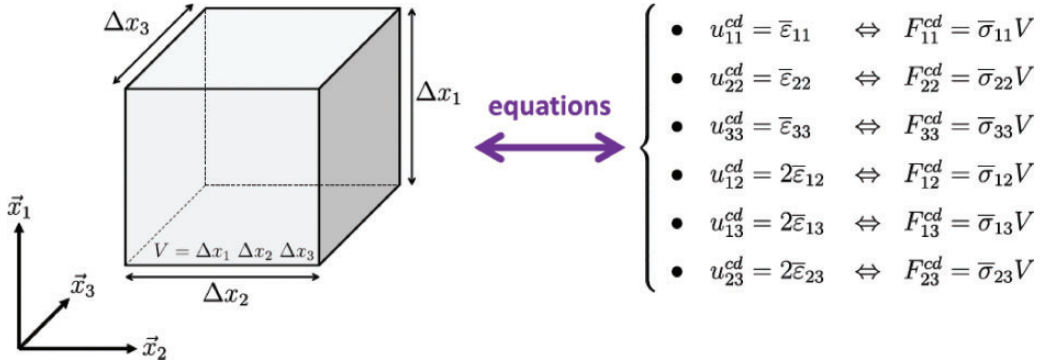


Figure 2. Connection of the ‘constraint drivers’ with the unit cell.

macroscopic strain tensor as ‘additional degrees of freedom’ that are directly involved in the boundary conditions (Li, 1999, 2001; Li and Wongsto, 2004). These ‘additional degrees of freedom’ are linked to the mesh of the unit cell using kinematic constraint equations obtained from (6) and are thus used as ‘constraint drivers’. From a practical point of view, the ‘constraint drivers’ can be introduced by adding six new nodes among which only the first degree of freedom is used. Each displacement of those ‘constraint drivers’, noted u_{11}^{cd} , u_{22}^{cd} , u_{33}^{cd} , u_{12}^{cd} , u_{13}^{cd} and u_{23}^{cd} , takes the values of each component of the macroscopic strain tensor: $\bar{\epsilon}_{11}$, $\bar{\epsilon}_{22}$, $\bar{\epsilon}_{33}$, $2\bar{\epsilon}_{12}$, $2\bar{\epsilon}_{13}$ and $2\bar{\epsilon}_{23}$, respectively. By proceeding this way, after properly formulating the kinematic constraint equations (Praud, 2018), the dual forces associated with the ‘constraint drivers’, noted F_{11}^{cd} , F_{22}^{cd} , F_{33}^{cd} , F_{12}^{cd} , F_{13}^{cd} and F_{23}^{cd} , directly provide the product of the unit cell’s volume with the corresponding components of the macroscopic stress tensor, $\bar{\sigma}_{11}$, $\bar{\sigma}_{22}$, $\bar{\sigma}_{33}$, $\bar{\sigma}_{12}$, $\bar{\sigma}_{13}$ and $\bar{\sigma}_{23}$, respectively, as illustrated in Figure 2.

This approach enables to apply any state of macroscopic strain or stress on the unit cell. Since each ‘constraint driver’ can be independently set either in terms of displacement (macroscopic strain) or in terms of force (macroscopic stress). Mixed stress–strain states can also be assigned. As previously mentioned, the solution of a periodic homogenization is determined up to a rigid body motion. For this reason, a node of the model needs to be clamped in order to guarantee the uniqueness of the solution and the solvability of the FE system.

Unit cells for woven composites

In order to apply the framework of periodic homogenization to the case of woven composites, it is necessary to provide a geometric representation of the unit cell along with its associated FE mesh. With this purpose, many works have been already undertaken (Couégnat, 2008; Lin et al., 2011; Lomov et al., 2000, 2001, 2007; Sherburn, 2007), leading to the development of several dedicated tools. Among these tools, the *TexGen* platform (Lin et al., 2011; Sherburn, 2007), which is utilized in this work, is an open source and free software developed at the University of Nottingham and shows very interesting capabilities in generating FE unit cell of any woven pattern.

Concerning the 2-2 twill weave pattern studied in the present case (see Figure 3(b)), the geometry of the woven microstructure is defined through the parameters l_1 , l_2 , l_3 , l_4 and l_5 , shown in Figure 3(a). For the examined composite, the characteristic dimensions l_1 , l_2 and l_3 are evaluated from experimental observations carried out by means of X-ray computed micro-tomography, as illustrated in Figure 4. The dimension l_4 is obtained by dividing the total thickness of the provided plates by the number of layers they contain. The parameter l_5 has been deliberately over-sized in the present work

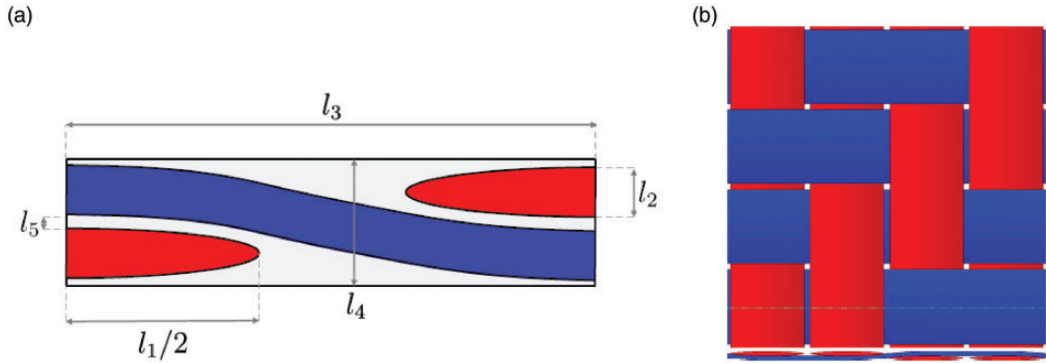


Figure 3. Geometric definition of the microstructure. The grey domain represents the matrix phase, while the blue and red domains are the warp and weft yarns, respectively. (a) Characteristic dimensions of a woven microstructure. (b) 2–2 twill weave pattern.

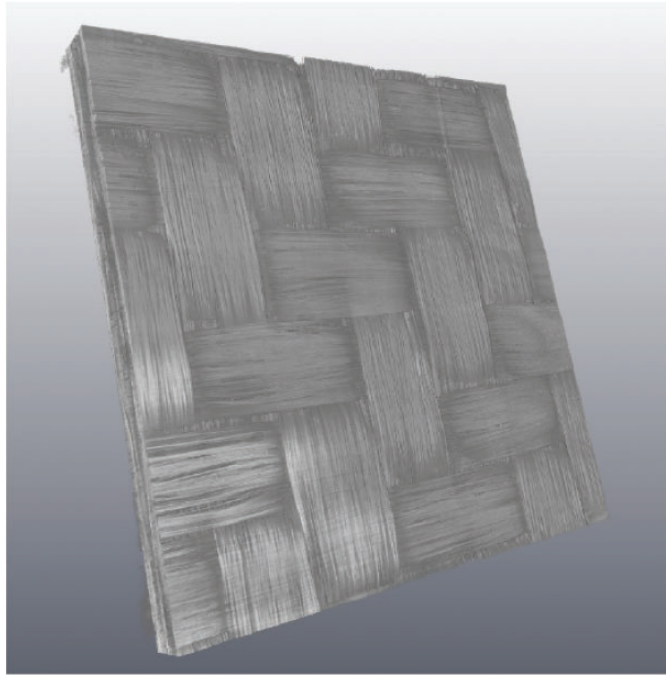


Figure 4. 3D reconstruction of the microstructure of the studied composite using X-ray computed micro-tomography with a voxel size of 6 μm .

to ensure a proper enough mesh within the matrix domain. The average values considered for the multi-scale model are listed in Table 2. Note that, under this configuration, the unit cell yields to a yarn volume fraction of 59%. Furthermore, analyses from micrography have shown that the intra-yarn fibre volume fraction is about 85%. Overall, the fibre volume fraction in the whole composite is about 50%, which is well in accordance with the supplier data.

Using the data in Table 2, the unit cell of the studied composite is generated and subsequently meshed through the *TexGen* utilities (Lin et al., 2011; Sherburn, 2007) (see Figure 5). The yarns, which are composed of numerous fibres unidirectionally oriented inside the matrix, are treated within the described modelling approach as an equivalent homogeneous medium with an anisotropic constitutive behaviour. The material orientation is defined for each point with respect to the yarns middle line whose waviness is automatically calculated according to the considered weaving pattern, as shown in Figure 5(d).

The mesh of the unit cell, shown in Figure 5, contains 8,522 nodes and 40,060 first-order tetrahedral elements (C3D4 in *ABAQUS/Standard*). Note that a spatial convergence analysis was carried out regarding the mesh refinement in order to obtain a good enough compromise between accuracy and reasonable computational cost.

Local constitutive models

The constitutive models (or sub-models) presented in this section are utilized to describe the behaviour of the matrix and yarn phases. Nevertheless, it should be pointed out that the homogenization framework previously introduced is completely independent of the local constitutive models, which

Table 2. Characteristic dimensions of the microstructure and adopted values for the studied composite.

Characteristic dimensions	l_1	l_2	l_3	l_4	l_5
Values (mm)	3.46	0.21	3.75	0.5	0.025

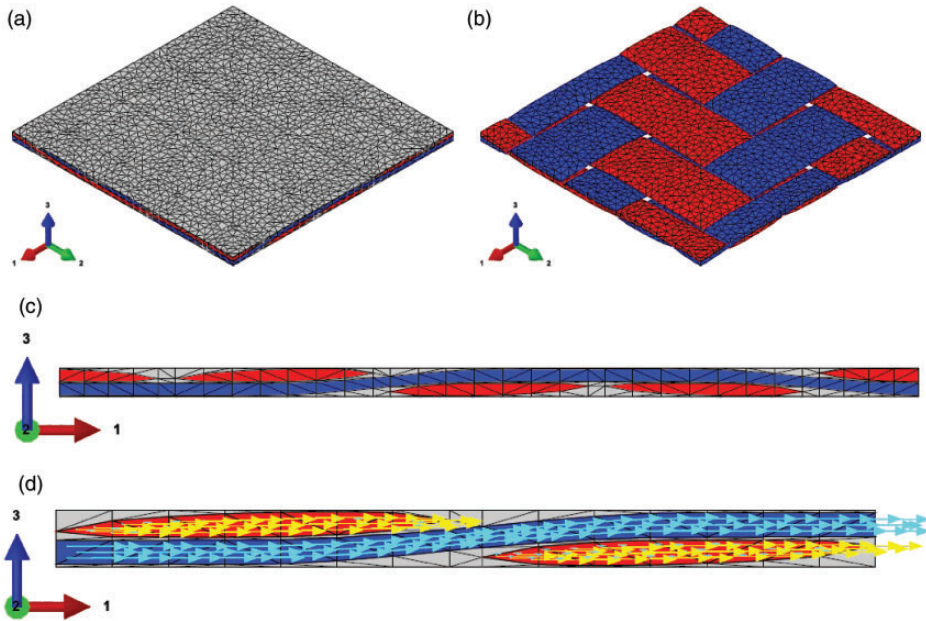


Figure 5. Finite element mesh of the unit cell of the studied composite. (a) Mesh of the entire unit cell; (b) mesh of the yarns; (c) side view of the mesh; (d) material orientations of the yarns elements: the first axis (in blue) is always oriented along the middle line of the yarns, while the second axis (in yellow) is always parallel to the plane of the woven reinforcement.

means that the sub-models presented in this section work as ‘bricks’ that can be easily interchanged with other sub-models.

