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Thermo-mechanical characterization of the Ti17 titanium alloy under extreme loading conditions

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Abstract Understanding the physics of chip formation in machining operations is often difficult due to the complexity of the phenomena involved, such as the extreme and complex loading conditions that occur in the cutting zone. In order to model the machining process, it is necessary to use a constitutive behavior law that is capable of reproducing as accurately as possible the behavior of the material under these extreme conditions. In this context, this paper presents a study of the mechanical behavior of the Ti17 titanium alloy at high strain rates and high temperatures. This has been achieved by undertaking compression and shear tests over a wide range of strain rates (from 10^{-1} s^{-1} to 100 s^{-1}) and temperatures (from 25 to 800 °C). The results show that the Ti17 alloy is sensitive to strain rate, especially for strain rates greater than 1 s^{-1} . In addition, the alloy retains good mechanical properties at high temperature (up to 500 °C). Based on the experimental results, the parameter of the Johnson-Cook constitutive equation have been identified using the inverse method. Some weaknesses in the model have been highlighted after the identification phase, especially in terms of the m and C parameters. A modification of the model has been proposed.

Keywords High strain rate · High temperature · Johnson-Cook · Characterization · Titanium alloy · Machining

1 Introduction

Titanium alloys are known for their excellent mechanical properties, even at high temperatures, and for their very good strength to weight ratio. This explains the diverse fields of application for these alloys and the particular interest shown by the aeronautical and aerospace industries. However, titanium alloys typically have very poor machinability. To deal with this problem, it is necessary to understand the physics involved in cutting operations and the different phenomena that can occur. Numerical simulation of the cutting process can provide valuable information necessary for the understanding of chip formation [2, 10, 25, 35]. However, this modeling must accurately represent the physical phenomena involved, and it must reproduce the thermo-mechanical behavior of the material.

Experimental measurement of the temperature in the cutting zone, using various techniques, show that it varies between 700 and 1000 °C [1, 11, 18, 24, 26]. In addition, via both analytical and experimental methods, the maximum strain rate in the cutting zone is estimated to be in the range of 10^3 s^{-1} to 10^5 s^{-1} . The generation of heat combined with the high strain rates leads to the localization of the strain and the formation of shear band during chip formation. Hence, in order to simulate the machining process, it is necessary to use a plasticity model that is capable taking into account these phenomena.

As a general rule, constitutive models can be grouped into three categories [14]: empirical, semi-physical, and physical.

- Empirical constitutive models are usually simple to identify. This facilitates their implementation in computer codes [3, 7, 15]
- Semi-physical constitutive models are more complex and require more experimental tests, the identification is more difficult than the empirical case [20, 22, 36]
- Physical constitutive models are based completely on metallurgical and physical aspects (microstructure, dislocations, recrystallization ...). However, the number of model parameters is typically high and by consequence a large number of experimental tests are required to identify the parameters [5], using sometimes complicated methodologies.

At present, the most widely used constitutive equation for the simulation of dynamic phenomena is the Johnson-Cook (JC) equation [15]. This model has several advantages which have lead to its outstanding success. In particular, its mathematical simplicity and the simple identification procedure combined with good prediction accuracy for many physical phenomena. In addition, its implementation by default in many finite element computer codes has also promoted its use.

The Johnson-Cook (JC) equation is shown in Eq. 1. The first term represents the isotropic hardening [19]. The second term represents the sensitivity to the strain rate. The sensitivity to temperature is taken into account by the third term. Parameters A , B , n , C , m are constants that need to be determined experimentally over a wide range of temperatures and strain rates. $\dot{\epsilon}_0$, T_f and T_a are the reference strain rate, the melting temperature of the material and the ambient temperature, respectively.

$$\sigma = \underbrace{(A + B\varepsilon^n)}_1 \underbrace{\left(1 + C \ln \frac{\dot{\epsilon}}{\dot{\epsilon}_0}\right)}_2 \underbrace{\left(1 - \left(\frac{T - T_a}{T_f - T_a}\right)^m\right)}_3 \quad (1)$$

Nevertheless, many studies have focused about modifying this constitutive equation to take into account different thermomechanical mechanisms in particular the thermal softening and materials behavior at high strain rates. Moreover, various comparative studies have been conducted to compare JC with other constitutive equations [12, 13, 17, 23, 28, 30, 38].

The difficulty in implementing and identifying more complex and more efficient material behavior models is an obstacle limiting their wide spread adoption. This makes

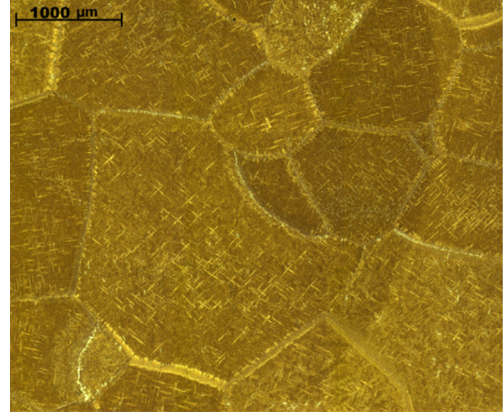


Fig. 1 Microstructure of the as-received Ti17 alloy

the use of the JC model indispensable for the simulation of dynamic problems under certain conditions. Hence, the JC model has been used in the present work to model the material behavior of the Ti17 alloy.

