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Finite element simulation of magnesium alloys laser beam welding

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A B S T R A C T

In this paper, a three-dimensional finite element model is developed to simulate thermal history magnesium-based alloys during laser beam welding. Space-time temperature distributions in weldments are predicted from the beginning of welding to the final cooling. The finite element calculations were performed using Cast3M code with which the heat equation is solved considering a non-linear transient behaviour. The applied loading is a moving heat source that depends on process parameters such as power density, laser beam dimensions and welding speed, and it is associated to moving boundary conditions. Experiments were carried out to determine temperature evolution during welding and to measure the laser weld width. By comparing the thermal model answers with the measurements, it is found that numerical simulations results are in a good agreement with the experimental data.

Keywords:

FEM simulation
Laser welding
Magnesium alloy
Thermal analysis

1. Introduction

The requirement to reduce fuel consumption and gas emission entices auto industries to replace dense materials, not only steels and cast iron alloys but even aluminium alloys, by magnesium-based alloys. Friedrich and Mordike (2006) reported that these materials have the lowest density of conventional casting metals (33% lighter than aluminium alloys), and other attractive characteristics' such as excellent specific strength, good castability and recyclability.

With the increasing uses of magnesium alloys especially in automotive industry, it was important to develop assembly processes. Today, magnesium alloy components may be joined using mechanical fasteners and some welding techniques with high energy density and shielding gases to protect the metal from the oxygen action. Basically, TIG and MIG processes are the most used methods for magnesium alloys welding. However, some disadvantages of these techniques, like low welding speeds, large heat affected zone (HAZ) and high residual stress and distortion of joints, limit their uses. For these reasons, magnesium alloys weldability by innovative welding techniques, like laser beam welding (LBW), has been studied during the last decade. Dhahri et al. (2000, 2001) studied

laser beam weldability of AZ91 and WE43 magnesium-based alloys. Using a CO₂ laser source, they have determined welding parameters to joint 6 and 2 mm thickness sheets. Some studies recently published by Quan et al. (2008) were interested on laser welding of dissimilar magnesium alloys. Joining of magnesium-based alloys using focused laser beam is an interesting research field that is still in progress.

On the back of this, laser welding process is advantageous, it leads to small heat affected zone, deep and narrow fusion zone, high processing speed and low residual stresses and weldment distortion. But experimental investigations are long and expensive so it is important to develop numerical techniques to simulate thermal and mechanical consequences of this welding process. Numerical results can be used to explain the physics of some complex phenomena in welding process and to optimize welding parameters. Several numerical models have been developed to determine temperature profiles and stresses distribution during laser beam welding. Nevertheless, most of investigations refer to steel structural components and recently to aluminium alloys. Spina et al. (2007) established a thermo-mechanical model to predict temperature and analyse the welding parameters influence on sample displacement after cooling during AA5083 aluminium alloy laser welding. Using coupled analyses, Moraitis and Labeas (2008) modelled the laser welding of 6061 aluminium-based alloys. Considering a cone shaped keyhole as thermal source, they predicted residual stresses distribution on 2 mm thickness sheets.

To the author's knowledge, no transient numerical analysis has been made for laser welding magnesium alloys; published investigations are limited to local problems like those proposed by Abderrazak et al. (2008, 2009a,b). In their work, they studied local

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Nomenclature

C	specific heat ($\text{J kg}^{-1} \text{ } ^\circ\text{C}^{-1}$)
d	laser beam diameter (μm)
e	piece thickness (mm)
h	convective coefficient ($\text{W m}^{-2} \text{ } ^\circ\text{C}^{-1}$)
i	increment
np_s	time step number during welding stage
t	time (s)
t_{r0}	initial time of cooling stage (s)
T	temperature ($^\circ\text{C}$)
T_i	initial temperature ($^\circ\text{C}$)
T_s	surface temperature ($^\circ\text{C}$)
T	fluid temperature ($^\circ\text{C}$)
T_0	ambient temperature ($^\circ\text{C}$)
P_{ak}	keyhole absorbed power (W)
P_{ap}	plasma absorbed power (W)
q	surface heat density (W m^{-2})
Q	volume heat density (W m^{-3})
V	welding speed (m min^{-1})
x_i	coordinates (mm)
(x, y, z)	Cartesian coordinates (mm)

Greek symbol

ε	emissivity
Δt_s	time step-welding stage (s)
Γ_{ext}	external surface (mm^2)
Γ_c	contact surface (mm^2)
$\Gamma_{p,i}$	plasma lighted surface at i position (mm^2)
$\Gamma_{e,i}$	keyhole lighted surface at i position (mm^2)
λ	thermal conductivity ($\text{W m}^{-1} \text{ } ^\circ\text{C}^{-1}$)
Ω	volume (mm^3)
ρ	density (kg m^{-3})
τ	laser-matter interaction time (s)

parameter effects on molten pool formation during CO_2 laser welding of AZ91 and WE43 magnesium alloys.