Local constitutive model for the matrix

Thermoplastics and more especially semi-crystalline polymers, such as polyamide 6-6, are known to exhibit a complex dissipative behaviour combining both fluid and solid properties. Moreover, experimental investigations (Detrez et al., 2011) showed that these materials, when loaded, present a reduction of their apparent stiffness induced by damage mechanisms. To account for this particular behaviour, the constitutive model developed for such type of materials by Praud (2018) and Praud et al. (2017a) is utilized to describe the response of the matrix phase. This model is written within the framework of thermodynamics (Chatzigeorgiou et al., 2018; Germain et al., 1983; Lemaitre and Chaboche, 1990) and integrates viscoelasticity, viscoplasticity and ductile damage through a multi-mechanisms formulation, as represented by the rheological scheme in Figure 6.

For the matrix phase, the state laws are based on the following form of the Helmholtz free energy potential

$$\begin{aligned} \rho\psi(\boldsymbol{\varepsilon}, \boldsymbol{\varepsilon}_{v_i}, \boldsymbol{\varepsilon}_p, r, D) = & \frac{1}{2} \left(\boldsymbol{\varepsilon} - \sum_{i=1}^N \boldsymbol{\varepsilon}_{v_i} - \boldsymbol{\varepsilon}_p \right) : (1 - D) \mathbb{C}_e : \left(\boldsymbol{\varepsilon} - \sum_{i=1}^N \boldsymbol{\varepsilon}_{v_i} - \boldsymbol{\varepsilon}_p \right) \\ & + \sum_{i=1}^N \frac{1}{2} \boldsymbol{\varepsilon}_{v_i} : (1 - D) \mathbb{C}_{v_i} : \boldsymbol{\varepsilon}_{v_i} + \int_0^r R(\xi) d\xi \end{aligned} \quad (7)$$

which describes the energetic state of any matrix material point as a function of the strain $\boldsymbol{\varepsilon}$, as observable state variable, and the internal state variables $\boldsymbol{\varepsilon}_{v_i}$, $\boldsymbol{\varepsilon}_p$, r and D that represent the strain related to the i th Kelvin–Voigt branch, the viscoplastic strain, the hardening variable and the damage variable, respectively.

Through the thermodynamical derivation, the stress in the matrix phase is expressed as

$$\boldsymbol{\sigma} = \rho \frac{\partial \psi}{\partial \boldsymbol{\varepsilon}} = (1 - D) \mathbb{C}_e : \left(\boldsymbol{\varepsilon} - \sum_{i=1}^N \boldsymbol{\varepsilon}_{v_i} - \boldsymbol{\varepsilon}_p \right) \quad (8)$$

In the same manner, for the other associated variables related to the matrix phase, it yields

$$-\boldsymbol{\sigma}_{v_i} = \rho \frac{\partial \psi}{\partial \boldsymbol{\varepsilon}_{v_i}} = (1 - D) \mathbb{C}_{v_i} : \boldsymbol{\varepsilon}_{v_i} - \boldsymbol{\sigma} \quad (9)$$

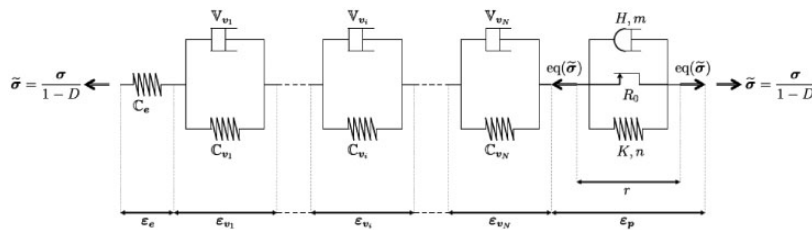


Figure 6. Rheological scheme of the proposed model for the matrix (Praud, 2018; Praud et al., 2017a).

and

$$-\boldsymbol{\sigma} = \rho \frac{\partial \psi}{\partial \boldsymbol{\varepsilon}_p}, \quad R(r) = \rho \frac{\partial \psi}{\partial r}, \quad -Y = \rho \frac{\partial \psi}{\partial D} \quad (10)$$

where, $\boldsymbol{\sigma}_{v_i}$, $R(r)$ and Y denote the viscous stress in the i th Kelvin–Voigt branch, the hardening function and the energy density release rate, respectively. Note that, in equations (7) to (9), \mathbb{C}_e and \mathbb{C}_{v_i} denote the initial fourth-order stiffness tensors of the single spring and the spring of the i th Kelvin–Voigt branch, respectively. These tensors are classically formulated for bulk isotropic materials and are defined by the Young modulus E_e or E_{v_i} , respectively, as well as the Poisson ratio ν which is assumed to be the same in all stiffness tensors. Moreover, in equations (7) and (10), the hardening function $R(r)$ is chosen as a power law, such as $R(r) = Kr^n$, where K and n are material parameters.

The evolution of each viscoelastic strain $\boldsymbol{\varepsilon}_{v_i}$ is governed by a dual dissipation potential written as

$$\varphi^*(\boldsymbol{\sigma}_{v_i}; D) = \sum_{i=1}^N \frac{1}{2} \boldsymbol{\sigma}_{v_i} : \frac{\mathbb{V}_{v_i}^{-1}}{1-D} : \boldsymbol{\sigma}_{v_i} \quad (11)$$

whose derivative with respect to the associated variable $\boldsymbol{\sigma}_{v_i}$ gives the following evolution law

$$\dot{\boldsymbol{\varepsilon}}_{v_i} = \frac{\partial \varphi^*}{\partial \boldsymbol{\sigma}_{v_i}} = \frac{\mathbb{V}_{v_i}^{-1}}{1-D} : \boldsymbol{\sigma}_{v_i} \quad (12)$$

where \mathbb{V}_{v_i} denotes the viscosity tensor of the linear dash-pot of the i th Kelvin–Voigt branch. As for the stiffness tensors, each viscosity tensor is classically formulated for bulk isotropic materials and is defined by a viscosity η_{v_i} and the Poisson ratio ν . The latter is assumed to be the same in each stiffness and viscosity tensor.

In the matrix phase, the damage mechanism is assumed to be ductile as it only evolves with the viscoplasticity, making those two mechanisms directly coupled and simultaneously activated. Such an evolution is represented through the normality rule of an indicative function (Krairi and Doghri, 2014; Lemaitre, 1985) given by

$$F(\boldsymbol{\sigma}, R, Y; D) = \underbrace{\frac{\text{eq}(\boldsymbol{\sigma})}{1-D} - R - R_0}_{f(\boldsymbol{\sigma}, R; D)} + \underbrace{\frac{S}{(\beta+1)(1-D)} \left(\frac{Y}{S}\right)^{\beta+1}}_{f_D(Y; D)} \quad (13)$$

In the above equation, the first term $f(\boldsymbol{\sigma}, R; D)$ represents the yield function where $\text{eq}(\boldsymbol{\sigma})$ designates the equivalent Von Mises stress² and R_0 the yield threshold. The second term $f_D(Y; D)$ depicts the damage contribution in which S and β are material parameters. Thus, expressing the normality of the indicative function $F(\boldsymbol{\sigma}, R, Y; D)$ leads to the following viscoplastic-damage flow rules

$$\dot{r} = -\frac{\partial F}{\partial R} \dot{\lambda} = \dot{\lambda} \quad (14)$$

$$\dot{\boldsymbol{\varepsilon}}_p = \frac{\partial F}{\partial \boldsymbol{\sigma}} \dot{\lambda} = \frac{\boldsymbol{\Lambda}(\boldsymbol{\sigma})}{1-D} \dot{r}, \quad \text{with} \quad \boldsymbol{\Lambda}(\boldsymbol{\sigma}) = \frac{3 \text{Dev}(\boldsymbol{\sigma})}{2 \text{eq}(\boldsymbol{\sigma})} \quad (15)$$

$$\dot{D} = \frac{\partial F}{\partial Y} \dot{\lambda} = \frac{\Omega(Y)}{1-D} \dot{r}, \quad \text{with} \quad \Omega(Y) = \left(\frac{Y}{S}\right)^\beta \quad (16)$$

where λ depicts the viscoplastic-damage multiplier, which appears to be equal to the hardening variable ($\lambda = r$). Its evolution is obtained by considering that the positive part of the yield function f is linked to \dot{r} by

$$\underbrace{\left\langle \frac{\text{eq}(\boldsymbol{\sigma})}{1-D} - R(r) - R_0 \right\rangle}_f = Q(\dot{r}) \quad (17)$$

In this relationship, $Q(\dot{r})$ represents a viscous stress function, which is chosen under the form of a power law, such as $Q(\dot{r}) = H\dot{r}^m$, where H and m are material parameters. It should be noticed that r is only allowed to increase, $\dot{r} > 0$ if $f > 0$, or to remain constant, $\dot{r} = 0$ if $f < 0$.

Note that the convexity of φ^* and F , given in equations (11) and (13), respectively, guarantees the thermodynamical admissibility of the evolution laws (12), (14) to (16).

The constitutive models of the matrix have been implemented into the FE solver *ABAQUS/Standard* by means of User MATerial subroutines (UMAT). The numerical integration scheme is based on the ‘convex cutting plane’ form of the ‘return mapping algorithm’ (Ortiz and Simo, 1986; Simo and Hughes, 1998; Simo and Ortiz, 1985), which is described in Praud (2018) and Praud et al. (2017) for this model. Readers are referred to these references for more details regarding the numerical implementation.

Local constitutive model for the yarns

As previously mentioned, at lower scale a yarn is composed of numerous unidirectionally oriented fibres embedded in the matrix. Consequently, their behaviour can be considered as equivalent to the one of a unidirectional composite. In media with continuous reinforcement (long fibres), the longitudinal behaviour (tension 11) appears to be linear elastic up to the material brittle failure due to fibres breakage. The transverse behaviour (tension 22 and/or in-plane shear 12) exhibits a more progressive degradation induced by the growth of a diffuse micro-crack network that initiates by debonding at the fibre/matrix interfaces and propagates by coalescence (Yang et al., 2020). To represent this behaviour, the constitutive model specifically developed for this type of materials (Praud, 2018; Praud et al., 2017b) is utilized to describe the response of the yarn phase. This model is also written within the framework of thermodynamics (Chatzigeorgiou et al., 2018; Germain et al., 1983; Lemaitre and Chaboche, 1990) while being based on a hybrid micromechanical–phenomenological formulation. Accordingly, the damage is introduced through a micromechanical description of a RVE containing a micro-crack density γ_c , as illustrated in Figure 7. Furthermore, in this type of material, damage is often accompanied by permanent strains caused by the non-closure effect of the micro-cracks. This aspect is phenomenologically described by an anelastic strain tensor $\boldsymbol{\varepsilon}_s$ that is added to the elastic part of the strain.