2 Experimental setup

The study has been carried out on a beta-rich titanium alloy, Ti17 (Ti-5Al-2Sn-4Mo-2Zr-4Cr). At room temperature, it is composed of α and β phases. The α phase can exist in different lamellar morphologies: α_{GB} , α_{WGB} and α_{WI} morphologies [32]. The microstructure of the material is presented in Fig. 1. Table 1 presents the main thermal and mechanical properties of Ti17.

The experimental tests were carried out on a GLEEBLE 3500 thermo-mechanical testing machine. The machine is equipped with a 100 kN load cell. Strain measurements are made using strain gauges. The temperature is measured by a K-type thermocouple. The specimen is placed between two anvils and is heated by the passage of an electric current (Joule effect). All tests were carried out in a vacuum (10^{-5} bar). To reduce the friction and to promote the thermal conductivity, graphite paper and a nickel paste are applied to the anvils/specimen interface.

Table 1 Thermal and mechanical properties of Ti17 (25°C)

Tensile Strength, σ_{UTS} (MPa)	1110
Elongation at Break (%)	5–8
Density, ρ (Kg/m ³)	4650
Specific heat, C_p (J/Kg°C)	525
Thermal conductivity, λ (W/m°C)	7

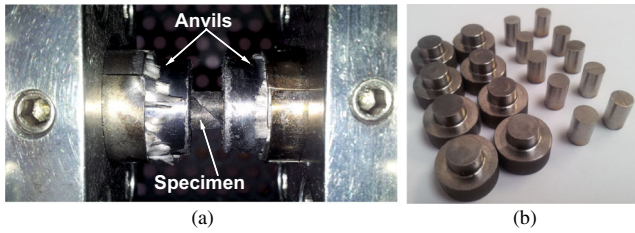


Fig. 2 a Experimental setup, b Shear and compression specimens

In order to determine the mechanical behavior of the Ti17 alloy under extreme conditions, both compression and shear tests have been conducted at different strain rates and different temperatures. The tests cover a wide range of strain rates (0.1 s^{-1} – 100 s^{-1}) and temperatures (25 – $800 \text{ }^{\circ}\text{C}$). Figure 2 shows the experimental setup and the specimen shapes for the compression and shear tests.

3 Compression tests

In order to determine the influence of the strain rate, a series of tests has been carried out with different impact velocities. Figure 3 shows the results of the first series of tests. It can be seen that the Ti17 alloy exhibits a nonlinear response to the strain rate, at ambient temperature. Moreover, the influence of strain rate can be observed for strain rates greater than 1 s^{-1} .

The objective of the second series of tests is to determine the effect of the temperature on the behavior of the Ti17. For this, the temperature has been varied from 25 to

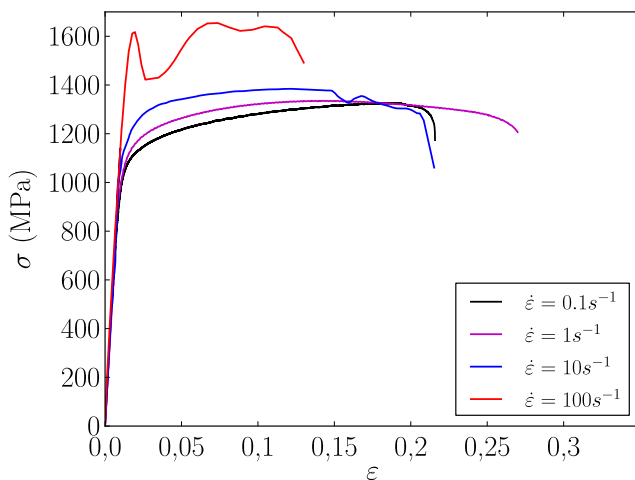


Fig. 3 Influence of strain strain rate ($T = 25 \text{ }^{\circ}\text{C}$)

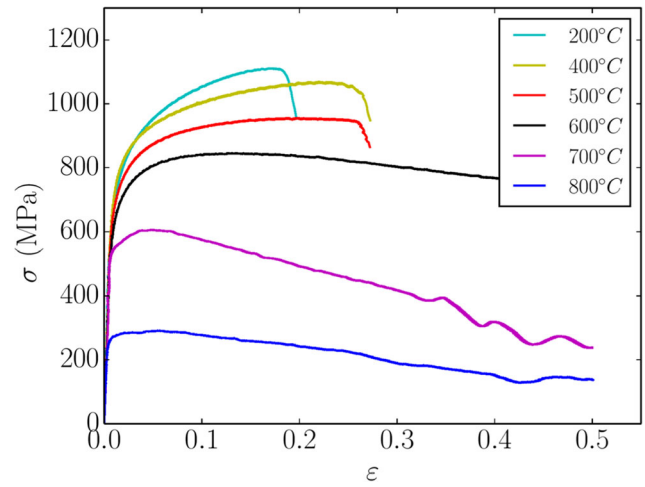


Fig. 4 Influence of temperature ($\dot{\epsilon} = 0.1 \text{ s}^{-1}$)

$800 \text{ }^{\circ}\text{C}$ ($\dot{\epsilon} = 0.1 \text{ s}^{-1}$). The principal results have been plotted in Fig. 4. It can be seen that good mechanical properties are conserved even at high temperatures (500 – $600 \text{ }^{\circ}\text{C}$). Thermal softening occurs at temperatures greater than $600 \text{ }^{\circ}\text{C}$ and is more pronounced for the tests realized at 700 and $800 \text{ }^{\circ}\text{C}$.