In the present study, the thermal history of butt-joint laser beam welding of thin AM60 magnesium alloys plates was simulated. A transient non-linear three-dimensional model was developed, within a finite elements computational code Cast3M, in order to predict the space-time distribution of temperature in magnesium alloy sheets from the beginning of welding until the return to the thermal equilibrium at cooling. The developed model took into account the non-linearity introduced by the loading which depends on time and space, and by thermo-physical properties which are temperature dependent. The heat source was introduced as mobile volume source modelling the power density produced by the laser spot during laser-matter interaction. As well as, in this model, a surface thermal source is introduced in order to take into account the effect of the plasma during laser welding.

Numerical results were presented in the form of isotherms at different times of treatment and instantaneous evolutions of the temperature in each point of the mesh. Simulated temperature evolutions were compared to those measured experimentally by thermocouples implanted in several points of the weldments. Predicted molten zone form during heating stage was also compared to weld morphology obtained by metallurgical investigations.

2. Numerical simulation model

During laser continuous wave welding process, the power density, produced by the focused beam, is very intense allowing the vaporization of metal directly under the beam. A thin hole, com-

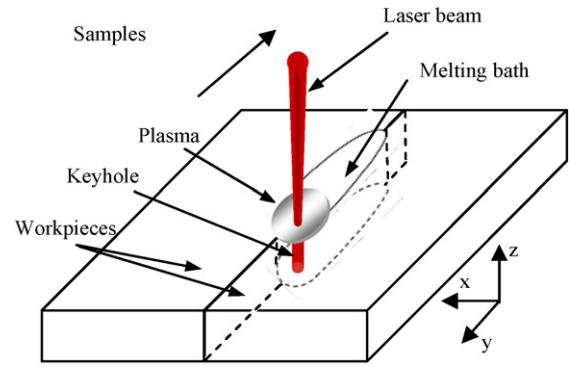


Fig. 1. Keyhole and plasma formation during laser welding.

posed of metallic vapors is created through the welded components (Fig. 1). This one, known as keyhole, transmits the laser beam energy to metal. During weldments moving, the keyhole is maintained under the laser beam and surrounded by molten metal which is solidified after beam moving allowing the assembly of the workpieces. The keyhole is protected by a shielding gas producing the plasma that constitutes a secondary heat source. The described physical phenomena were simulated through a numerical finite element model in order to simulate thermal behaviour of laser welded samples.

2.1. Assumptions of simulation

Some simplifying assumptions were adopted for the development of the numerical model. They concern on: (i) the reduction of field study by making use of symmetry. The thermal history of only one half of the assembly was predicted. (ii) Simulation was made considering that the laser beam moves at constant speed. We have also assumed (iii) a perfect contact between the two welded parts, (iv) a uniform power distribution in the keyhole and (v) an isotropic thermal behaviour during welding.

2.2. Heat balance

The developed thermal model results from the energy balance during laser beam welding. Two treatment phases were modelled.

(1) *Stage I* (Fig. 2): The applied loading was the combination of laser beam power density and surface heat flow due to the plasma. Boundary conditions are convection loss flows on external surface and radiation losses in lighted laser beam surface.

(2) *Stage II*: After applying the laser spot, the weldments cooled on free air. During cooling, laser beam was cancelled. We considered the temperature distribution at the end of heating phase as

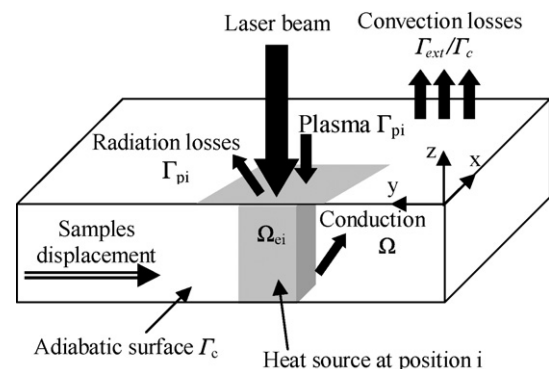


Fig. 2. Energy balance during laser welding process (stage I).