For the yarn phase, the state laws are based on the following form of the Helmholtz free energy potential

$$\rho\psi(\boldsymbol{\varepsilon}, \boldsymbol{\varepsilon}_s, \gamma_c) = \frac{1}{2}(\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_s) : [\mathbb{C}_0 - \mathbb{D}(\gamma_c)] : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_s) \quad (18)$$

This potential depends on the strain $\boldsymbol{\varepsilon}$, as observable state variable, and the internal state variables $\boldsymbol{\varepsilon}_s$ and γ_c representing the anelastic strain and the micro-crack density, respectively.

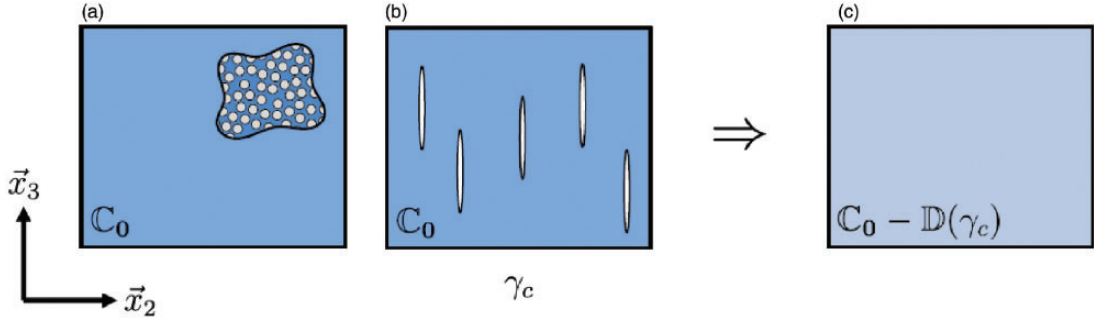


Figure 7. Damage definition in the yarn phase: (a) Initial state: transversely isotropic. (b) Damaged state: introduction of a micro-crack density γ_c (void volume fraction) in the RVE. (c) Evaluation of the stiffness reduction induced by γ_c by homogenization (Praud, 2018; Praud et al., 2017b).

Through the thermodynamical derivation, the stress in the yarn phase is expressed as

$$\boldsymbol{\sigma} = \rho \frac{\partial \psi}{\partial \boldsymbol{\varepsilon}} = [\mathbb{C}_0 - \mathbb{D}(\gamma_c)] : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_s) \quad (19)$$

The other associated variables related to the yarn phase are given by

$$-\boldsymbol{\sigma} = \rho \frac{\partial \psi}{\partial \boldsymbol{\varepsilon}_s}, \quad -Y_c = \rho \frac{\partial \psi}{\partial \gamma_c} \quad (20)$$

where, Y_c depicts the energy density release rate.

In equations (18) to (20), the initial stiffness tensor \mathbb{C}_0 , defined as transversely isotropic, is gradually lowered by the stiffness reduction tensor, denoted by $\mathbb{D}(\gamma_c)$. The latter is calculated as a function of the micro-crack density γ_c through the micromechanical scheme of Mori–Tanaka (Mori and Tanaka, 1973), where micro-cracks are idealized by quasi-flat ellipsoidal inclusions of void (with zero stiffness) whose normal is oriented along the second direction \vec{x}_2 (see Figure 7). Indeed, due to the microstructure arrangement in the yarns, the micro-cracks are forced to propagate in a plane parallel to the fibre direction \vec{x}_1 (Li et al., 2019). Moreover, by assuming that the yarns are mainly loaded in the plane (\vec{x}_1, \vec{x}_2) , the propagation plane of the micro-cracks necessarily becomes perpendicular to the second direction \vec{x}_2 and consequently always oriented in the same plane. Accordingly, it yields for the stiffness reduction tensor

$$\mathbb{D}(\gamma_c) = \gamma_c \mathbb{C}_0 : \mathbb{T}_c : \mathbb{A}_0(\gamma_c) \quad (21)$$

with

$$\mathbb{T}_c = (\mathbb{I} - \mathbb{S}_E)^{-1}, \quad \text{and} \quad \mathbb{A}_0(\gamma_c) = (\mathbb{I} + \gamma_c(\mathbb{T}_c - \mathbb{I}))^{-1} \quad (22)$$

where \mathbb{T}_c is the interaction tensor of the void inclusion, itself defined from the Eshelby's tensor \mathbb{S}_E (Eshelby, 1957). The latter is numerically evaluated (Gavazzi and Lagoudas, 1990) from the stiffness tensor of the reference medium, namely \mathbb{C}_0 , and the geometrical configuration of the void inclusion, which is the same as in Praud (2018) and Praud et al. (2017b). $\mathbb{A}_0(\gamma_c)$ designates the strain

localization tensor, which allows to define the local strain and stress fields, and more specially the ones in the virgin part of the material

$$\boldsymbol{\varepsilon}_0(\boldsymbol{\varepsilon}, \gamma_c, \boldsymbol{\varepsilon}_s) = \mathbb{A}_0(\gamma_c) : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_s), \quad \boldsymbol{\sigma}_0(\boldsymbol{\varepsilon}, \gamma_c, \boldsymbol{\varepsilon}_s) = \mathbb{C}_0 : \mathbb{A}_0(\gamma_c) : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_s) \quad (23)$$

In the yarns, the damage is driven by Hill-like quadratic interaction criterion (Hill, 1948; Ottosen and Ristinmaa, 2005) expressed from the stress in the virgin part of the material, namely $\boldsymbol{\sigma}_0$

$$H_c(\boldsymbol{\sigma}_0) = \sqrt{\boldsymbol{\sigma}_0 : \mathbb{H} : \boldsymbol{\sigma}_0} = \sqrt{\left(\frac{\sigma_{022}}{R_{22}}\right)^2 + \left(\frac{\sigma_{012}}{R_{12}}\right)^2} \quad (24)$$

where \mathbb{H} is a fourth-order tensor set in such a way that H_c only depends on the components 22 and 12 of $\boldsymbol{\sigma}_0$. \mathbb{H} contains the parameters R_{22} and R_{12} , which represent the initial damage thresholds in pure transverse tension and in pure in-plane shear, respectively. The development of the micro-crack density γ_c initiates only when H_c exceeds 1. After this stage, it follows a Weibull-like function g of the maximal value of H_c reached in the whole loading history, noted hereafter as $\sup(H_c)$. This gives

$$\gamma_c = g(\sup(H_c)) = \gamma_c^\infty \left[1 - \exp \left[- \left[\frac{\langle \sup(H_c) - 1 \rangle_+}{S} \right]^\beta \right] \right] \quad (25)$$

where S and β are material parameters. Additionally, γ_c^∞ depicts a saturation level that cannot be exceeded ($\gamma_c < \gamma_c^\infty$). Note that the development relationship (25) accounts well for the irreversible aspect of damage. Indeed, γ_c can only grow, $\dot{\gamma}_c > 0$ if $H_c = \sup(H_c)$, or remain constant, $\dot{\gamma}_c = 0$ if $H_c < \sup(H_c)$.

The proposed model for the yarn phase considers that the anelasticity occurs as permanent strains caused by the micro-cracks non-closure upon unloading. Thus, the anelastic strain $\boldsymbol{\varepsilon}_s$ evolves with the micro-crack density γ_c , making the two mechanisms directly coupled and simultaneously activated. This evolution is governed by the normality rule of an indicative function given by

$$F(\boldsymbol{\sigma}, Y_c) = H_s(\boldsymbol{\sigma}) + Y_c \quad (26)$$

with

$$H_s(\boldsymbol{\sigma}) = \sqrt{\boldsymbol{\sigma} : \mathbb{F} : \boldsymbol{\sigma}} = \sqrt{(a_{22}\sigma_{22})^2 + (a_{12}\sigma_{12})^2} \quad (27)$$

In the above two equations, $H_s(\boldsymbol{\sigma})$ is another quadratic interaction criterion, where the fourth-order tensor \mathbb{F} is set in such a way that H_s only depends on the components 22 and 12 of $\boldsymbol{\sigma}$. \mathbb{F} contains the parameters a_{22} and a_{12} , which are transverse tension and in-plane shear anelasticity parameters, respectively. Therefore, applying the normality of the indicative function $F(\boldsymbol{\sigma}, Y_c)$ gives the following evolution laws

$$\dot{\gamma}_c = \frac{\partial F}{\partial Y_c} \dot{\lambda} = \dot{\lambda} \quad (28)$$

$$\dot{\boldsymbol{\varepsilon}}_s = \frac{\partial F}{\partial \boldsymbol{\sigma}} \dot{\lambda} = \boldsymbol{\Lambda}_s(\boldsymbol{\sigma}) \dot{\gamma}_c, \quad \text{with} \quad \boldsymbol{\Lambda}_s(\boldsymbol{\sigma}) = \frac{\mathbb{F} : \boldsymbol{\sigma}}{H_s(\boldsymbol{\sigma})} \quad (29)$$

where λ is the damage-anelasticity multiplier, which appears to be equal to the micro-crack density γ_c ($\lambda = \gamma_c$) whose evolution is governed by the damage development relationship (25). Note that the form of $H_s(\boldsymbol{\sigma})$ implies that only the components 22 and 12 of $\boldsymbol{\epsilon}_s$ are active.

Note that the convexity of F given in equation (27), as well as the irreversibility aspect of γ_c through the damage development relationship (25), ensures the thermodynamical admissibility of the evolution laws (28) and (29).

Like for the matrix, the constitutive model of the yarns has also been implemented into the FE solver *ABAQUS/Standard* by means of UMAT. The numerical integration scheme is based on the ‘convex cutting plane’ form of the ‘return mapping algorithm’ (Ortiz and Simo, 1986; Simo and Hughes, 1998; Simo and Ortiz, 1985), which is described in Praud (2018) and Praud et al. (2017b) for this model. Readers are referred to these references for more details regarding the numerical implementation.

Remarks and discussion

In the matrix phase, damage is assumed to be isotropic through the scalar internal state variable D . However, it is worth mentioning that, even if in reality the matrix is assumed to be initially isotropic, its response may exhibit anisotropic effects induced by damage depending on the directions of the principal stresses. Although some modelling approaches can take such behaviour into account (Ayadi et al., 2018; Chaboche, 1992; Ekh et al., 2003; Lemaitre and Desmorat, 2005), this requires unconventional characterization highlighting the directional effects of damage. In the absence of such data, the isotropic idealization of damage remains the most appropriate assumption.