4 Identification of the model parameters

The identification procedure for the Johnson-Cook constitutive model is widely documented in the literature [6, 9, 16, 27, 29, 33, 34, 37]. The range of validity of the

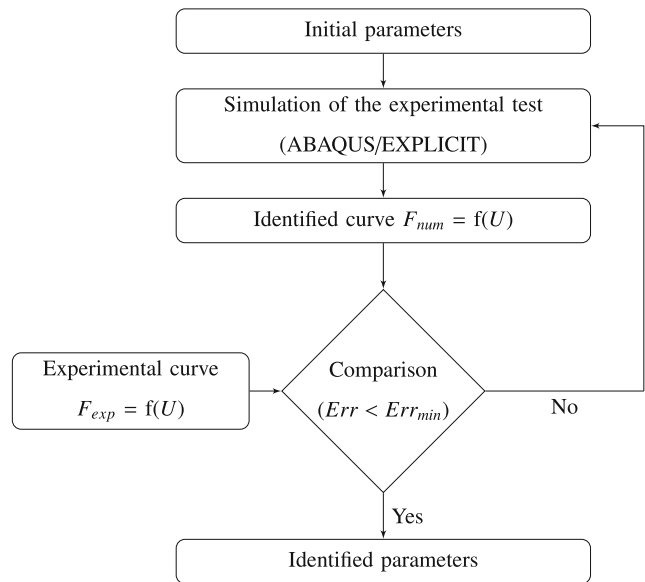


Fig. 5 Identification procedure

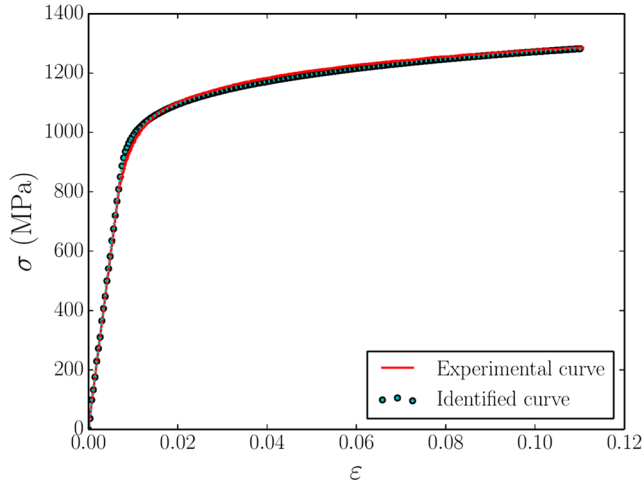


Fig. 6 Comparison of the experimental/identified curves ($A = 750$ MPa, $B = 803$ MPa, $n = 0.17$)

identified parameters depends on the experimental data in terms of strain rate and temperature. The parameters can be identified by a direct method or an inverse method. The direct method is faster but gives an average estimation for the C and m parameters. In this work, the parameters of the Johnson-Cook law have been identified by an inverse method.

The inverse identification method consists of an iterative procedure in which a numerical stress-strain curve is calculated from a finite element simulation of the mechanical test using the Johnson-Cook constitutive model. For the first iteration, an initial set of parameters is used. The numerical curve is then compared to the experimental curve. An error function is calculated to quantify the difference or error between the two curves. The ‘‘Lavemberg-Marquart’’ optimization algorithm is used to optimize the set of parameter. Thus, the aim of the method is to minimize the relative difference between the numerical curve and the experimental curve. Figure 5 illustrates the identification method.

Fig. 7 Comparison of the experimental/identified curves: **a** $m = f(T)$, **b** $m = 1.02$

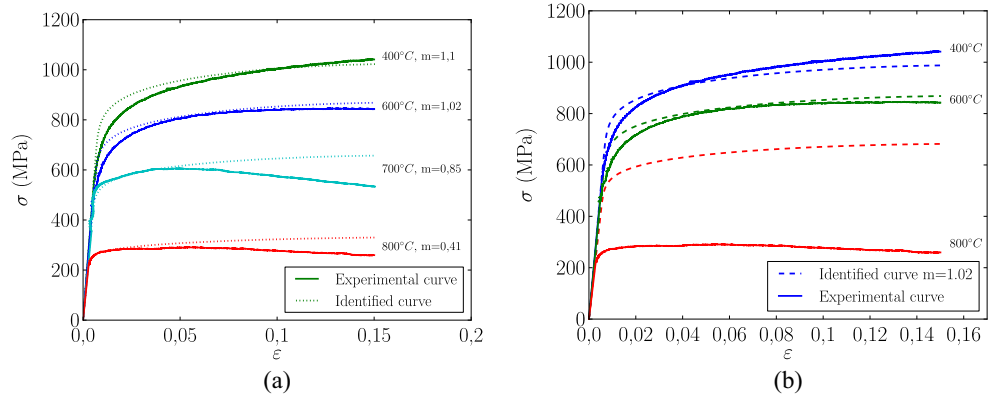


Table 2 Variation of parameter m ($\dot{\epsilon} = 0.1 \text{ s}^{-1}$)