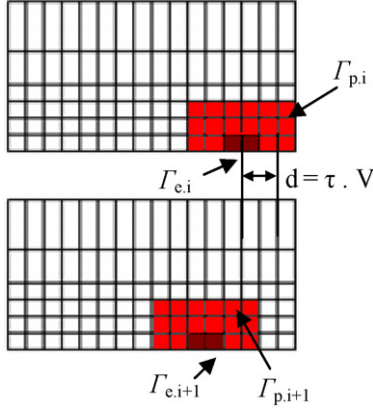


Fig. 3. Meshing of laser lighted surface.

initial condition and only convection losses on external surface as boundary conditions.

2.3. Geometrical model

The geometrical model of weldment was a three-dimensional mesh modelled using cubic elements with eight nodes and quadratic elements with four nodes. To introduce a mobile heat source, mesh construction must depend on laser beam dimension and welding rate. A dense mesh was used in the area along the weld line as shown in Fig. 3. Geometry dimensions were 60 mm in length 40 mm in width and 3 mm in thickness. The built mesh is composed of 17 100 elements for 24 080 nodes (Fig. 4).

2.4. Thermal problem formulation

Heat equation resolution, in non-linear transient state with a mobile volumetric heat source, allowed the determination of the space–time temperature evolution during welding.

- During *stage I*, the mathematical formulation is given by:

$$\text{on } \Omega : \frac{\partial \rho(T)C(T)T(x_i, t)}{\partial t} - \text{div}(\lambda(T)\text{grad}T(x_i, t)) - Q = 0 \quad (1)$$

The convection and radiation limit conditions are:

$$\text{on } \Gamma_{p,i} : \lambda(T)(\text{grad}T(x_i, t))_{\text{surface}} + \varepsilon\sigma(T(x_i, t)^4 - T_{\infty}^4) = q \quad (2)$$

$$\text{on } \Gamma_{\text{ext}} \setminus \Gamma_c : \lambda(T)(\text{grad}T(x_i, t))_{\text{surface}} + h(T(x_i, t) - T_{\infty}) = 0 \quad (3)$$

The adiabatic condition on the contact surface is:

$$\text{on } \Gamma_c : \lambda \text{grad}T(x_i, t) = 0 \quad (4)$$

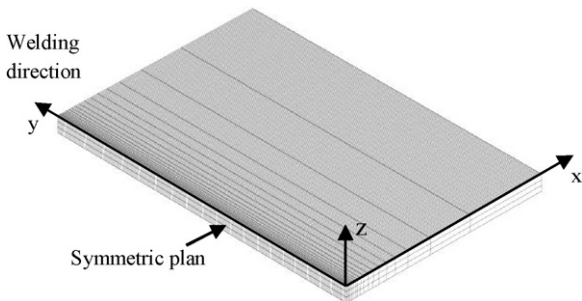


Fig. 4. Geometric model–meshing.

Table 1
Magnesium alloy properties evolution with temperature.

$T (^{\circ}\text{C})$	0	40	120	200	500	700
$\lambda (\text{Wm}^{-1} \text{ } ^{\circ}\text{C}^{-1})$	60	66	77	85	100	60
$T (^{\circ}\text{C})$	25	100	150	200	600	
$\rho (\text{kgm}^{-3})$	1792	1781	1774	1766	1730	
$T (^{\circ}\text{C})$	20	200	250	270	350	600
$C (\text{J kg}^{-1} \text{ } ^{\circ}\text{C}^{-1})$	1010	1080	1150	1145	1155	1300

The initial condition is:

$$\text{at } t = 0 : T(x_i, 0) = T_0 \quad (5)$$

- During *stage II*, mathematical formulation is given by:

$$\text{on } \Omega : \frac{\partial \rho(T)C(T)T(x_i, t)}{\partial t} - \text{div}(\lambda(T)\text{grad}T(x_i, t)) = 0 \quad (6)$$

The convection limits conditions are:

$$\text{on } \Gamma_{\text{ext}} \setminus \Gamma_c : \lambda(T)(\text{grad}T(x_i, t))_{\text{surface}} + h(T(x_i, t) - T_{\infty}) = 0 \quad (7)$$

The adiabatic condition on the contact surface is:

$$\text{on } \Gamma_c : \lambda \text{grad}T(x_i, t) = 0 \quad (8)$$

The initial condition is the temperature distribution in the sample at the end of laser phase application:

$$\text{at } t = t_{r0} : T(x_i, t) = T_{np_s} \quad (9)$$

2.5. Heat sources model

In the numerical model, the thermal loading was introduced as mobile volume heat source. Based on metallurgical observations of laser beam magnesium alloys weld made by Belhadji (2009) and Dhahri et al. (2000, 2001), the formed keyhole was considered cylindrical. It was modelled by a volume density power Q that depends on laser beam diameter d and keyhole absorbed power P_{ak} (Eq. (10)). In addition to the volume source, a surface density source q introduced as boundary condition (Eq. (2)) modelling the plasma consequence. This depends on the plasma absorbed power P_{ap} and plasma affected surface S_{plasma} (Eq. (11)). Heat source model parameters were experimental data.