Unlike the matrix, the definition of damage in the yarn phase is anisotropic through the stiffness reduction tensor $\mathbb{D}(\gamma_c)$. Based on micromechanical relationships, this tensor depends on the internal state variable γ_c , which represents a density of micro-cracks whose normal is oriented along \vec{x}_2 (see Figure 7). It is recalled that this assumes that the yarns are mainly loaded in the plane (\vec{x}_1, \vec{x}_2) .

The constitutive model of the matrix phase is time-dependent whereas the one of the yarn phase is not. Since the yarns are composed of fibres and matrix, they should normally exhibit a time-dependent response inherited from the matrix they contain. However, in the studied woven composite, the amount of matrix within the yarns is relatively low (about 15%). Therefore, it is assumed that the behaviour of the yarns is idealized as time-independent as it is mostly driven by the fibres. This assumption also allows to reduce the number of parameters for the identification, which is the topic of the next section.

It is important to mention that the constitutive models utilized for the matrix and the yarn phases make use of local continuum damage theories for modelling the degradation mechanisms caused by micro-defects within the unit cell of the woven composite. Thus, the damage mechanisms are described according to continuum quantities (internal state variables). This allows to conveniently formulate the problem according to the theory of continuum mechanics. This works well as long as the materials do not reach the strain softening regime, which was well verified in all the examples considered in this study. In the contrary case, the use of non-local modelling theories (Kiefer et al., 2018; Miehe et al., 2010; Peerlings et al., 1996; Pijaudier-Cabot and Bazant, 1987; Seupel and Kuna, 2019) would be necessary to objectively represent the localization phenomena beyond the strain softening onset (Bazant, 1984; De Borst et al., 1993).

Moreover, the macro-scale and micro-scale equations are both expressed in the small strains formalism. In this paper, all the studied cases and the related results are performed and presented at moderate strain levels. However, it is worth noticing that the proposed multi-scale model cannot capture geometrical non-linearities such as micropolar or chiral effects (Kadic et al., 2019) that are

likely to occur at high strain levels in a woven microstructure. To account for these phenomena, the use of higher-order homogenization strategies (Forest, 2002; Goda et al., 2013; Goda and Ganghoffer, 2016; Larsson and Diebels, 2007) would be necessary. This would also require extending the local constitutive models of the matrix and the yarns to a large deformation formalism.

Identification and comparisons with experimental data

Experimental procedure and identification strategy

The matrix is identified from experiments directly performed on the unfilled polyamide 6–6, from specific experiments and a dedicated identification procedure, which are detailed in Praud (2018) and Praud et al. (2017b). The obtained parameters for the matrix are listed in Table 3. Note that polyamide and polyamide-based composites are well known to be highly sensitive to the environmental conditions (Arif et al., 2014; Launay et al., 2013; Malpot et al., 2015), especially the relative humidity (RH) and the temperature (T). In this work, the following environmental conditions were considered: $RH = 50\%$ and $T = 23^\circ\text{C}$ (room temperature) for both the studied composite and its unfilled polyamide 6–6 matrix.

Regarding the yarns, it is impossible to be separated from the matrix in order to perform mechanical tests on them. Consequently, the yarns parameters are identified from the macroscopic response of the entire woven composite through reverse techniques (Levenberg, 1944; Marquardt, 1963; Meraghni et al., 2011, 2014). Moreover, it is recalled that the behaviour of the yarns is assumed to be time-independent. Thus, for the multi-scale model, the overall time-dependency is driven exclusively by the rheology of the matrix phase. With this in mind, the parameters related to

Table 3. Identified parameters for the constitutive model of the matrix (polyamide 6–6).

Feature		Parameter	Value	Unit
Viscoelasticity	Single spring	E_e	2,731	MPa
		E_{v1}	8,766	MPa
	Kelvin–Voigt branch 1	η_{v1}	1,395	MPa.s
		$\tau_{v1} = \frac{\eta_{v1}}{E_{v1}}$	0.16	s
		E_{v2}	13,754	MPa
		η_{v2}	165,601	MPa.s
	Kelvin–Voigt branch 2	$\tau_{v2} = \frac{\eta_{v2}}{E_{v2}}$	12.04	s
		E_{v3}	15,010	MPa
		η_{v3}	457,955	MPa.s
		$\tau_{v3} = \frac{\eta_{v3}}{E_{v3}}$	30.51	s
	Kelvin–Voigt branch 3	E_{v4}	11,634	MPa
		η_{v4}	1,307,516	MPa.s
		$\tau_{v4} = \frac{\eta_{v4}}{E_{v4}}$	112.39	s
	Poisson ratio (standard value)		ν	0.3
Viscoplasticity coupled to damage	Yield threshold		R_0	4.86
	Hardening function	K	1,304.33	MPa
		n	0.674	–
		H	47.35	MPa.s ^m
	Viscous stress function	m	0.068	–
		S	21.607	MPa
		β	–1.105	–

the yarns are identified only from strain-controlled off-axis tests. Those tests are performed on $[\pm\theta]_s$ tensile laminated specimens³ (see Figure 8) repeatedly loaded and unloaded at progressively increasing stress levels and at a relatively slow strain rate (about $3.5 \times 10^{-3} \text{ s}^{-1}$) until failure. These tests, referred to as ‘quasi-static’, are performed with a servo-hydraulic tensile machine where the axial macroscopic strain $\bar{\epsilon}_{xx}$ is measured by means of an extensometer, while the axial macroscopic stress $\bar{\sigma}_{xx}$ is monitored by a load cell.

From these quasi-static tests, an optimization algorithm based on the Levenberg–Marquardt technique (Levenberg, 1944; Marquardt, 1963; Meraghni et al., 2011, 2014) is utilized to identify the parameters of the yarn phase. This is achieved by minimizing the least squares between the numerical and experimental macroscopic stress responses ($\bar{\sigma}_{xx}$). Beforehand, the initially transversely

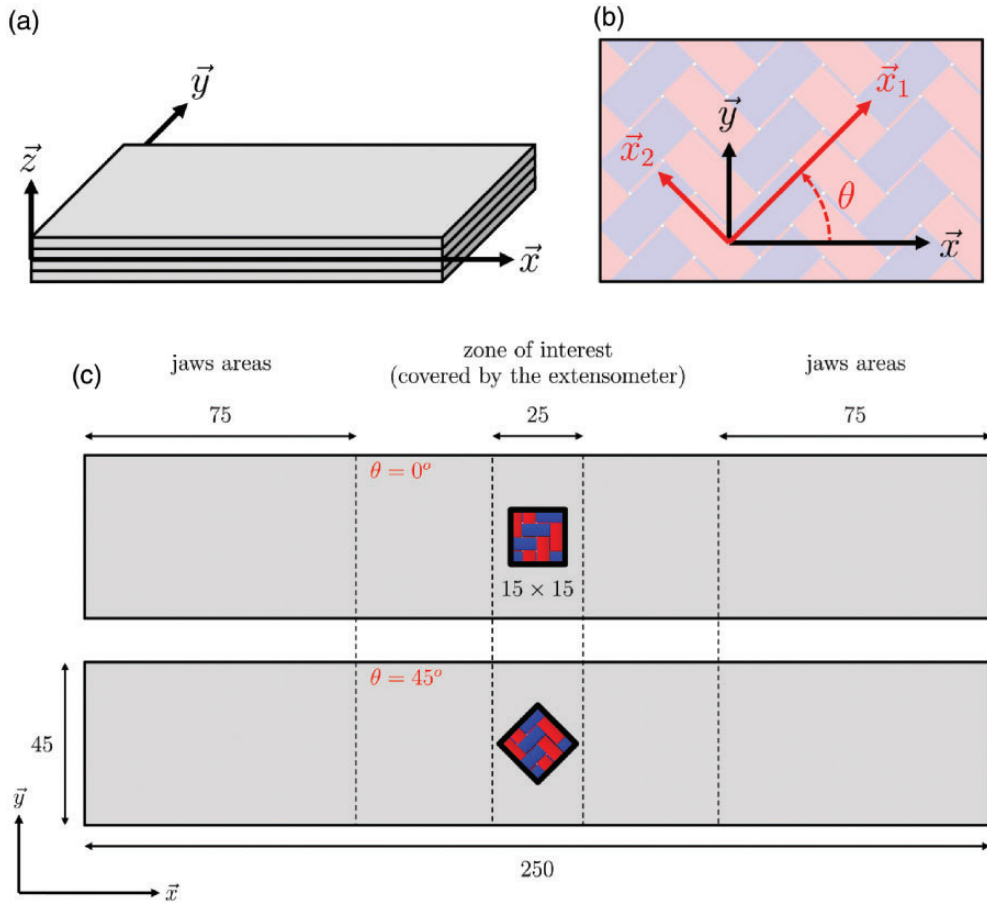


Figure 8. Tensile laminated specimens $[\pm\theta]_s$ axially loaded in the \vec{x} direction. During the tests, the axial macroscopic strain $\bar{\epsilon}_{xx}$ is measured by means of an extensometer, while the axial macroscopic stress $\bar{\sigma}_{xx}$ is monitored by a load cell. (a) Laminate: multi-layered composite; the thickness of a single layer is about 0.5 mm, making a total thickness of 2 mm for the whole laminated specimens. (b) Oriented layer: $(\vec{x}, \vec{y}, \vec{z})$ is the coordinate system of the laminate, while $(\vec{x}_1, \vec{x}_2, \vec{x}_3)$ is the material one within a single layer. (c) Geometry and adopted dimensions of the laminated specimens (dimensions in mm), rectangular specimens with large enough dimensions were considered to obtain experimental data that are reasonably representative of the macroscopic response of the composite.

isotropic stiffness of the yarns (C_0) is estimated by means of linear periodic homogenization (Praud, 2018). Therefore, only the parameters related to the damage and the anelasticity in the yarns are identified through the reverse engineering procedure. However, during the identification, the micro-crack saturation parameter γ_c^∞ is kept fixed at a sufficiently high level so that it is never reached and only the ascending part of the Weibull function (25) is acting (Praud, 2018; Praud et al., 2017b). In this manner, the identification remains well conditioned and robust. The obtained values of the yarns parameters are listed in Table 4.

Once all parameters are identified, the predictions obtained with the multi-scale model are compared with additional experimental data, where the laminated specimens are subjected to a sinusoidal stress signal oscillating at a frequency of 1 Hz during 100 s, i.e. 100 cycles. These tests are referred to as cyclic. Under cyclic loading, thermoplastic-based composites may exhibit a significant temperature increase due to the self-heating phenomenon, caused by the dissipation (Benaarbia et al., 2014, 2015; Praud, 2018). For this reason, during the cyclic tests, thermal measurements were carried out by means of an IR thermal camera.