Temperature °C	400	600	700	800
m	1.1	1.02	0.85	0.41

The finite element simulation of the experimental tests has been performed using ABAQUS/EXPLICIT. An axisymmetric model with an explicit integration scheme has been adopted. The model has been meshed with four nodes elements and reduced integration (CAX4RT). The friction between the machine anvils and the specimen is neglected. All physical parameters of the material vary as function of the temperature.

Identification of the hardening parameters (A , B , n)

The first step consists of identifying the hardening parameters A , B , and n . For this, tests at a strain rate of 0.1 s^{-1} have been carried out at room temperature. In this case, the JC equation may be written in the form of Eq. 2.

$$\sigma = A + B\varepsilon^n \quad (2)$$

The optimum parameters given by the optimization algorithm are $A = 750$ MPa, $B = 803$ MPa, $n = 0.17$. Figure 6 shows the experimental response and the numerical response using these parameters. The difference between these two curves does not exceed 1 %. It can be considered that a variation of 5 % in the hardening parameters does not drastically degrade the accuracy of the results.

Sensitivity to the temperature The second step consists of identifying the parameter m , which reflects the sensitivity to the temperature. Four temperature levels have been selected: 400, 600, 700, and 800 °C. Equation 3 shows the equation to be identified

$$\sigma = \left(750 + 803\varepsilon^{0.17}\right) \left(1 - \left(\frac{T - T_a}{T_f - T_a}\right)^m\right) \quad (3)$$

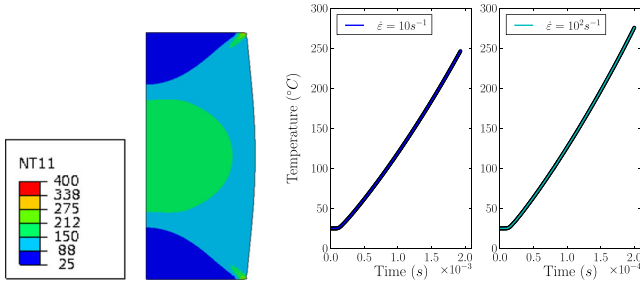


Fig. 8 Temperature evolution in the centre of the specimen (compression tests)

Figure 7 illustrates the obtained results from two different identification strategies. The first one consists of identifying the m parameter for each temperature level (Fig. 7a). The second involves finite element simulations using a constant m parameter. In this case, a significant difference between the experimental and the numerical results can be seen, particularly for temperatures greater than 600 °C (Fig. 7b). Thus, it can be concluded that parameter m should vary as a function of the temperature to minimize the estimation error Fig. 7b. It is also important to highlight that the JC model is not able to reproduce the thermal softening phenomena that occurs in the studied temperature range.

Table 2 shows the summary of the values of the parameter m as a function of the temperature.

Ti17 sensitivity to strain rate The last step involve the identification of the C parameter which reflects the sensitivity to the strain rate. The strain rate has been varied from $0.1 s^{-1}$ to $100 s^{-1}$. The identification can be performed in two ways.

The first consists of identifying the parameter C without the consideration of the thermal softening due to the heat

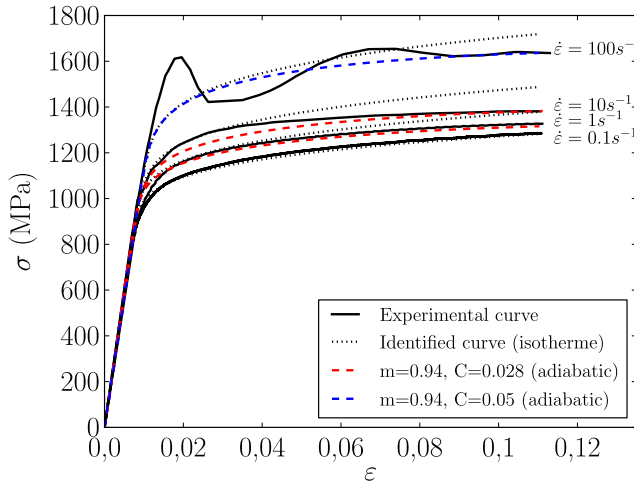


Fig. 9 Comparison of the experimental and identified curves

Table 3 Variation of parameter C ($T = 25$ °C)

$\dot{\epsilon}$ (s^{-1})	1	10	100
C	0.028	0.028	0.05

generated by the plastic deformation. In this case, the JC model can be written as Eq. 4

$$\sigma = (750 + 803\epsilon^{0.17}) \left(1 + C \ln \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right) \right) \quad (4)$$

The second identification approach takes into account thermal softening. Equation 5 shows the temperature change due to plastic deformation. Where C_p , ρ , and β are the heat capacity, density, and Taylor-Quinney coefficient [31], respectively. The Taylor-Quinney coefficient represents the fraction of the plastic deformation energy transformed into heat.