$$Q = \frac{P_{ak}}{V_{\text{keyhole}}} = \frac{P_{ak}}{e(\pi d^2/4)} \quad (10)$$

$$q = \frac{P_{ap}}{S_{\text{plasma}}} \quad (11)$$

2.6. Material data

During laser welding process an important temperature gradient was produced between various parts of weldments, from the beginning to the end of treatment. Thermo-physic characteristics of material must be temperature depended. In their investigation on magnesium alloys MIG-welding simulation, Michailov et al. (2003) had used the evolution of thermal conductivity, density and specific heat according temperature. The values of these properties, shown in Table 1, are exploited in this work.

2.7. Thermal problem resolution

Thermal problem was solved using ‘‘PASAPAS’’ procedure. This Cast3M operator was used by Bessroul et al. (2002) to developed transient, non-linear and incremental calculations taking into consideration conduction, convection and radiation. The numerical scheme used for heat equation resolution was an implicit

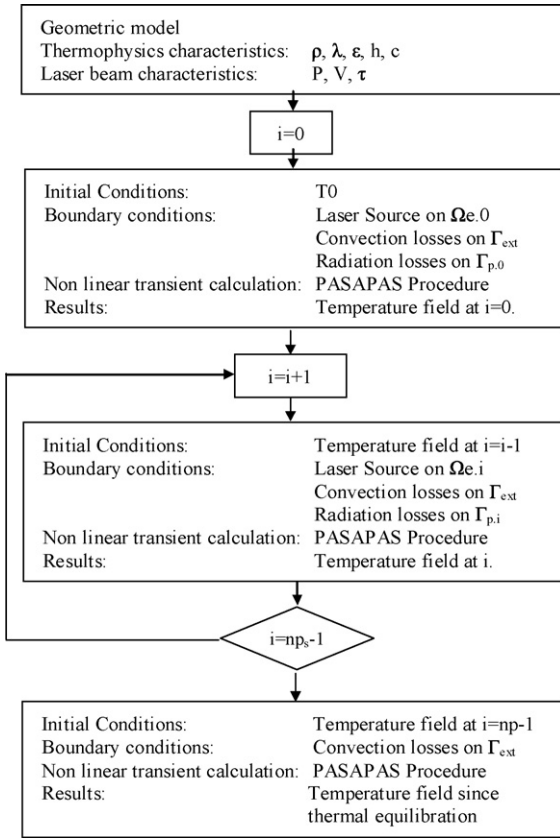


Fig. 5. Flowchart of numerical calculation.

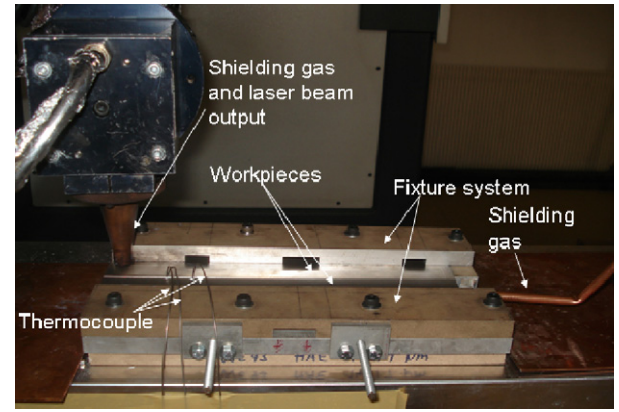


Fig. 6. Welding fixture with clamped AM60 magnesium alloy samples.

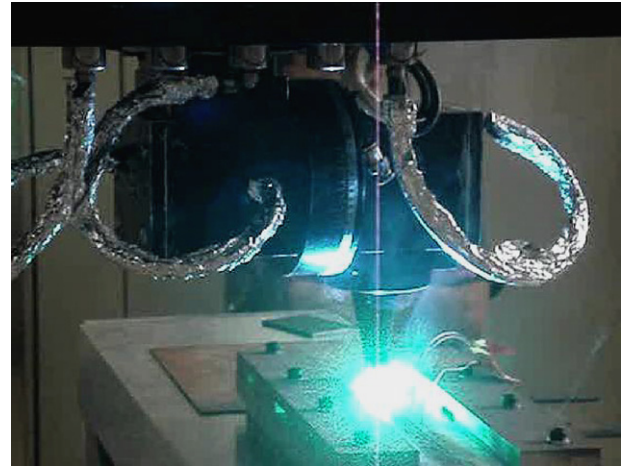


Fig. 7. Plasma creation during magnesium alloys laser welding.

schema with two time steps according to DUPONT2 algorithm and θ -method for the first step.