Results and comparisons with experimental data

Figure 9(a) to (d) shows the numerical simulations provided by the multi-scale model and the experimental data for the quasi-static tests performed with the $[0^\circ]_4$, $[\pm 15^\circ]_s$, $[\pm 30^\circ]_s$ and $[\pm 45^\circ]_s$ specimens, respectively. It is recalled that these tests were used for the identification. First of all, it is observed that the response of the $[0^\circ]_4$ specimen is quasi-elastic, as only a small amount of apparent damage and anelasticity are generated before the composite brutally fails at a relatively high stress level (about 430 MPa). On the contrary, for the $[\pm 45^\circ]_s$ specimen, the response is much more ductile and no failure occurs at the end of the test. For the $[\pm 15^\circ]_s$, $[\pm 30^\circ]_s$ specimens, the composite exhibits an intermediate response between the ones observed with the $[0^\circ]_4$ and $[\pm 45^\circ]_s$. This important difference of behaviour for the different layers angles brings out the strong anisotropy induced by the microstructure which is, overall, well captured by the multi-scale model. Indeed, for the $[0^\circ]_4$, $[\pm 15^\circ]_s$ and $[\pm 30^\circ]_s$ specimens, the simulated quasi-static responses are in very good agreement with the experiments (see Figure 9(a) to (c)). For the $[\pm 45^\circ]_s$ specimen, the multi-scale model

Table 4. Identified parameters for the constitutive model of the yarns. The initial stiffness properties of the yarns were estimated by means of linear periodic homogenization.

Feature	Parameter	Value	Unit
Transversely isotropic stiffness tensor (non-null components)	C_{01111}	65,822	MPa
	$C_{01122} = C_{01133}$	7,041	MPa
	$C_{02222} = C_{03333}$	23,947	MPa
	C_{02233}	6,971	MPa
	$C_{01212} = C_{01313}$	8,661	MPa
	$C_{02323} = \frac{1}{2}(C_{02222} - C_{02233})$	8,488	MPa
Pure transverse tension threshold	R_{22}	20.0	MPa
Pure in-plane shear threshold	R_{12}	7.5	MPa
Weibull length parameter	S	12.3	—
Weibull exponent parameter	β	2.75	—
Micro-cracks saturation (fixed)	γ_c^∞	0.025	—
Transverse tension anelasticity parameter	a_{22}	3.60	—
In-plane shear anelasticity parameter	a_{12}	2.15	—

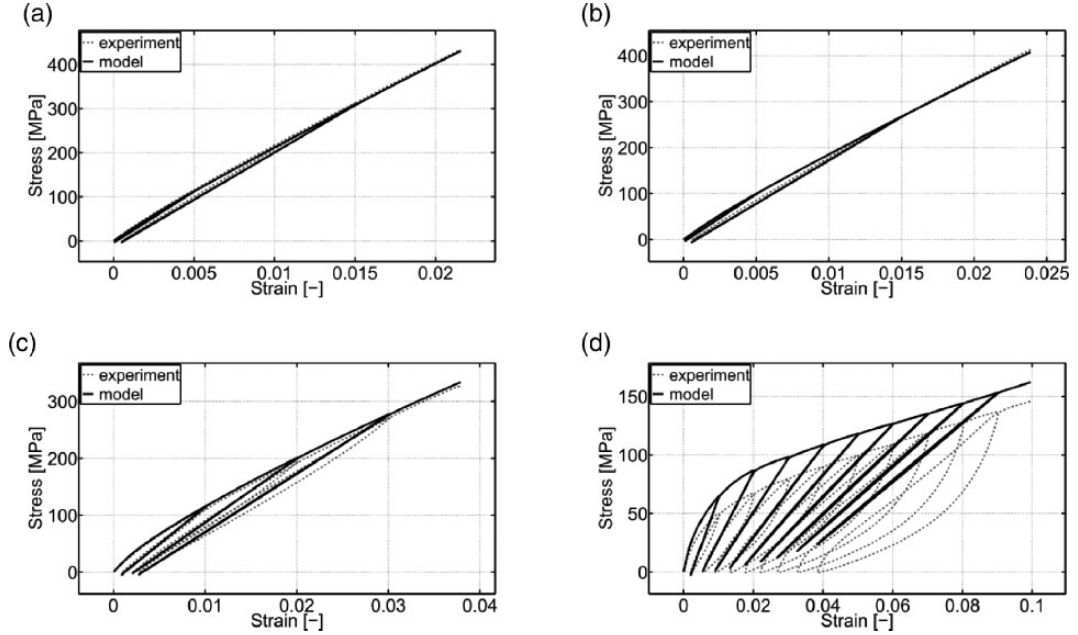


Figure 9. Quasi-static tests for the $[0]_4$, $[\pm 15]_s$, $[\pm 30]_s$ and $[\pm 45]_s$ laminated specimens. These data were used for the identification. (a) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\epsilon}_{xx}$) for the $[0]_4$ laminated specimen. (b) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\epsilon}_{xx}$) for the $[\pm 15]_s$ laminated specimen. (c) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\epsilon}_{xx}$) for the $[\pm 30]_s$ laminated specimen. (d) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\epsilon}_{xx}$) for the $[\pm 45]_s$ laminated specimen.

overestimates the quasi-static response (see Figure 9(d)), retaining though the same order of stress levels and a similar tendency. The deviation of the present model may be caused by not accounting for other damage mechanisms occurring under significant in-plane shear stress levels, like for instance the debonding at the yarns/matrix interface.

Figures 10 and 11 show the predictions provided by the multi-scale model and the experimental data obtained for the stress-controlled cyclic tests performed with the $[0]_4$ and $[\pm 45]_s$ laminated specimens, respectively. These tests were not used for the identification. It is noted that the $[0]_s$ specimen was loaded at a maximum stress level which corresponds to about 80% of the quasi-static failure point. For the $[\pm 45]_s$ specimens, as the response is much more ductile, a maximum stress level of 95 MPa is taken instead, in order to keep a moderate strain amplitude. The failure occurred after 80 cycles for the $[0]_4$ specimen, while for the $[\pm 45]_s$ no failure appeared before the completion of the 100 cycles. When the composite is subjected to a cyclic loading, phenomena directly inherited from the viscous and damage mechanisms of the matrix phase can be clearly observed, namely, the accumulation of strain accompanied by a progressive stiffness reduction. According to the layers angles, the amplitudes of these phenomena are quite different and, once more, bring out the anisotropy induced by the microstructure. Overall, similar tendencies are predicted by the multi-scale model, compared to the experimental results. The macroscopic strain responses are in relatively good agreement for the $[0]_4$ specimen, while the overall accumulation of strain and damage is underestimated for the $[\pm 45]_s$ specimen.

Moreover, it is worth pointing out that the hysteresis loops upon the loading/unloading stages of each single cycle are not well reproduced by the multi-scale model, especially for the $[\pm 45]_s$

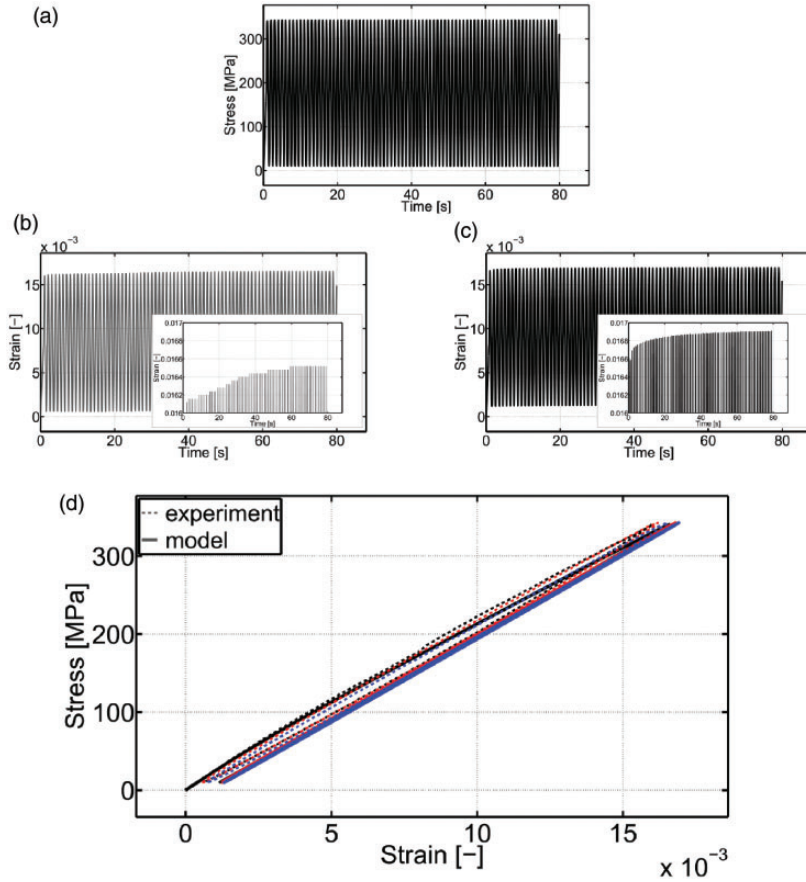


Figure 10. Cyclic test: 100 cycles performed at 1 Hz for the $[0^\circ]_4$ laminated specimen. These data were not used for the identification. (a) Applied stress ($\bar{\sigma}_{xx}$) vs. time. (b) Experimental strain response ($\bar{\varepsilon}_{xx}$) vs. time. (c) Simulated strain response ($\bar{\varepsilon}_{xx}$) vs. time. (d) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\varepsilon}_{xx}$) for the 1st, 10th and 79th cycles, represented in black, red and blue, respectively.

laminated specimen (see Figure 11). This is likely due to the sub-model of the yarn phase, which, unlike the one of the matrix, does not integrate any viscoelastic mechanism and time-dependent features in general. Moreover, from the thermal measurements (see Figure 12(a) and (b)), it can be observed that, while the self-heating is relatively limited for the $[0^\circ]_4$ specimen (about 3°C of temperature increase), this phenomenon becomes important for the $[\pm 45^\circ]_s$ specimens (about 10°C of temperature increase). This can also explain the deviation between the experimental data and the model (see Figure 11), which assumes isothermal conditions in the present case.

