Tensile response of the muscle-tendon complex using Discrete Element Model

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1. Introduction

Tear of the muscle-tendon complex (MTC) is one of the main causes of sport injuries (De Labareyre et al. 2005). However, the mechanisms leading to such injury are still unclear (Uchiyama et al. 2011). Before modeling the tear of the MTC, its behavior in tensile test will be first studied. The MTC is a multi-scale, non isotropic and non continuous structure that is composed of numerous fascicles gathered together in a conjunctive sheath (epimysium). Many MTC models use the Finite Element Method (FEM) (Bosboom et al. 2001) to simulate MTC’s behavior as a hyperviscoelastic material. The Discrete Element Method (DEM) used for modeling composite materials (Iliescu et al. 2010) could be adapted to fibrous materials as the MTC. Compared to FEM, the DEM could allow to capture the complex behavior of a material with a simple discretization scheme in terms of concept and implementation as well as to understand the influence of fibers’ orientation on the MTC behavior. The aim of this study was to obtain the force/displacement relationship during a numerical tensile test of a pennate muscle model with DEM.

2. Material and Methods

Geometrical construction with DEM

The MTC model was built with the GranOO (Granular Object Oriented) software, developed at the Mechanics Institute of Bordeaux (I2M) by J.L. Charles et al. Fibers were constructed with spherical discrete elements linked by springs. The extra cellular matrix (ECM) was created by springs between fibers, in longitudinal and transversal directions. Tendons of the MTC were composed of fibers with links between them to create sliding. Those tendon’s fibers presented the same architecture as muscle’s fibers and they were composed of the same material as epimysium. The myo-tendinous junction was constructed by multilinks between tendon and muscle to respect the finger-like insertion (Turrina et al. 2013) (Figure 1).

Mechanical properties

Young’s modulus values of the MTC’s components were retrieved from the literature to model the microscopic stiffness of each spring (Table 1). The stiffness of each element was related to discrete elements’ cross-sectional area, initial length of links and structure’s Young’s modulus. Myo-tendinous junction’s Young’s modulus was supposed to be a compromising value between Young’s moduli of muscle and tendon. ECM’s Young’s modulus was also fixed.

<table>
<thead>
<tr>
<th>MTC Components</th>
<th>Young’s Modulus (MPa)</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fiber</td>
<td>28.2</td>
<td>Lieber et al. 2003</td>
</tr>
<tr>
<td>Tendon</td>
<td>800</td>
<td>Matschke et al. 2013</td>
</tr>
<tr>
<td>Extra Cellular Matrix</td>
<td>100</td>
<td>/</td>
</tr>
<tr>
<td>Myo-Tendinous Junction</td>
<td>300</td>
<td>/</td>
</tr>
</tbody>
</table>

3. Results and Discussion

The force/displacement curve could be divided into two parts. In the first part, the force was approximately null. It was due to the alignment and the orientation of all muscle’s fiber with the tensile axis which was the main axis of the MTC. The second part showed the hyper-elastic behavior of the stretching MTC, with a gap of 2N in order to fit with in vitro experimental data of Gras et al. (2012) over the sternocleidomastoid muscle (SCM) (Figure 2). MTC architectural parameters are computed regarding in vitro SCM data from Gras et al. (2012), except for pennation angle which has been arbitrary chosen at 45°.

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The force/displacement computed curve’s shape was in agreement with experimental ones despite a 50 times higher value. This difference could be attributed to the chosen values of mechanical properties of MTC’s components, which were not adapted to our model. Values of mechanical properties should be adjusted in order to fit with experimental data. Furthermore, we used Young’s modulus from patellar tendon (Matschke et al. 2013) which could be not directly applied to SCM tendon. In addition, we have made hypothesis about mechanical properties on the ECM (one of the main components of the MTC) and the myo-tendinous junction, due to the lack of data in the literature which could lead to those differences. The variation of the pennation angle during the tensile test was in agreement with the literature since during a passive muscle stretching, the pennation angle decreased, allowing a greater alignment between fibers and the muscle axis (Zhao et al. 2011). The variation of the volume of the MTC, calculated during the simulation, was less than 1%, as previously described in the literature. This confirms the incompressibility property of MTC thanks to springs’ properties in DEM.

4. Conclusions

The DEM seems to be a promising method to model the Muscle-Tendon Complex. The shape of numerical curve was in agreement with the experimental ones confirming the possibility to model the hyper-elastic macroscopic response of the muscle with simple elastic microscopic elements. The next step will be to adjust the numerical model in regard to the literature and to add viscoelastic properties in the MTC components. Furthermore, the study of the stress inside a cross-sectional area of muscle and tendon during the tensile test will help to detect where the MTC tear is most likely to occur.

References