$$\Delta T \simeq \beta \int \frac{\sigma \Delta \epsilon_p}{\rho C_p} \quad (5)$$

From the numerical simulation of the mechanical tests, the maximum temperature reached in the center of the specimen can be calculated (Fig. 8). Hence, the JC model can be written as Eq. 6.

$$\sigma = (750 + 803\epsilon^{0.17}) \left(1 + C \ln \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right) \right) \times \left(1 - \left(\frac{(T + \Delta T) - T_a}{T_f - T_a} \right)^m \right) \quad (6)$$

Figure 9 shows the results obtained for both cases. For the isothermal curves, the numerical response predicts the beginning of plasticity until a certain maximum stress is reached. It can be seen that thermal softening due to internal

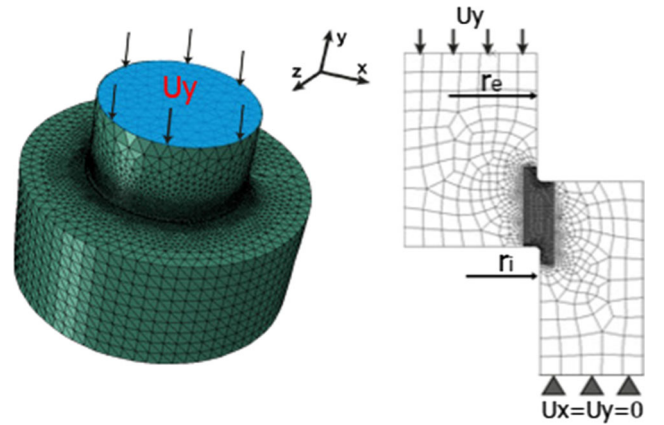


Fig. 10 Modeling of shear test

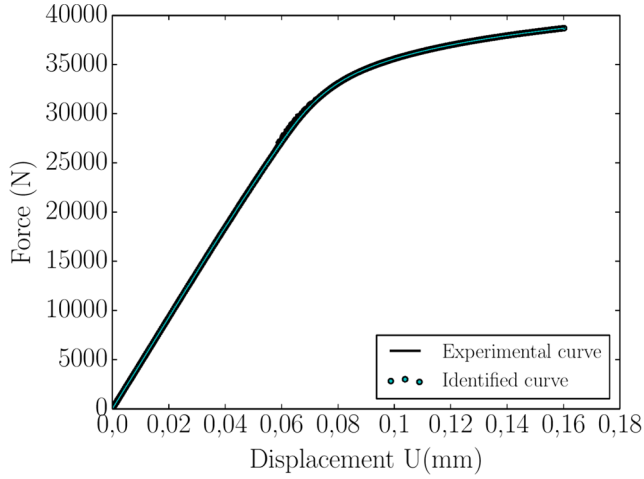


Fig. 11 Comparison of the experimental and identified curves ($A = 1012$ MPa, $B = 399$ MPa, $n = 0.22$)

heat generation via plastic deformation causes the experimental curves to drop. However, the numerical curves continues to increase. Taking into account internal heating by plastic deformation improves the accuracy of the results. In this case, the difference between the experimental and numerical responses does not exceed 4 %.

It is also important to note that in order to achieve better results the parameter C should not be considered constant in terms of the strain rate. Table 3 shows the values of the C parameter as a function of the strain rate.

5 Shear tests

For the shear tests, hat-shaped specimens have been used. The specimen is loaded in compression along its axis of revolution. This results in the formation of a cylindrical shear zone [8]. In addition, this type of specimen allows the study

Fig. 12 Comparison between the experimental and identified curves: **a** $m = f(T)$, **b** $C = f(\dot{\epsilon})$

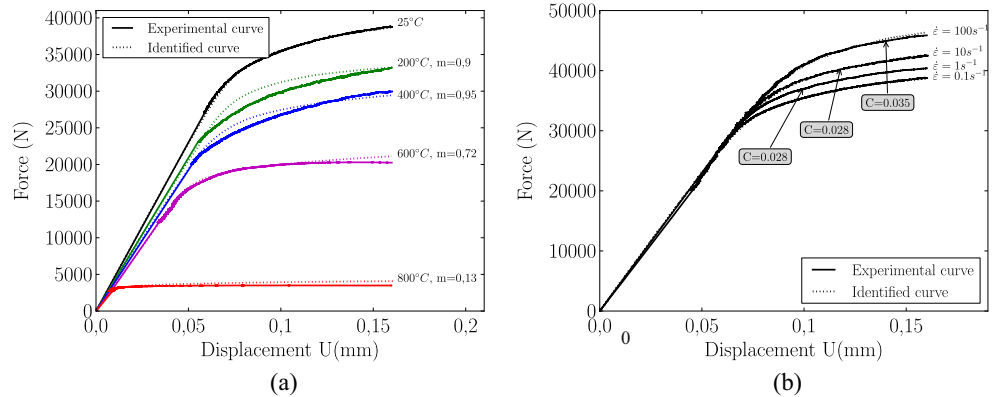


Table 4 Variation of parameter C ($T = 25$ °C)

$\dot{\epsilon} (s^{-1})$	1	10	100
C	0.028	0.028	0.035

of strain localization and the formation of shear bands at high strain rates. The thickness of the shear zone is assumed to be constant. The strain rate and the shear stress can be estimated using Eqs. 7 and 8 [21].

$$\dot{\gamma} = \frac{V}{e} \quad (7)$$

$$\tau = \frac{F}{\pi \frac{h(d_i - d_e)}{2}} \quad (8)$$

Where $\dot{\gamma}$ and τ are the strain rate and the shear stress, respectively. The parameters V , e , d_i , and d_e represent the impact velocity, the shear zone thickness $e = (r_i - r_e)$, and the inner and outer diameter of the specimen.