The flow chart of Fig. 5 shows the procedure for FE calculation. The proposed numerical model simulated the whole thermal history of welded pieces laser welding and cooling. The number of laser spot positions ($np = 150$) depends on sample length and key-hole diameter. The time step calculation Δt_s , in laser application stage, is in relation to the laser-matter interaction time given by Eq. (12):

$$\tau = np_s \Delta t_s = \frac{d}{V} = 0.0057 \text{ s} \quad (12)$$

3. Experimental investigations

A number of welding tests were performed to optimize laser welding parameter for as-cast AM60 magnesium-based alloy. Welds were carried out using a Rofin 3 kW CW CO₂ laser source generating a high quality beam (TEM₀₁ mode). The laser beam was focused with 50 mm focal length parabolic mirror and its diameter at the focal point was $d = 400 \mu\text{m}$.

Samples, machined in the form of 60 mm $L \times$ 46 mm $W \times$ 3 mm T sheets, were positioned in the fixture system (Fig. 6) and welded using helium as shielding gas (Fig. 7). Tables 2 and 3 give respectively the chemical composition of welded material and optimized welding parameters used in experimental investigations.

To record temperature evolution during laser welding process, 1 mm diameter K-type thermocouples were used. As shown in Fig. 8, thermocouples were fixed near the weld at two different distances to the centre-line (T_1, T_2) and at different axial locations (location in the advancing direction of welding T_2, T_3).

After welding, the microstructure of the different zones of the assembly was analysed using a high magnification zoom micro-

Table 2
AM60 composition.

% Al	% Mn	% Zn	% Si	% Cu	% Ni
5.5–6.5	0.1–0.4	≤0.2	≤0.2	≤0.2	≤0.03

Table 3
Welding parameters.

Laser power (W)	Velocity (mm/min)	Focus point (mm from surface)	Shielding gas
3000	4.2 m/min	0	40 l/min, 2 bars

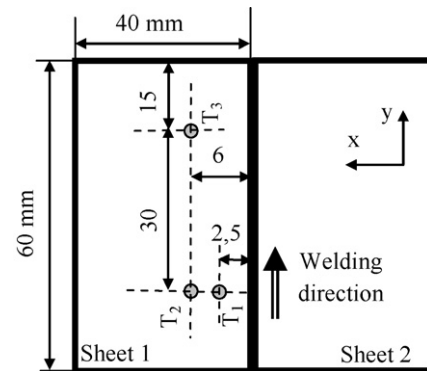


Fig. 8. Thermocouples position during welding.

scope. Metallurgical samples were mounted by resin ground and polished using 180–1200-grit silicon carbide papers (SiC). Immediately after the last polishing step, the samples were washed with water, rinsed with methanol CH_3OH , and dried. A fine polishing was conducted using $0.5\ \mu\text{m}$ oil based diamond compounds. Samples were subsequently etched with acetic glycol etchant (60 ml ethylene glycol $\text{C}_2\text{H}_6\text{O}_2$, 20 ml acetic acid $\text{C}_2\text{H}_4\text{O}_2$, 19 ml water H_2O , 1 ml HNO_3).

4. Results and discussion

As concern numerical study, results of FEM thermal model are given for 3 mm AM60 magnesium alloy sheet thickness. Processing parameters are those used for experimental investigations and

specified in Table 3. For results figures, (x, y, z) point coordinates are given in mm.

Fig. 9 illustrates temperature distribution on the welded sheet at different times during stage I (Fig. 9a–d) and stage II that begins at $t=0.855\ \text{s}$ (Fig. 9e). The figures show that during laser beam application, there is an important thermal gradient near the keyhole but away from heat source, the weldments temperature does not change (30°C). Isotherm distribution of Fig. 9c demonstrates that the temperature, reached at the laser beam run, exceeds the AM60 magnesium alloy melting point (610°C) and falls quickly enabling the solidification of material and weldments assembly. Plasma effect is noted by a larger fusion zone width on the weldment top surface where the heat input is elevated.