Macroscopic response of the woven composite

In order to provide a better understanding of the multi-scale model, additional examples of simulations carried out on a single macroscopic material point, so-called virtual tests, are performed. In these examples, the parameters previously identified for the matrix and the yarns in Tables 3 and 4 are utilized. The composite is subjected to several loading configurations: warp tension, in-plane

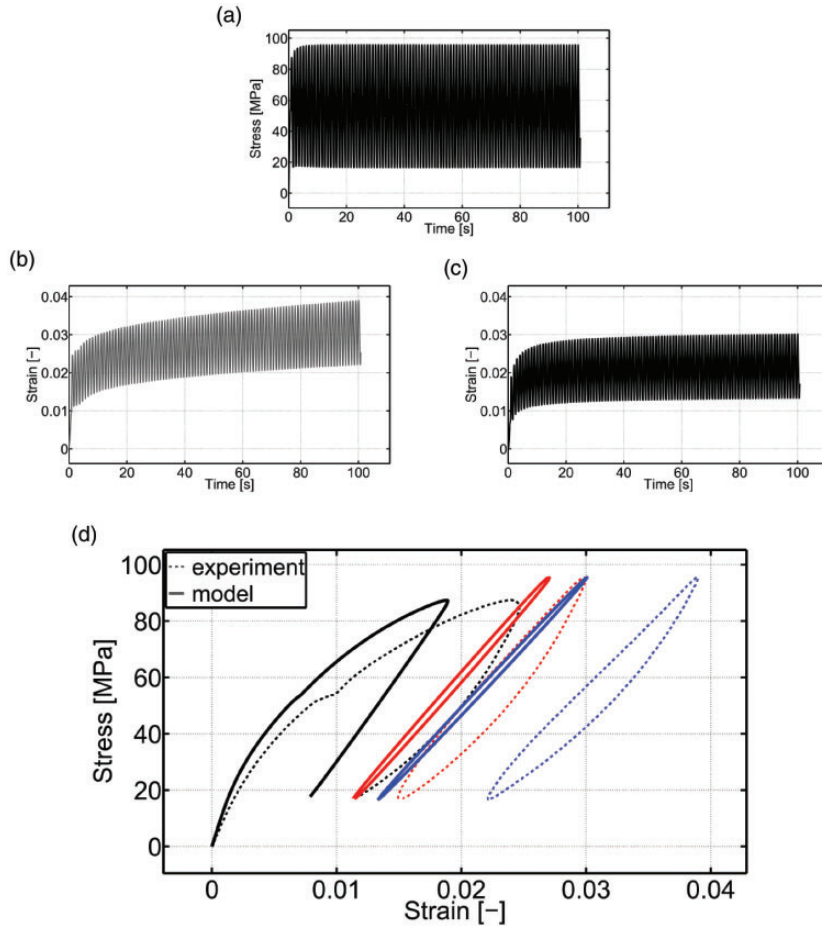


Figure 11. Cyclic test: 100 cycles performed at 1 Hz for the $[\pm 45^\circ]_s$ laminated specimen. These data were not used for the identification. (a) Applied stress ($\bar{\sigma}_{xx}$) vs. time. (b) Experimental strain response ($\bar{\varepsilon}_{xx}$) vs. time. (c) Simulated strain response ($\bar{\varepsilon}_{xx}$) vs. time. (d) Stress ($\bar{\sigma}_{xx}$) vs. strain ($\bar{\varepsilon}_{xx}$) for the 1st, 10th and 100th cycles, represented in black, red and blue, respectively.

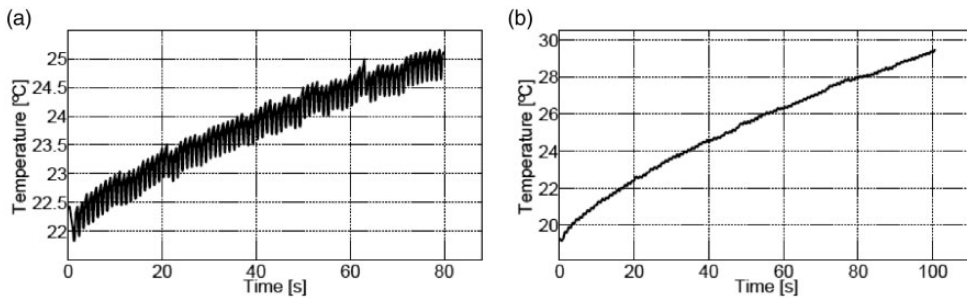


Figure 12. Temperature elevation measured during the cyclic tests for the $[0^\circ]_4$ and $[\pm 45^\circ]_s$ laminated specimens. (a) Temperature (T) vs. time for the $[0^\circ]_4$ laminated specimen. (b) Temperature (T) vs. time for the $[\pm 45^\circ]_s$ laminated specimen.

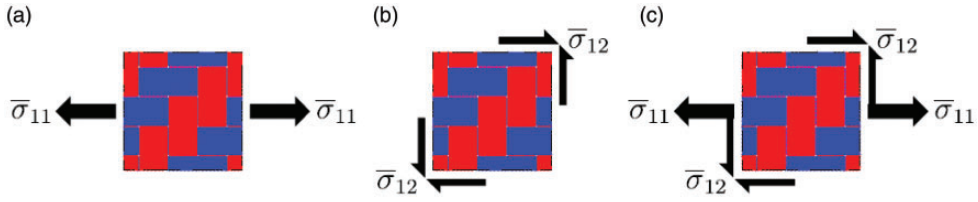


Figure 13. Illustrations of the simulated loading configurations. (a) Warp tension. (b) In-plane shear. (c) Combined warp tension and in-plane shear.

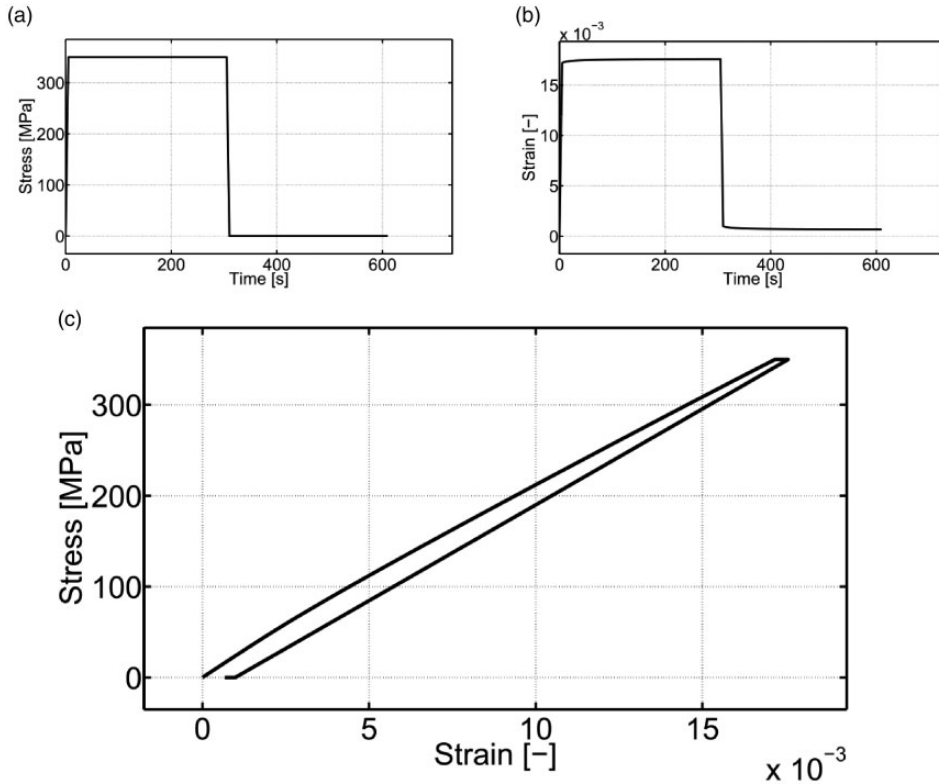


Figure 14. Macroscopic response of the composite for the creep and strain recovery in warp tension ‘virtual test’. (a) Applied stress ($\bar{\sigma}_{11}$) vs. time. (b) Strain response ($\bar{\epsilon}_{11}$) vs. time. (c) Stress ($\bar{\sigma}_{11}$) vs. strain ($\bar{\epsilon}_{11}$).

shear and combined warp tension and in-plane shear stress states, as illustrated in Figure 13(a) to (c), respectively. These loading configurations are applied according to different paths including, creep and strain recovery in warp tension and in in-plane shear, and non-proportional combined warp tension and in-plane shear.

Creep and strain recovery

In the creep and strain recovery in warp tension ‘virtual test’, a normal stress $\bar{\sigma}_{11}$ of 350 MPa is first applied on the composite in 5 s. This stress is then held for 300 s before returning back to zero in 5 s.

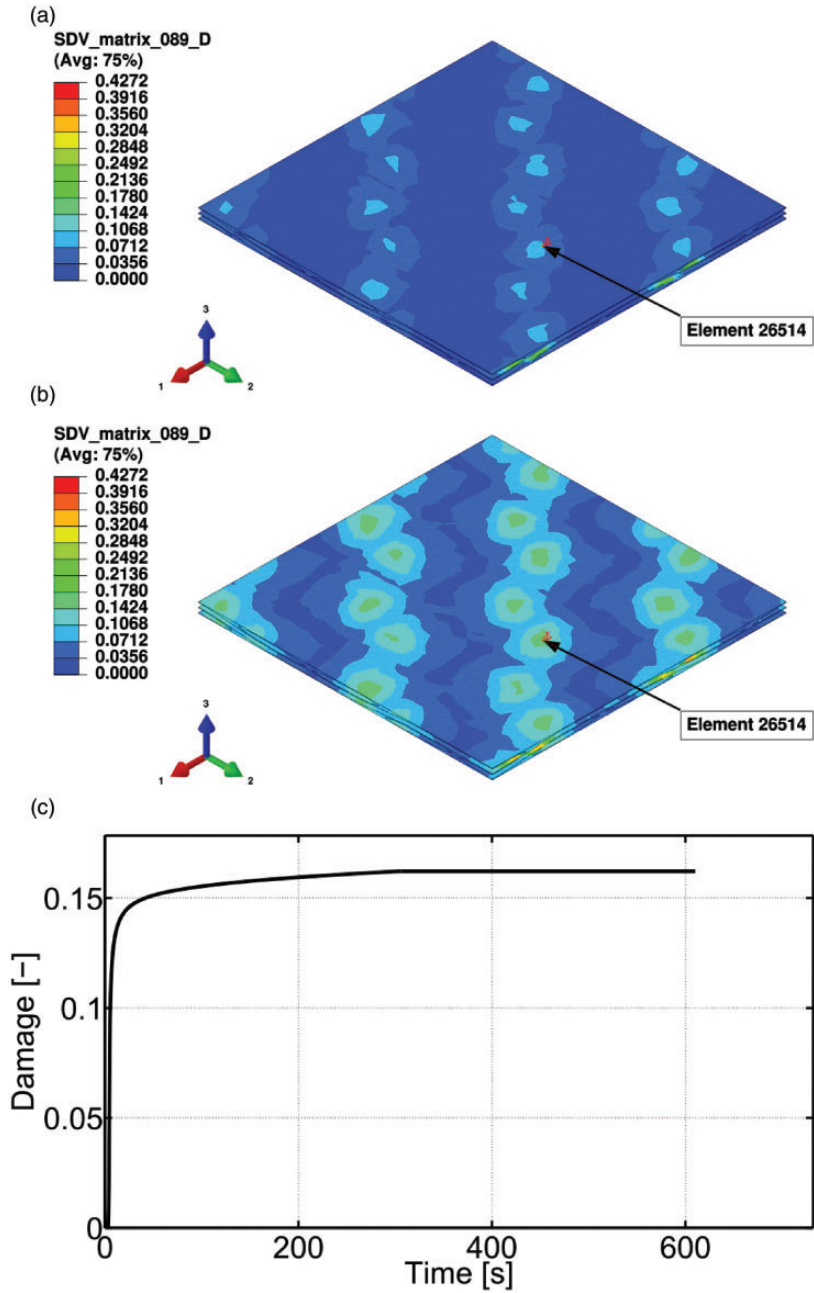


Figure 15. Local damage fields (D) in the matrix for the creep and strain recovery in warp tension 'virtual test', presented in Figure 14. (a) Damage (D) in the matrix at the end of the loading stage ($t = 5$ s). (b) Damage (D) in the matrix at the end of the creep stage ($t = 305$ s). (c) Damage (D) in the matrix, for the element 26514 marked above.