The identification procedure described above for the compression tests is used for the shear tests. Figure 10 shows the finite element model of the hat-shaped specimens. The model contains 3000 elements and the mesh is refined in the shear zone. The average element size in this area is of the order of $20 \mu m$.

Firstly, the hardening parameters (A , B , and n) have been identified at $T = 25$ °C and $\dot{\epsilon} = 0.1 s^{-1}$. Figure 11 shows the results of the identification. It can be seen that very good correlation is obtained between the numerical and the experimental curves (the difference does not exceed 1 %). The identified parameters are $A = 1012$ MPa, $B = 399$ MPa, and $n = 0.22$

Then, m parameter has been identified for different temperatures. The identification of this parameter is illustrated by Fig. 12a. When the temperature exceeds 600 °C thermal softening takes place. The same phenomenon has been

Table 5 Variation of parameter m

Temperature °C	200	400	600	800
m	0.9	0.95	0.72	0.13

Fig. 13 Compression specimens: **a** 25 °C; 0.1 s⁻¹, **b** 25 °C; 1 s⁻¹, **c** 25 °C; 10 s⁻¹, **d** 400 °C; 0.1 s⁻¹, **e** 800 °C; 0.1 s⁻¹

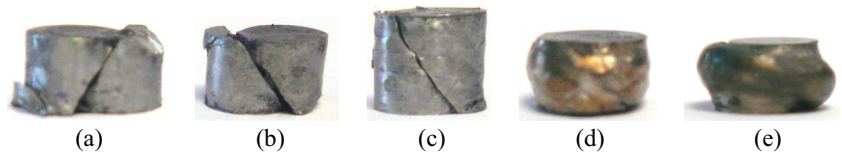


Fig. 14 Microscopic observation of a compression specimen ($T = 600$ °C, $\dot{\epsilon} = 0.1$ s⁻¹): Shear band formation

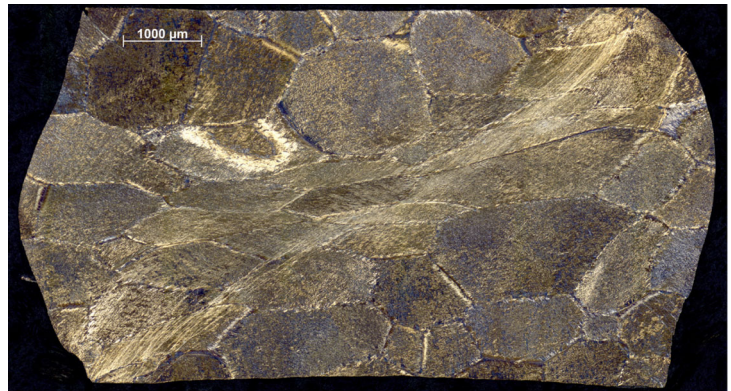
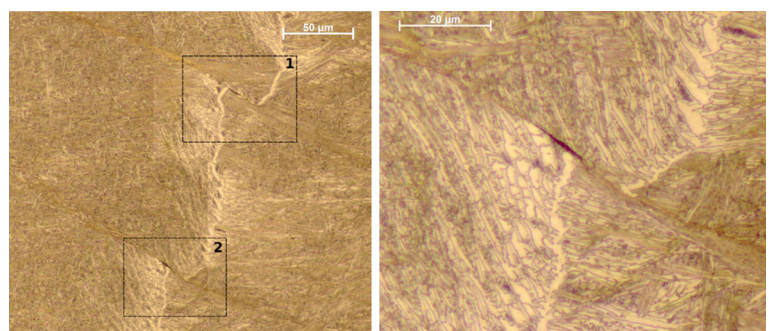


Fig. 15 Microscopic observation of a compression specimen ($T = 600$ °C, $\dot{\epsilon} = 0.1$ s⁻¹): Microcracks



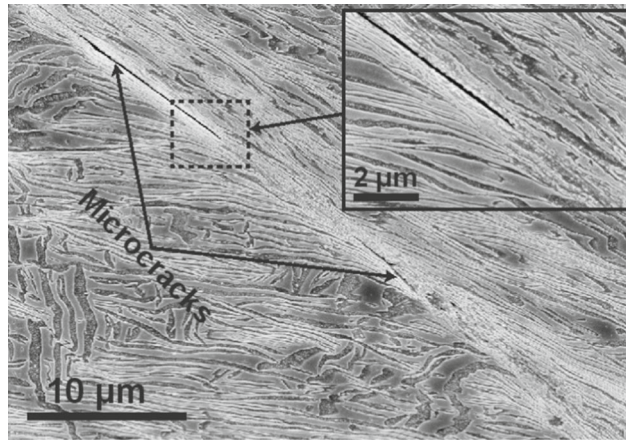


Fig. 16 Microscopic observation of the shear zone ($T = 400\text{ }^{\circ}\text{C}$, $\dot{\epsilon} = 0.1\text{ s}^{-1}$)