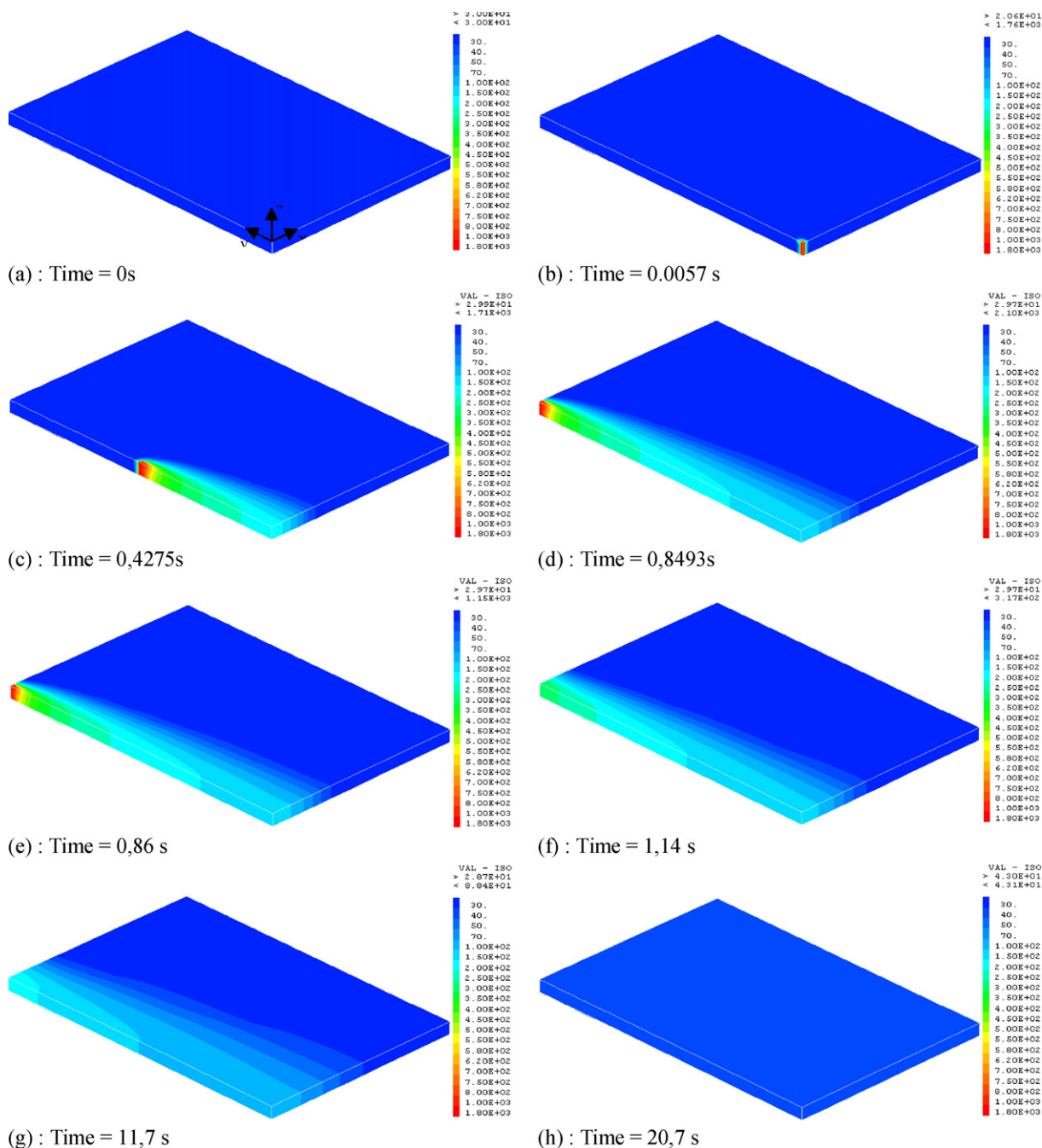


Fig. 9. Isotherm evolution during laser application (a–d) and cooling (e–h).

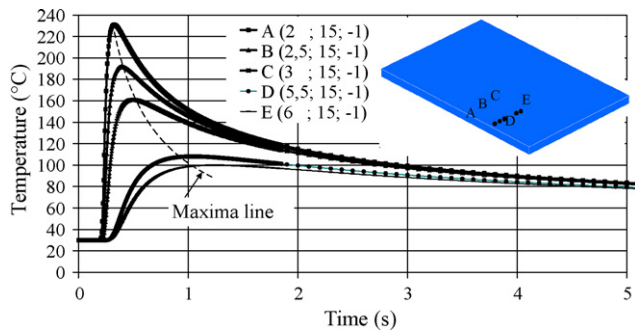


Fig. 10. Predicted temperature evolution during laser beam welding.

Fig. 10 shows simulated temperature evolutions according time, in five points A–E at different positions from weld centre-lines, since the beginning of welding until thermal balance. It can be noted that heating and cooling rates are important during laser application stage whereas during cooling, heat flow is lower.