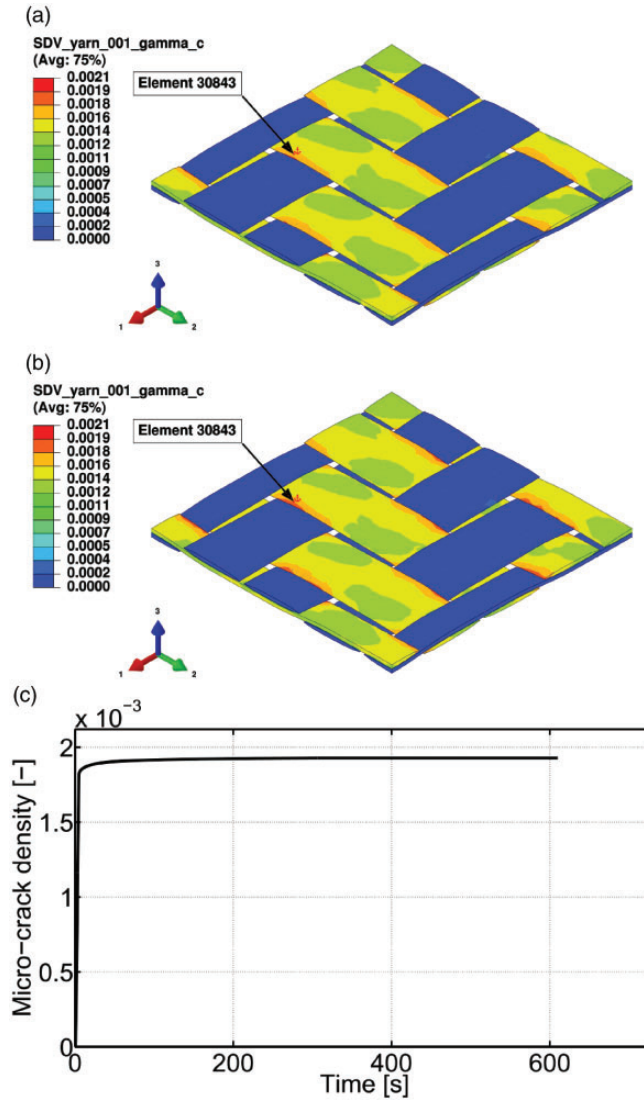


Figure 16. Local micro-crack density fields (γ_c) in the yarns for the creep and strain recovery in warp tension ‘virtual test’, presented in Figure 14. (a) Micro-crack density (γ_c) in the yarns at the end of the loading stage ($t = 5$ s). (b) Micro-crack density (γ_c) in the yarns at the end of the creep stage ($t = 305$ s). (c) Micro-crack density (γ_c) in the yarns, for the element 30843 marked above.

In the final stage, the composite is kept at zero stress for another 300 s (see Figure 14(a)). The results of this ‘virtual test’ are presented in Figures 14 to 16. In the case of the creep and strain recovery in-plane shear, a shear stress $\bar{\sigma}_{12}$ of 40 MPa is applied on the composite with the same loading path as for the warp tension (see Figure 17(a)). The results of this ‘virtual test’ are presented in Figures 17 to 19.

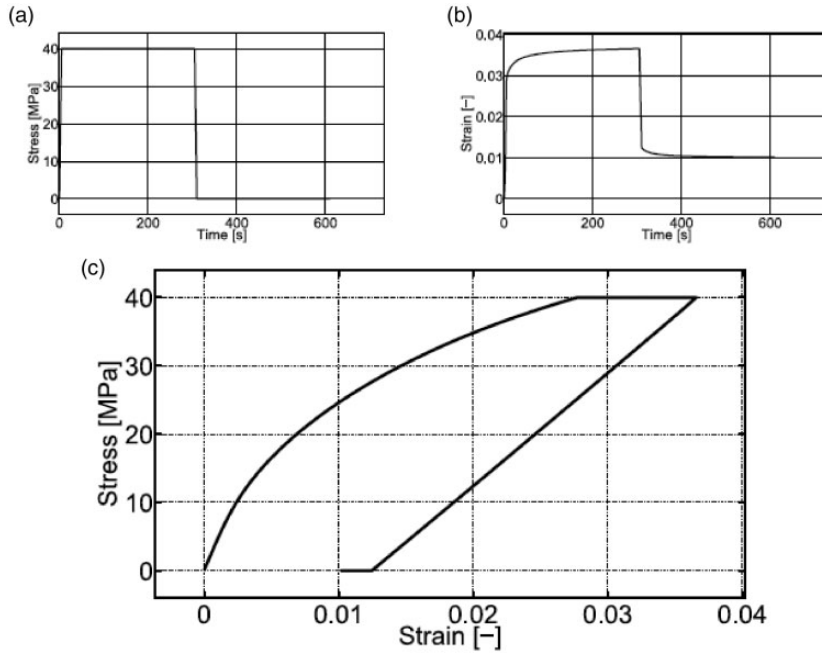


Figure 17. Macroscopic response of the composite for the creep and strain recovery in in-plane shear ‘virtual test’. (a) Applied stress ($\bar{\sigma}_{12}$) vs. time. (b) Strain response ($2\bar{\epsilon}_{12}$) vs. time. (c) Stress ($\bar{\sigma}_{12}$) vs. strain ($2\bar{\epsilon}_{12}$).

When the composite is loaded in the warp direction ($0 \text{ s} < t < 5 \text{ s}$), most of the load is carried by the warp yarns in their longitudinal direction. Meanwhile, a small part of this load is also carried by the weft yarns in their transverse direction. This brings about the occurrence of micro-cracks only in these yarns (see Figure 16(a)). In the matrix, most of the stresses are concentrated in the yarns-crossing areas, leading to the development of some damage in these locations (see Figure 15(a)). The degradations occurring in the weft yarns and in the matrix seem to have limited consequences at the macroscopic scale, as most of the load is carried by the warp yarns in their longitudinal direction, which behave elastically with an important stiffness. For this reason, the response of the composite at the macroscopic scale remains quasi-linear during the first loading stage (see Figure 14(c)).

When the composite is loaded in in-plane shear ($0 \text{ s} < t < 5 \text{ s}$), most of the load is carried by the yarns in in-plane shear. This brings about a fast growth of the micro-cracking in both warp and weft yarns (see Figure 19(a)). Then, the overall load is progressively transferred to the matrix, in the inter-yarns areas, where the stresses are mainly concentrated and where damage develops (see Figure 18(a)). Note that those degradation mechanisms have a significant influence on the macroscopic in-plane shear response of the composite, which appears to be more matrix-dominated and strongly non-linear (see Figure 17(c)).

Note that identical degradation mechanisms were experimentally observed by means of X-ray computed micro-tomography for a similar thermoplastic-based woven composite (Pomarède et al., 2018).

During the creep stages, when the stress is held ($5 \text{ s} < t < 305 \text{ s}$), the macroscopic strain increases under the action of a constant macroscopic stress (see Figures 14(b) and (c), 17(b) and (c)). The macroscopic creep response of the composite is caused by the time-dependent behaviour of the

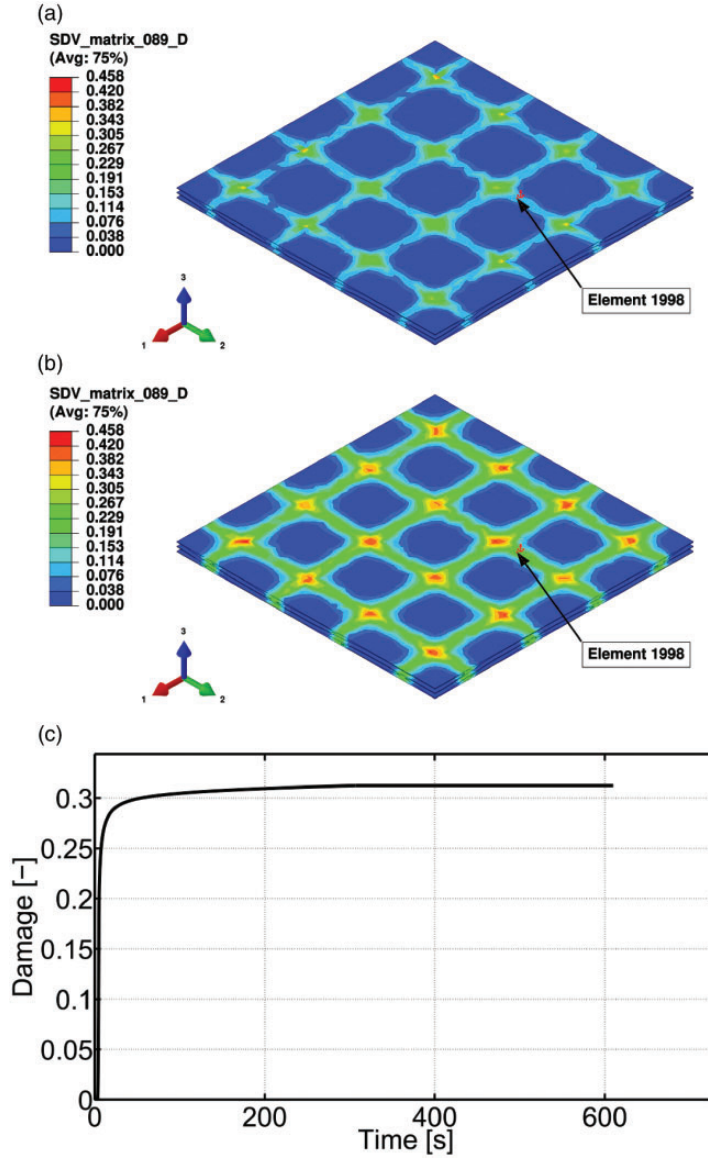


Figure 18. Local damage fields (D) in the matrix for the creep and strain recovery in in-plane shear ‘virtual test’, presented in Figure 17. (a) Damage (D) in the matrix at the end of the loading stage ($t = 5$ s). (b) Damage (D) in the matrix at the end of the creep stage ($t = 305$ s). (c) Damage (D) in the matrix, for the element 1998 marked above.

matrix phase, as well as the microstructure interactions between the matrix and the yarn phases. Although the sub-model of the yarns does not account for any time-dependent feature, a micro-crack density growth is observed within the yarn phase (see Figures 16 and 19). Indeed, when the matrix locally creeps and gets damaged, a part of its sustained load is gradually transferred to the yarns, leading to an increase of the micro-crack density in this phase. Moreover, in warp tension,