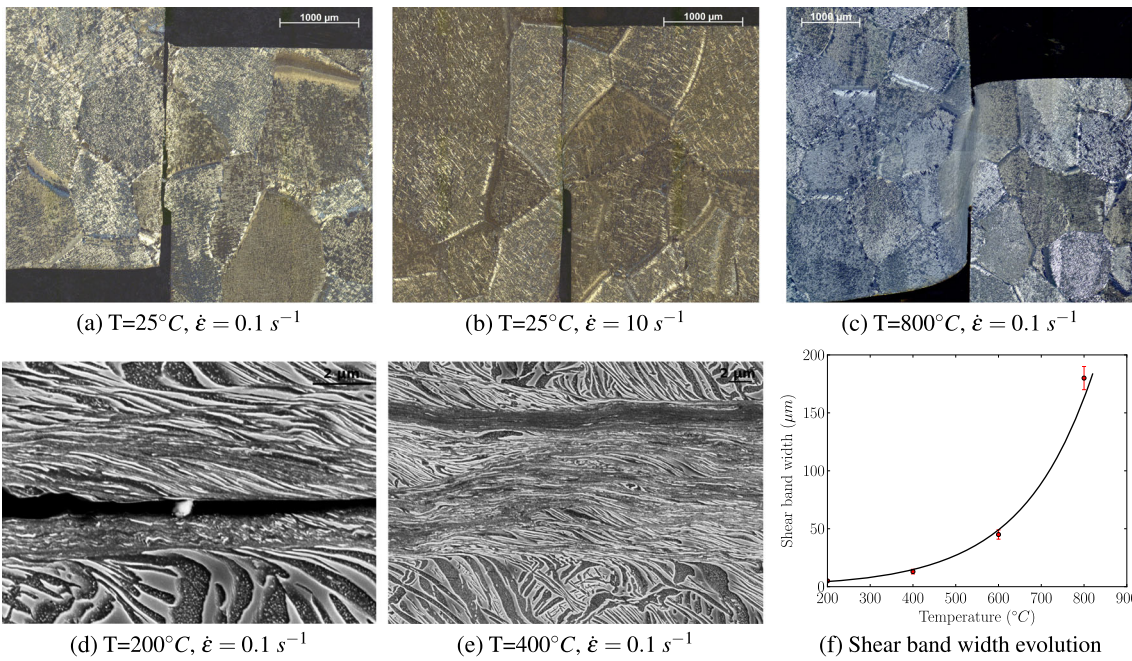
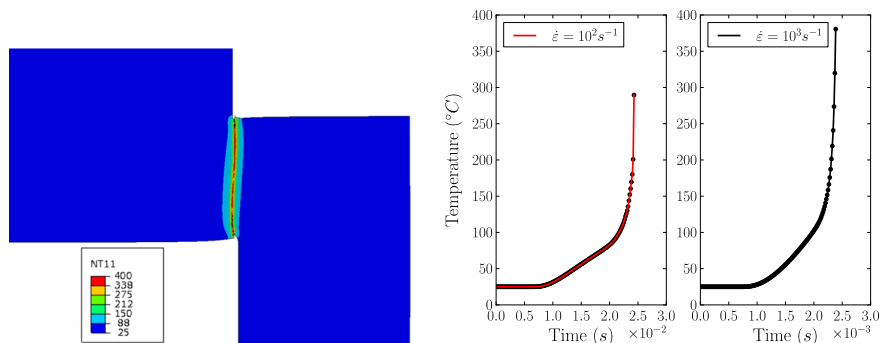


Fig. 17 Microscopic observation of the shear specimens

Fig. 18 Shear test simulation and temperature evolution in the shear band



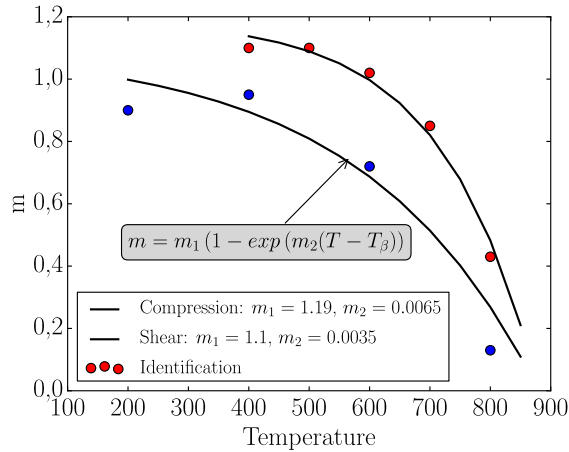


Fig. 19 Evolution of m and C parameters

also observed for the Ti6Al4V and the Ti555-3 titanium alloys [4]. Finally, the last step is to identify parameter C . Figure 12b shows the identified curves.