Using temperature evolution according time, heating and quenching rate are calculated for five points situated on the molten zone (points F and G) and near laser–matter interaction surface (points H–J). According to Fig. 11, predicted quenching rate on the melting zone exceeded 10^4 °C/s. This result is in accordance with those of Liu et al. (2005).

For experimental investigations, results concern temperature measurements during welding and weld metallurgical observations.

Fig. 12 gives K-thermocouple measured temperature during laser beam welding. The temperature evolutions according time are given for three specific points of weldment T_1 , T_2 and T_3 representing the thermocouple position (Fig. 8). From measured evolution, we can note there are two stages of the process: the heating one for which the heating rate is important compared to quenching rate during cooling stage.

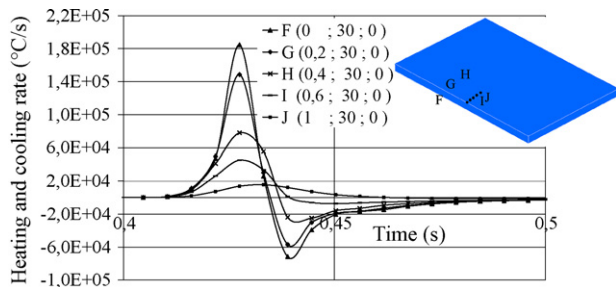


Fig. 11. Predicted heating and cooling rates evolution during laser welding.

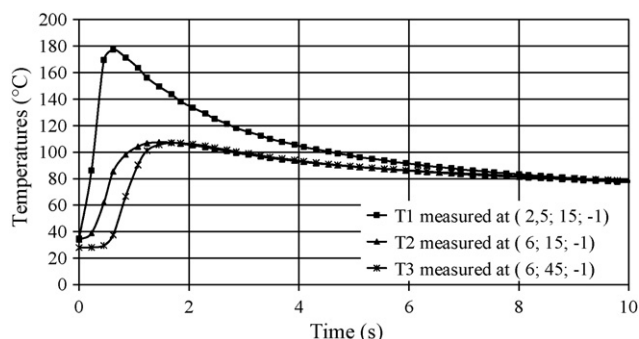


Fig. 12. Thermocouple measured temperatures.

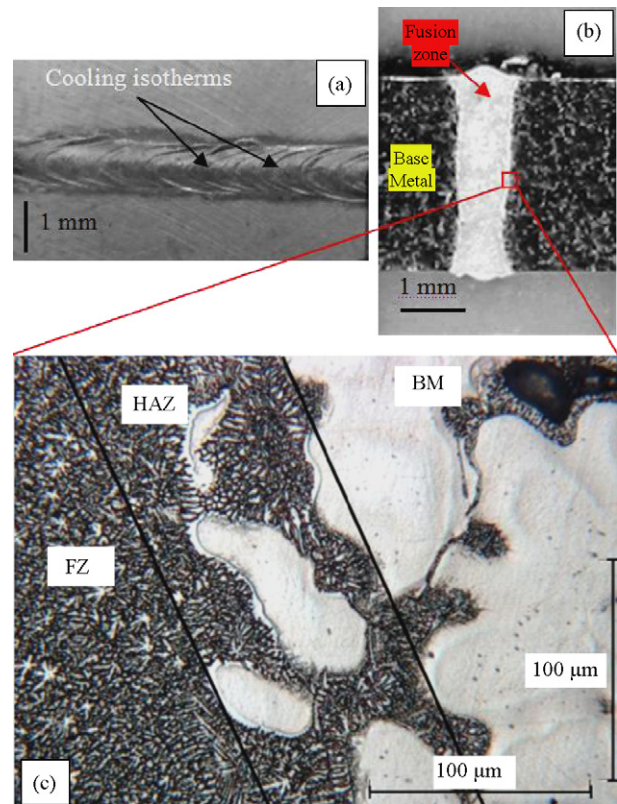


Fig. 13. Weld metallurgical observations: LP=3000 W; V=4.2 m/min; FP=0 mm from surface, GF=40 l/min.

The metallurgical properties of laser welded joint, obtained by process parameter given in Table 3, were investigated. Transversal weld macrograph of Fig. 13b shows that, after magnesium alloy laser welding, noticeable change in microstructure occurred. Two principal zones were present: the fusion zone (FZ) and the base metal (MB). A very small heat affected zone (HAZ), with 90 µm in width, was detected on weld microstructure presented in Fig. 13c. The molten zone was characterized by a dendritic microstructure. Liu et al. (2005) had observed this structure with high solidification rate of as-cast magnesium alloys melted by laser radiation.

Experimental investigations, presented above, were used to calibrate and to validate numerical results in terms of temperature evolution and weld geometrical characteristics.