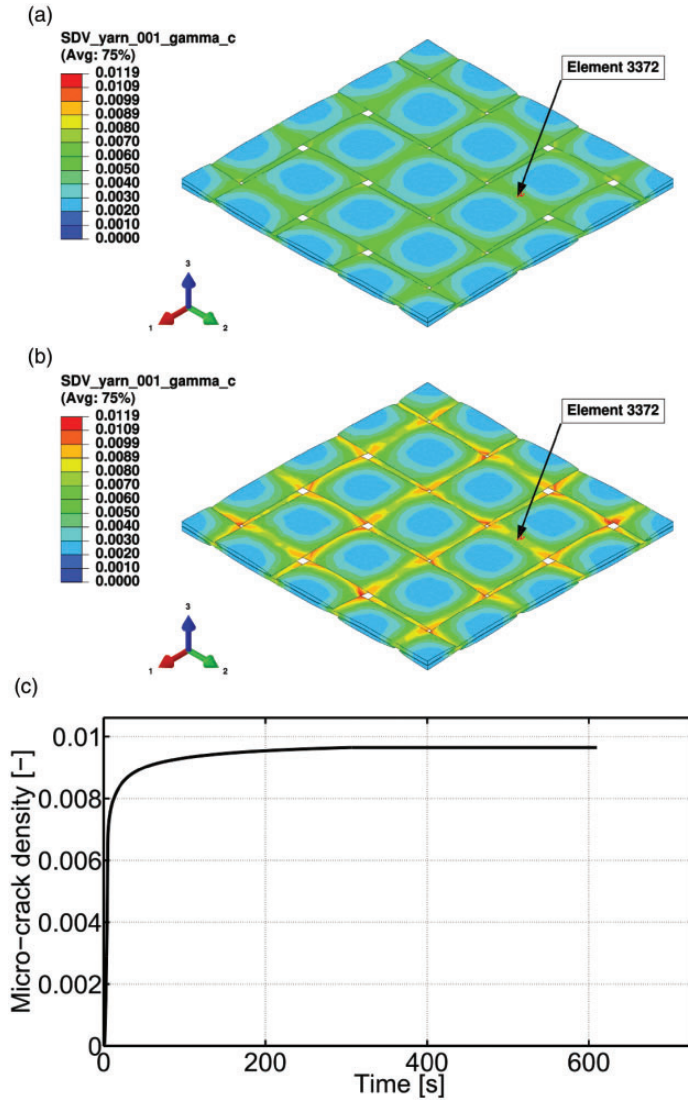


Figure 19. Local micro-crack density fields (γ_c) in the yarns for the creep and strain recovery in in-plane shear ‘virtual test’, presented in Figure 17. (a) Micro-crack density (γ_c) in the yarns at the end of the loading stage ($t = 5$ s). (b) Micro-crack density (γ_c) in the yarns at the end of the creep stage ($t = 305$ s). (c) Micro-crack density (γ_c) in the yarns, for the element 3372 marked above.

the macroscopic creep is quite low, in contrast to the in-plane shear. Indeed, in the latter case, the behaviour of the composite is mainly matrix-dominated.

Non-proportional combined warp tension and in-plane shear

In these examples, the composite is subjected to a combined warp tension and in-plane shear stress state, which is applied through two different loading paths having the same amplitudes. In the first

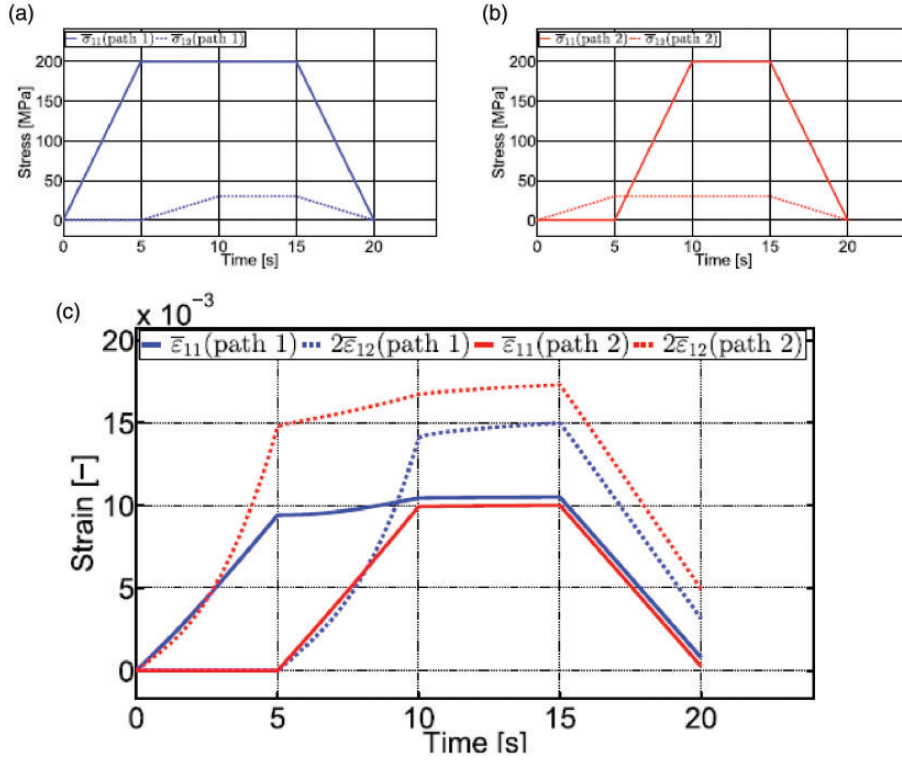


Figure 20. Macroscopic response of the composite for the non-proportional combined warp tension and in-plane shear ‘virtual tests’. (a) Path 1: applied stresses ($\bar{\sigma}_{11}$ and $\bar{\sigma}_{12}$) vs. time. (b) Path 2: applied stresses ($\bar{\sigma}_{11}$ and $\bar{\sigma}_{12}$) vs. time. (c) Paths 1 and 2: strain responses ($\bar{\epsilon}_{11}$ and $2\bar{\epsilon}_{12}$) vs. time.

loading path, referred to as path 1, a normal stress in the warp direction $\bar{\sigma}_{11}$ of 200 MPa is first applied in 5 s. In the next stage, $\bar{\sigma}_{11}$ is held constant, while an in-plane shear stress $\bar{\sigma}_{12}$ of 30 MPa is applied in 5 s. Afterwards, both $\bar{\sigma}_{11}$ and $\bar{\sigma}_{12}$ are held constant for 5 s before being released in another 5 s (see Figure 20(a)). In the second loading path, referred to as path 2, the normal and shear stresses are interchanged with respect to the path 1 (see Figure 20(b)).

The results of these simulations are presented in Figure 20. These ‘virtual tests’ highlight the importance of the loading path when the composite is subjected to combined stress states. Although the same stress amplitudes are applied for both paths 1 and 2, it can be noticed that the amplitudes of the strain responses are quite different (see Figure 20(c)). The maximum value of the normal strain $\bar{\epsilon}_{11}$ resulting from the path 1 is slightly greater than the one obtained from the path 2. Indeed, the normal stress $\bar{\sigma}_{11}$ is held longer for the path 1 than for the path 2, which means that the composite is exposed for more time to creep in the warp direction. Similarly, the maximum value of the in-plane shear strain $2\bar{\epsilon}_{12}$ resulting from the path 2 is far greater than the one obtained from the path 1. This time, the in-plane shear stress $\bar{\sigma}_{12}$ is held longer for the path 2 than for the path 1 and, consequently, the composite has more time to creep in in-plane shear. The difference in the strain amplitudes is much more important in in-plane shear, as in this case the behaviour of the composite is more matrix-dominated and therefore exhibits more creep.

Conclusions and perspectives

In this work, a multi-scale model is employed to describe the cyclic and time-dependent behaviour of thermoplastic-based woven composites. This effort has succeeded to combine advanced sub-models including viscoelastic, viscoplastic and damage deformation mechanisms in a robust fully integrated multi-scale modelling strategy, which is the main novelty of this work. The overall good agreements between the simulations and the experiments demonstrate the capabilities of the multi-scale model to capture the anisotropic response of the composite induced by the microstructure, as well as the time-dependent effects inherent to the thermoplastic matrix. Besides analyzing the influence of the local deformation processes on the macroscopic behaviour, these examples also highlight the capacity of the developed model to capture the effect of the loading path, considering either proportional or non-proportional conditions. The proposed multi-scale model has the strong advantage to be entirely modular and applicable to any type of composites with periodic microstructure. Furthermore, this modularity enables the multi-scale model to be easily enhanced with even more advanced sub-models that might be developed in the future.

Among the main perspectives of this work, the present multi-scale model could be implemented into the FE² computational scheme (Asada and Ohno, 2007; Feyel, 2003; Tchalla et al., 2013; Tikarrouchine et al., 2018, 2019), for performing large-scale structure analyses. In a computationally cheaper strategy, the multi-scale model could also be utilized to generate a ‘virtual tests’ in a view of identifying purely phenomenological models for the composite (Achour, 2017; Garoz et al., 2017; Sodhani et al., 2018). Another perspective would be to extend the proposed multi-scale model to fully coupled thermomechanical analyses (Chatzigeorgiou et al., 2016, 2018; Tikarrouchine et al., 2019). This would allow accounting for the self-heating phenomenon, which may be an important aspect, especially under cyclic loading. Such analyses would require the local constitutive models to account for the heat produced by the mechanical work through a proper thermodynamical formalism (Benaarbia et al., 2019; Krairi et al., 2019; Mouelle et al., 2020; Yu et al., 2017).

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Notes

1. Note that the use of periodic boundary conditions requires the mesh of the unit cell to be well periodic. This means that for each boundary surface node, there must be another node at the same relative position on the opposite boundary surface.
2. The operators $\text{eq}(\boldsymbol{\sigma})$ designate the equivalent Von Mises stress. Additionally, $\text{Dev}(\boldsymbol{\sigma})$ and $\text{hyd}(\boldsymbol{\sigma})$ depict the deviatoric and the hydrostatic parts of a stress tensor $\boldsymbol{\sigma}$, respectively. They are all defined by
$$\text{eq}(\boldsymbol{\sigma}) = \sqrt{\frac{3}{2}(\text{Dev}(\boldsymbol{\sigma}) : \text{Dev}(\boldsymbol{\sigma}))}, \quad \text{Dev}(\boldsymbol{\sigma}) = \boldsymbol{\sigma} - \text{hyd}(\boldsymbol{\sigma})\mathbf{I}, \quad \text{hyd}(\boldsymbol{\sigma}) = \frac{1}{3}\text{tr}(\boldsymbol{\sigma}).$$
3. It is noted that in $[\pm\theta]_s$ tensile laminated specimens, neither tension-shear nor tension-bending couplings appear. So, the laminates can be axially loaded in the \vec{x} direction without generating any unsuitable shear deformations or curvatures.

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