Tables 4 and 5 summarize the variation of parameter C as a function of strain rate and the parameter m as function of temperature.

6 Microscopic observations

Microscopic observations have been conducted on tested specimens. Figure 13 shows five compression specimens tested under various thermo-mechanical conditions.

Figure 14 shows a specimen tested at 600 °C with strain rate of $\dot{\epsilon} = 0.1 \text{ s}^{-1}$. A very high degree of strain can be seen with the grains being elongated along the diagonal of the specimen. Parallel shear bands can be seen along with the creation of microcracks (Figs. 14 and 15).

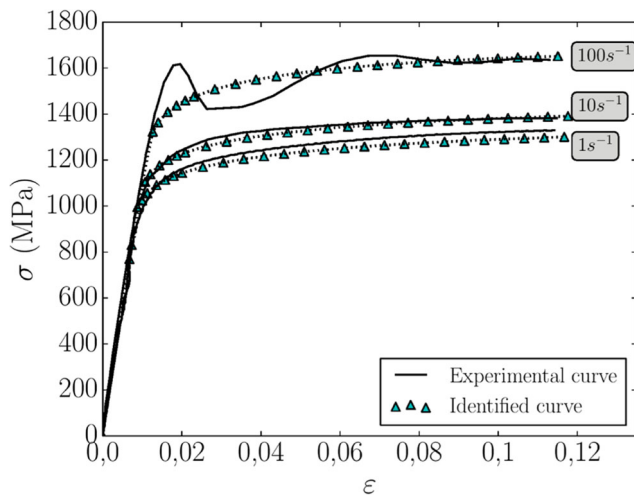
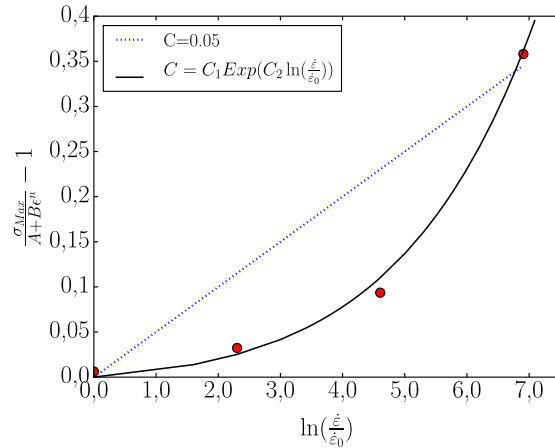


Fig. 20 Model response for different strain rates



Similar phenomena have been observed at the the temperature of 400 °C as shown in Fig. 16. The average widthof the shear band is about 7 μm . In addition, the figure shows microcracks along the shear band. The width of the microcracks is about 140 nm.

With regard to the shear tests, the shear band is highly localized notably at room temperature. However, it becomes larger with the increase of temperature. Figure 17 shows the shear zone for different tests. Figure 17f demonstrates that the shear band becomes larger depending on the temperature. The dependence of the shear band width of the temperature is illustrated by Fig. 17a–e.

Indeed, for the tests carried out at room temperature and at high strain rates, the temperature generated by plastic deformation reaches 400 °C (Fig. 18).

7 Discussion

Overall, the Johnson-Cook model can adequately reproduce the material behavior under different thermo-mechanical loading conditions. However, the identified parameters are not valid over a wide range of strain rates and temperatures.

Better results are achieved if the model parameters C and m are not considered to be constant. This simple modification is therefore proposed for future studies using the JC model. Indeed, defining parameters m as a function of the temperature and parameter C as a function of strain rate, results in a significant improvement in the model predictions while maintaining the same number of experimental tests and the same identification procedure.

Figure 19 illustrates the evolution of the parameters m and C . A model has been proposed to overcome this problem, Fig. 20 shows the model response. With this simple modification, the number of the experimental trials does not change and the result becomes significantly better.

8 Conclusion

The material behavior of the Ti17 titanium alloy loaded under extreme thermo-mechanical conditions has been investigated via compression and shear tests conducted over a large temperature and strain rate range. The tests have shown that the material is sensitive to strain rate and to temperature. The identification of the Johnson-Cook (JC) model parameters has been performed using an inverse method. The comparison between the experimental results and the predictions using the JC model highlights some differences, particularly at high strain rates and high temperatures. Micrographic analysis has shown the evolution, the formation of shear bands and microcracks before the rupture of the specimen. In these areas, the temperature is changing very considerably and can reach 400 °C.

The JC model does not guarantee good prediction accuracy for the thermo-mechanical behavior of the material over a wide range of strain rates and temperatures. It is nevertheless possible to use the model by restricting the range of validity depending on the temperature and strain rates. It is therefore more appropriate to identify the model for different temperature ranges and/or strain rate ranges. This makes it possible to make changes to the model while keeping the same number of tests and the same identification method. This, significantly improve the prediction accuracy of the model. Indeed, a simple evolution of the parameters m and C improves the response of the model. A change in these parameters has been proposed in this work.

For an enhanced reproduction of the material behavior, it might be better to use a crystal plasticity law. However, the identification of the constitutive equation parameters is much more complicated as well as the implementation in FEA computer codes.

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