According to Fig. 14, the comparison of the finite element simulated temperature evolution and those measured by thermocouples reveals a satisfactory agreement between numerical and experi-

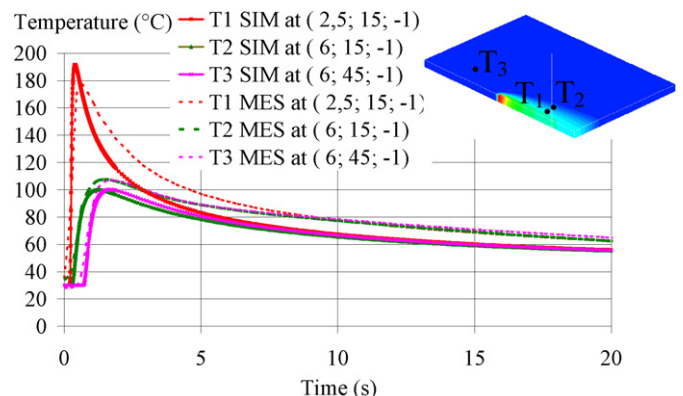


Fig. 14. Experiment vs. simulation: temperature evolution according time.

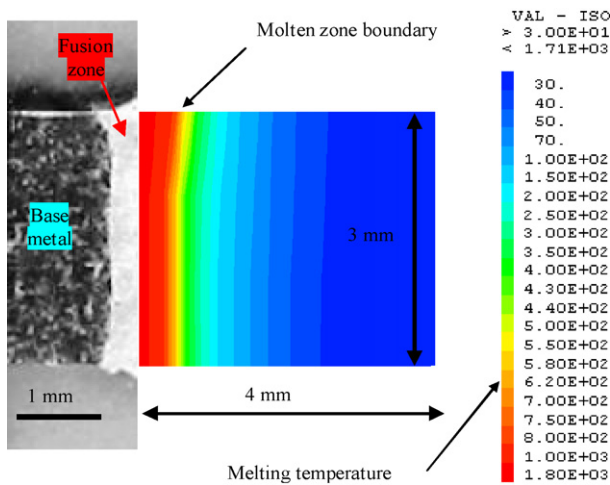


Fig. 15. Experiment vs. simulation: weld width.

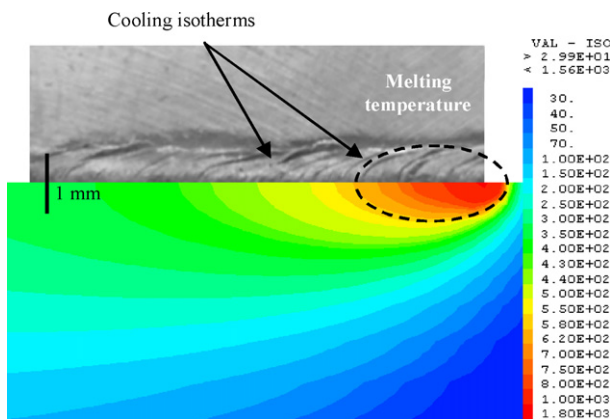


Fig. 16. Experiment vs. simulation: cooling isotherm.

mental results. The same thermal behaviour is noted during heating step. However, we can notice temperature value differences after the laser beam run. This difference can be due to considered hypothesis in the definition of the convective condition during cooling and some error calculation due to the lack of information concerning material properties especially at high temperature.

The comparison of simulated molten zone form and dimension with those determined by metallurgical investigations are presented in Figs. 15 and 16. Isotherm evolutions near heat source were compared to transversal weld macrographs (Fig. 15). With 3 kW laser power and 4.2 m/min welding rate, the measured weld width was between 0.6 and 1 mm. On the other hand, the simulated molten zone detected by melting temperature was about 0.9 mm. Similar solidification profiles on the weldment top surface were noted comparing simulated temperature distribution near heat source and molten zone morphology (Fig. 16).

5. Conclusion

A 3D finite element model has been developed to simulate the thermal history during laser welding of AM60 magnesium-based alloy thin plates. The non-linear transient calculation was performed using the CAST3 M FE code. The suggested model gave the possibility to determinate at every treatment time step, the temperature fields on weldments from the beginning of welding until the return to thermal balance. Instantaneous temperatures and heating and cooling rates evolutions according time were also determined in many meshwork points. Experimental studies were conducted to validate numerical model simulations. The temperature measurement results and metallurgical investigations were in good agreement with thermal model upshots. Temperature fields at various time steps, resulting from the developed model, will be used as input on the mechanical analysis of magnesium alloys laser beam welding process.

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